

Gold Eagle

360A / 100V

430A / 80V

Digital Servo Drive

Installation Guide



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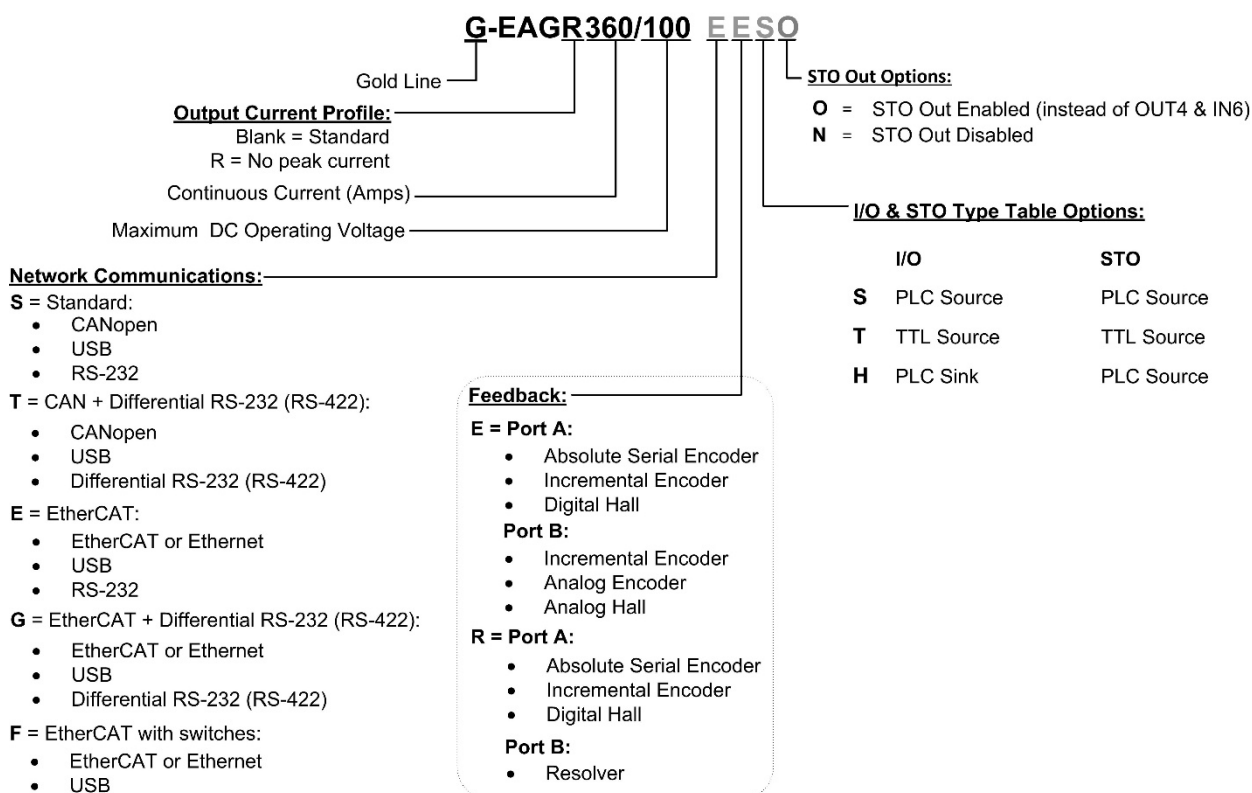
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1. This Installation Guide

This installation Guide details the technical data, pinouts, and power connectivity of the Gold Eagle 360/430. For a comprehensive detailed description of the functions, refer to the MAN-G-Panel Mounted Drives Hardware manual, which describes Panel Mounted products.

2. Safety Information

In order to achieve the optimum, safe operation of the Gold Eagle 360/430, it is imperative that you implement the safety procedures included in this installation guide. This information is provided to protect you and to keep your work area safe when operating the Gold Eagle 360/430 and accompanying equipment.

Please read this chapter carefully before you begin the installation process.

Before you start, ensure that all system components are connected to earth ground. Electrical safety is provided through a low-resistance earth connection.

Only qualified personnel may install, adjust, maintain and repair the servo drive. A qualified person has the knowledge and authorization to perform tasks such as transporting, assembling, installing, commissioning and operating motors.

The Gold Eagle 360/430 contains electrostatic-sensitive components that can be damaged if handled incorrectly. To prevent any electrostatic damage, avoid contact with highly insulating materials, such as plastic film and synthetic fabrics. Place the product on a conductive surface and ground yourself in order to discharge any possible static electricity build-up.

To avoid any potential hazards that may cause severe personal injury or damage to the product during operation, keep all covers and cabinet doors shut.

The following safety symbols are used in this and all Elmo Motion Control manuals:



Warning:

This information is needed to avoid a safety hazard, which might cause bodily injury or death as a result of incorrect operation.



Caution:

This information is necessary to prevent bodily injury, damage to the product or to other equipment.



Important:

Identifies information that is critical for successful application and understanding of the product.



2.1 Warnings

- To avoid electric arcing and hazards to personnel and electrical contacts, never connect/disconnect the servo drive while the power source is on.
- Power cables can carry a high voltage, even when the motor is not in motion. Disconnect the Gold Eagle 360/430 from all voltage sources before servicing.
- The high voltage products within the Gold Line range contain grounding conduits for electric current protection. Any disruption to these conduits may cause the instrument to become hot (live) and dangerous.
- After shutting off the power and removing the power source from your equipment, wait at least 1 minute before touching or disconnecting parts of the equipment that are normally loaded with electrical charges (such as capacitors or contacts). Measuring the electrical contact points with a meter, before touching the equipment, is recommended.



2.2 Cautions

- The maximum DC power supply connected to the instrument must comply with the parameters outlined in this guide.
- When connecting the Gold Eagle 360/430 to an approved isolated control backup (VCB), route the cables separately from other power cables, in accordance with approved safety standards.
- Before switching on the Gold Eagle 360/430, verify that all safety precautions have been observed and that the installation procedures in this manual have been followed.
- Make sure that the Safe Torque Off is operational

2.3 CE Marking Conformance

The Gold Eagle 360/430 is intended for incorporation in a machine or end product. The actual end product must comply with all safety aspects of the relevant requirements of the European Safety of Machinery Directive 2006/42/EC as amended, and with those of the most recent versions of standards EN 60204-1 and EN ISO 12100 at the least, and in accordance with 2006/95/EC.

Concerning electrical equipment designed for use within certain voltage limits, the Gold Eagle 360/430 meets the provisions outlined in 2006/95/EC. The party responsible for ensuring that the equipment meets the limits required by EMC regulations is the manufacturer of the end product.

2.4 Warranty Information

The products covered in this manual are warranted to be free of defects in material and workmanship and conform to the specifications stated either within this document or in the product catalog description. All Elmo drives are warranted for a period of 12 months from the date of shipment. No other warranties, expressed or implied — and including a warranty of merchantability and fitness for a particular purpose — extend beyond this warranty.



3. Product Description

The Gold Eagle 360/430 is a series of super compact digital servo drives, highly resilient and operating from a DC Power Voltage Input source. They are designed to deliver the highest density of power and intelligence. The Gold Eagle 360A/100V delivers up to **360 A operating from a DC bus of 11VDC- 95VDC**, while the Gold Eagle 430A/80V delivers up to **430 A operating from a power voltage bus of 11VDC- 75VDC**. The logic/ control supply input is a DC voltage in the range of 11VDC- 95VDC. Both drives naturally withstand the surges (40V & 100V) and spikes (250V) that might occur in battery operated systems.

The digital drives are part of Elmo's advanced Gold Line. They operate from a DC power source in current, velocity, position and advanced position modes, in conjunction with a permanent-magnet synchronous brushless motor, DC brush motor, linear motor or voice coil. They are designed for use with any type of sinusoidal and trapezoidal commutation, with vector control. The Gold Eagle 360/430 can operate as a stand-alone device or as part of a multi-axis system in a distributed configuration on a real-time network.

The drives are easily set up and tuned using Elmo Application Studio (EASII) software tools. This Windows-based application enables users to quickly and simply configure the servo drive for optimal use with their motor. The Gold Eagle 360/430, as part of the Gold Line, is fully programmable with Elmo's motion control language.

The Gold Eagle 360/430 can operate with the main power supply only (VP+ and VN-), then the control voltage is created by an internal SMPS powered directly from the VP+ supply. If it is required to leave the control section under power, while the power supply (VP+ - VN-) is removed, a control backup supply (VCB) with a range of 11 to 95 VDC can be connected, providing maximum flexibility and optional backup functionality when needed.



4. Technical Information

4.1 Physical Specifications

| Feature | Units | All Types |
|-----------------|---------|--|
| Weight | g (oz) | 2.4 Kg (84.7 oz) |
| Dimension | mm (in) | 160 x 180 x 90 (6.30" x 7.09" x 3.54") |
| Mounting method | | Panel / Wall Mounted |

4.2 Technical Data

| Feature | Units | R360/100 | R430/80 |
|--|-------|----------|---------|
| Minimum supply voltage | VDC | 11 | |
| Nominal supply voltage | VDC | 85 | 68 |
| Maximum supply voltage | VDC | 94 | 75 |
| Maximum continuous power output (at 85VDC) | kW | 25 | |
| Efficiency at rated power (at 360A @ 85VDC, 430A@70VDC) | % | > 99 | |
| VCB supply voltage option | VDC | 11 to 95 | |
| VCB power supply | VA | 7 | |
| Continuous current limit (Ic) Amplitude sinusoidal/DC trapezoidal commutation | A | 360 | 430 |
| Continuous RMS sinusoidal commutation current limit (Ic) | A | 254 | 304 |
| Peak Current | A | No Peak | |



4.2.1 Control Backup Supply

| Feature | Details |
|--------------------------|---|
| VCB supply | <i>Isolated from the mains DC source only</i> |
| VCB supply input voltage | 11 VDC to 95 VDC |
| VCB supply input power | 7 VA |

4.2.2 Product Features

| Main Feature | Details | Presence / No. |
|------------------------------|---|----------------|
| STO | TTL, <i>or</i> | ✓ |
| | PLC Source, <i>or</i> | ✓ |
| | STO Output Status (instead of OUT4 & IN6) | ✓ |
| Digital Input Option | TTL Source <i>or</i> | 6 |
| | PLC Source <i>or</i> | 6 |
| | PLC Sink | 6 |
| Digital Output Option | TTL Source <i>or</i> | 4 |
| | PLC Source <i>or</i> | 4 |
| | PLC Sink | 4 |
| Analog Input | Differential ± 10 V analog input | 1 |
| Feedback | Standard Port A, B, and C | ✓ |
| Communication Option | USB | ✓ |
| | EtherCAT without switches <i>or</i> | ✓ |
| | CAN <i>or</i> | ✓ |
| | EtherCAT with switches | ✓ |
| | RS-232 <i>or</i> | ✓ |
| | RS-422 | ✓ |



4.2.3 Environmental Conditions

You can guarantee the safe operation of the Gold Eagle 360/430 by ensuring that it is installed in an appropriate environment.



Caution:

The Gold Eagle 360/430 dissipates its heat by convection. The maximum ambient operating temperature of 70 °C (160 °F) must not be exceeded.

The ExtrIQ series of drives support the following extended environmental conditions.

| Feature | Operation Conditions | Range |
|----------------------------------|---|---|
| Ambient Temperature Range | According to IEC60068-2-2 in compliance with UL standards | 0 °C to 50 °C (32 °F to 122 °F) |
| | Non-operating conditions | -50 °C to +100 °C (-58 °F to 212 °F) |
| | Operating conditions | -40 °C to +70 °C (-40 °F to 160 °F) |
| Temperature Shock | Non-operating conditions | -40 °C to +70 °C (-40 °F to 160 °F) within 3 min |
| Altitude | Non-operating conditions | Unlimited |
| | Operating conditions | -400 m to 12,000 m (-1312 to 39370 feet) |
| Maximum Humidity | Non-operating conditions | Up to 95% relative humidity non-condensing at 35 °C (95 °F) |
| | Operating conditions | Up to 95% relative humidity non-condensing at 25 °C (77 °F), up to 90% relative humidity non-condensing at 42 °C (108 °F) |
| Vibration | Operating conditions | 20 Hz to 2,000 Hz, 14.6 g |
| Mechanical Shock | Non-operating conditions | ±40g; Half sine, 11 msec |
| | Operating conditions | ±20g; Half sine, 11 msec |



4.2.4 Gold Line Standards

The following table describes the Main Standards of the Gold Eagle 360/430 servo drive. For further details refer to the MAN-G-Board Level Modules Hardware Manual.

| Main Standards | Item |
|---|---|
| The related standards below apply to the performance of the servo drives as stated in the environmental conditions in section 4.2.3 Environmental Conditions above. | |
| Conformity with IEC/EN 61800-5-1 | Adjustable speed electrical power drive systems Safety requirements – Electrical, thermal and energy |
| Conformity with UL61800-5-1 | Adjustable speed electrical power drive systems Safety requirements – Electrical, thermal and energy |
| Conformity with CE 2006/95/EC | Low-voltage directive 2006/95/EC |
| Conformity with CSA C22.2 NO. 14-13 | Industrial Control Equipment |

4.2.5 Environmental

| Specification | Details |
|-------------------------------|---|
| Conformity with IEC60068-2-78 | Environmental testing – Damp heat, steady state |
| Conformity with IEC60068-2-6 | Environmental testing –Vibration (sinusoidal) |
| Conformity with IEC60068-2-2 | Environmental testing – Dry heat |
| Conformity with IEC60068-2-27 | Basic environmental testing procedures - Shock |

4.2.6 EMC

| Specification | Details |
|--------------------------------|---|
| Conformity with IEC/EN 61800-3 | Adjustable speed electrical power drive systems |

4.2.7 EtherCAT Conformance

| EtherCAT Conformance Test Certified |
|---|
| Approved and certified EtherCAT conformance |



4.2.8 Other Compliant Standards

| Quality Assurance | |
|---|--|
| ISO 9001:2008 | Quality Management |
| Design | |
| <ul style="list-style-type: none">• IPC-D-275• IPC-SM-782• IPC-CM-770 | Printed wiring for electronic equipment (clearance, creepage, spacing, conductors sizing, etc.) |
| Reliability | |
| MIL-HDBK- 217F | Reliability prediction of electronic equipment (rating, de-rating, stress, etc.) |
| Workmanship | |
| In compliance with IPC-A-610, level 3 | Acceptability of electronic assemblies |
| PCB | |
| In compliance with IPC-A-600, level 3 | Acceptability of printed circuit boards |
| Packing | |
| In compliance with EN 100015 | Protection of electrostatic sensitive devices |
| Environment | |
| In compliance with 2002/96/EC | Waste Electrical and Electronic Equipment regulations (WEEE) Note: Out-of-service Elmo drives should be sent to the nearest Elmo sales office. |
| In compliance with 2002/95/EC (effective July 2006) | Restrictions on Application of Hazardous Substances in Electric and Electronic Equipment (RoHS) |



5. Installation

The Gold Eagle 360/430 must be installed in a suitable environment and properly connected to its voltage supplies and the motor.

5.1 Unpacking the Drive Components

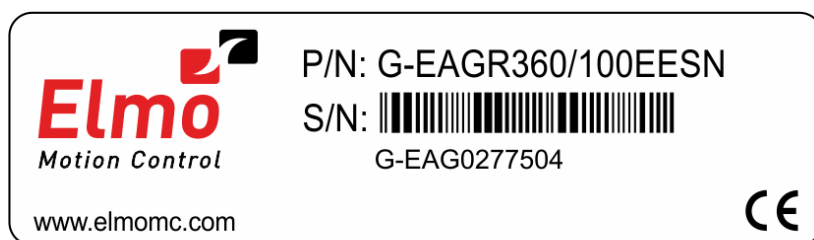
Before you begin working with the Gold Eagle 360/430, verify that you have all of its components, as follows:

- The Gold Eagle 360/430 servo drive
- The Elmo Application Studio (EAS) software and software manual

The Gold Eagle 360/430 is shipped in a cardboard box with Styrofoam protection.

To unpack the Gold Eagle 360/430:

1. Carefully remove the servo drive from the box and the Styrofoam.
2. Check the drive to ensure that there is no visible damage to the instrument. If any damage has occurred, report it immediately to the carrier that delivered your drive.
3. To ensure that the Gold Eagle 360/430 you have unpacked is the appropriate type for your requirements, locate the part number sticker on the side of the Gold Eagle 360/430. It looks like this:



GEAG360-001A

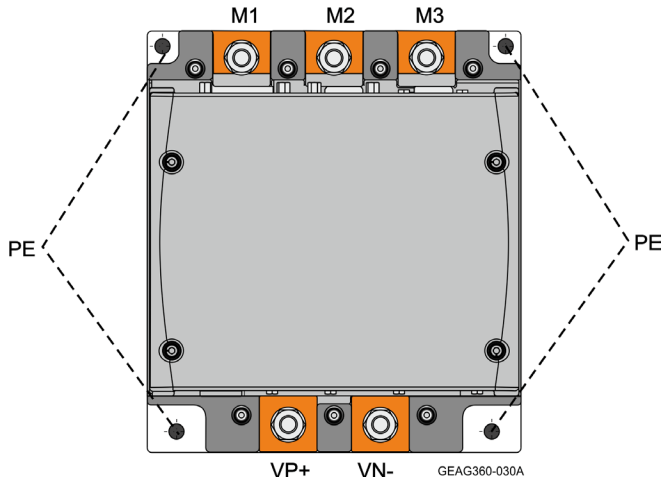
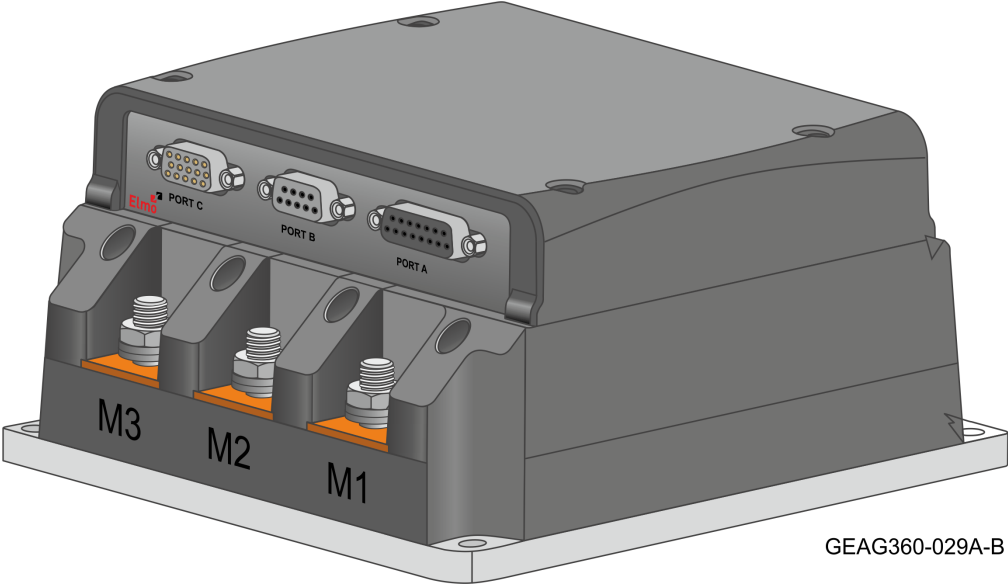
4. Verify that the Gold Eagle 360/430 type is the one that you ordered, and ensure that the voltage meets your specific requirements.

The part number at the top provides the type designation. Refer to the appropriate part number in the section Catalog Number at the beginning of the installation guide.



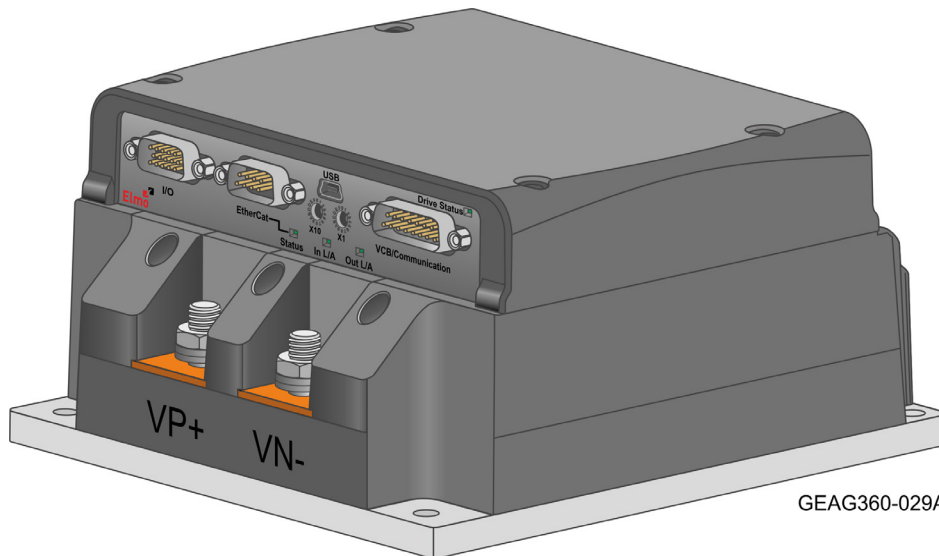
5.2 Connectors Types

The Gold Eagle 360/430 has the following nine connectors.

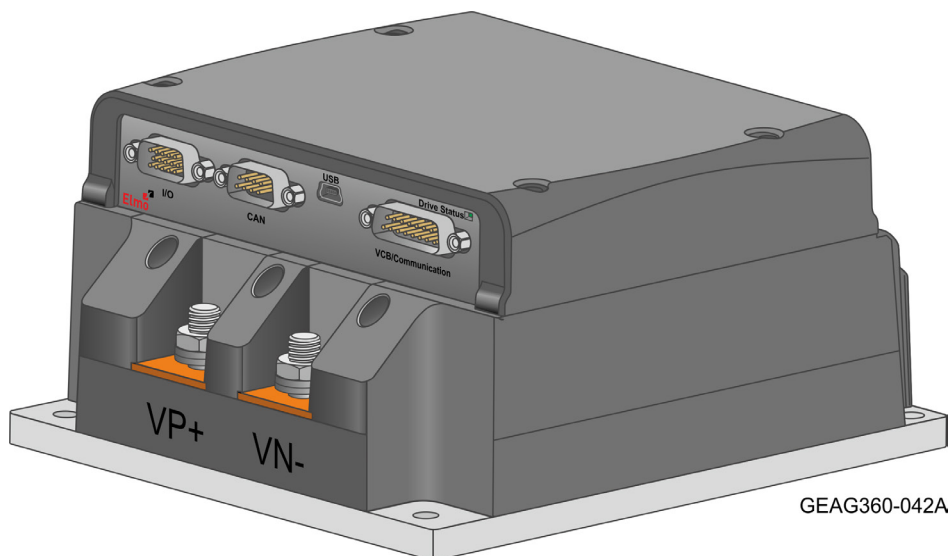
| Type | | Function | Port | Connector Location |
|--|----------------------------|---|------------------------------------|--|
| Terminal Lug + M8 Flat Washer + M8 Spring Washer + M8 Nut | | Power | VP+, VN- |  |
| | | Motor | M1, M2, M3 | |
| Terminal Lug + M6 Flat Washer + M6 Spring Washer + M6 screw | | Earth Connection | PE, PE, PE, PE | |
| Recommended for M8 screw | | Terminal Lug (FLEX) (Stud hall size: 8 mm (2/5")) 1/0 AWG | | |
| Pins | Type | | Function | |
| Rear Connectors | | | | |
|  | | | | |
| 15 | Socket D-Type | | Port A | |
| 9 | Socket D-Type | | Port B | |
| 15 | Socket High Density D-Type | | Port C and Functional Safety (STO) | |



Front Connectors



Front Connectors – EtherCAT



Front Connectors – CAN

| Pins | Type | Function |
|-------------------------|--------------------------|--|
| 15 | Plug High Density D-Type | I/O |
| 15 | Plug D-Type | VCB, RS-232, RS-422, USB |
| EtherCAT Version | | |
| 9 | Plug D-Type | Ethernet, EtherCAT IN, EtherCAT OUT, communication |
| 4 | USB Device Type Mini B | USB communication |
| CAN Version | | |
| 9 | Plug D-Type | CAN IN, CAN OUT, communication |
| 4 | USB Device Type Mini B | USB communication |



5.2.1 Recommended Cable Lugs and Cabling

Elmo recommends the following cable lugs depending on the cable to be installed. Refer to the specification drawings for the UL listed lug and cable application.

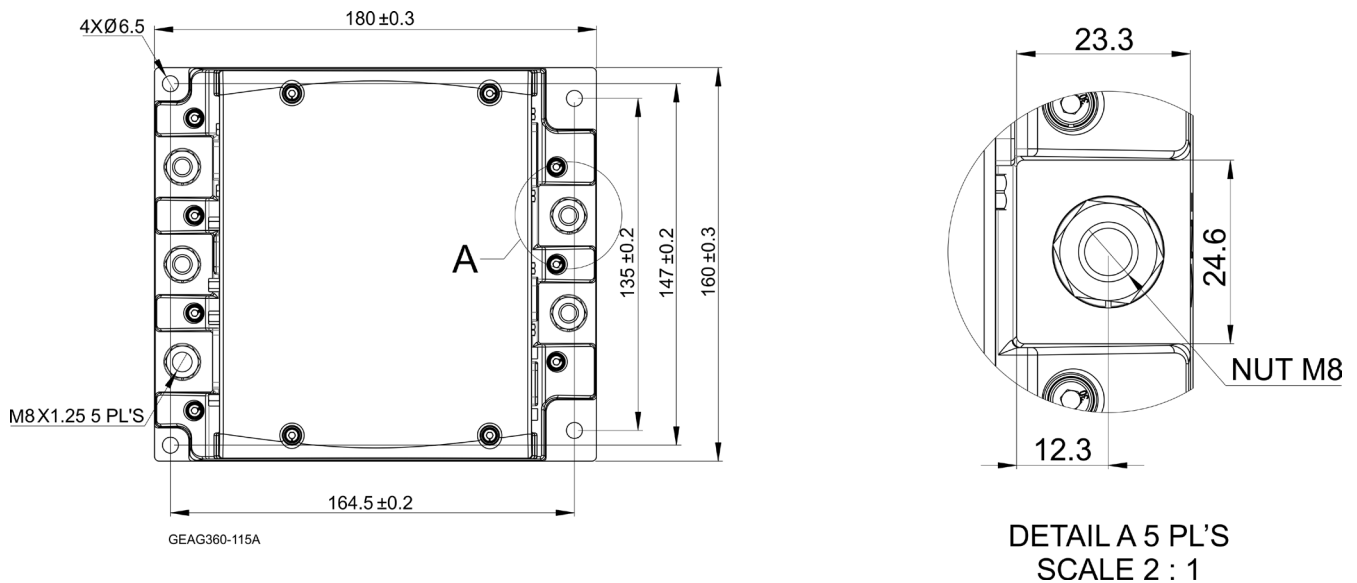
Panduit Copper Lug - One-Hole, Standard Flex Barrel

| Part No. | Barrel Col. and ID | Wire Size | Wire Type | Wire Strip Length | Stud Size |
|---------------|--------------------|--------------|---|-------------------|-------------------|
| LCAX1 /0-56-X | Pink P42 | 1/0 STR/FLEX | Stranded Copper: Class B & C, Compact, Class G, H, I, K, M, Locomotive | 3/4 in (19 mm) | 5/16 in (7.94 mm) |

5.3 Mounting the Gold Eagle 360/430

The Gold Eagle 360/430 has been designed for a standard mounting; Wall Mount along the back (can also be mounted horizontally on a metal surface)

Four M8 head cap (Allen) screws with a minimum length of 20 mm, one through each opening in the heat sink, are used to mount the Gold Eagle 360/430 (see the diagram below).





5.4 Connection Diagrams

There are connection diagrams for EtherCAT and CAN that show the two different ways of connecting the power supply in the Gold Eagle 360/430 models.

5.4.1 Connection Diagrams for EtherCAT Version

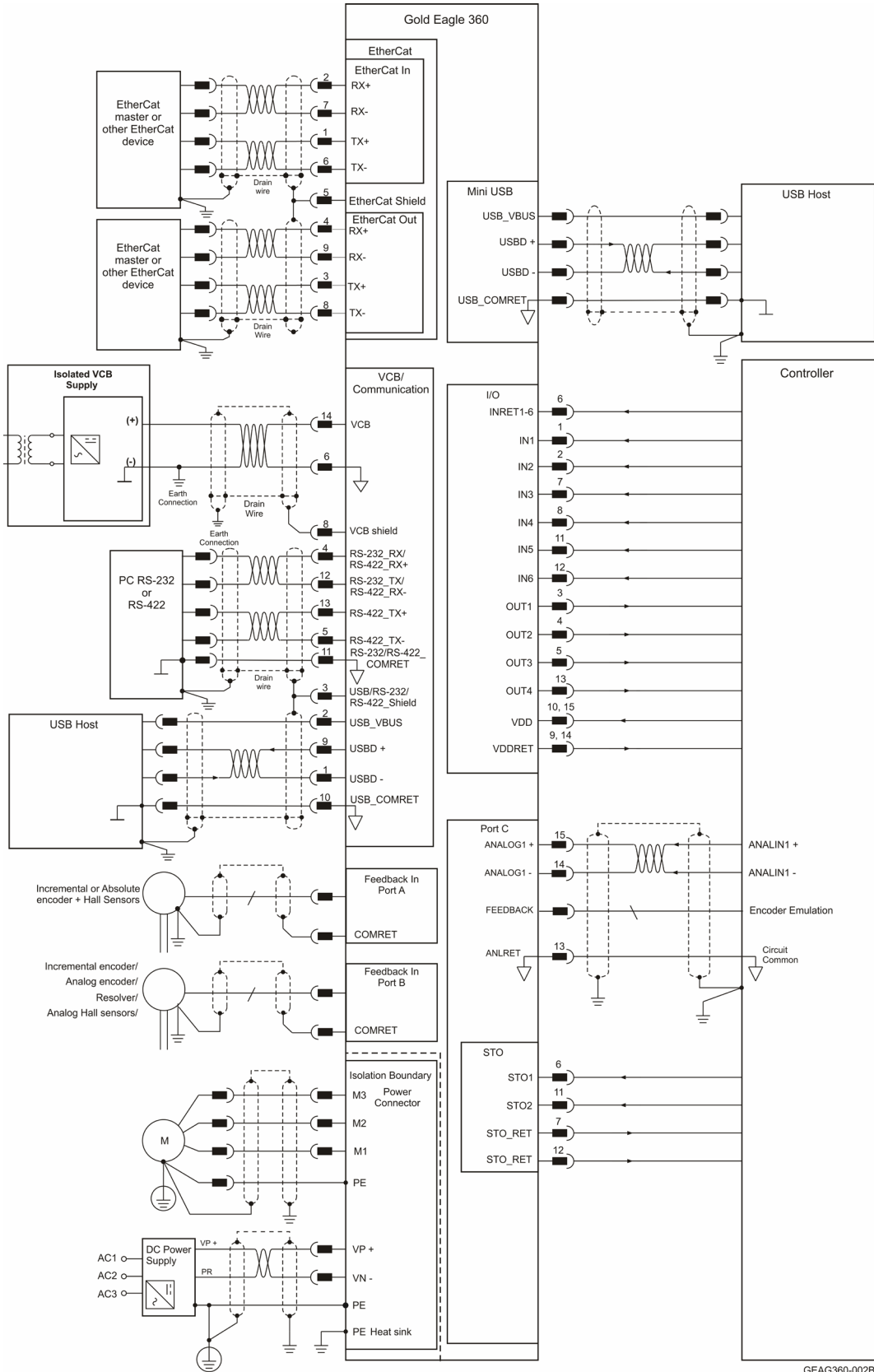
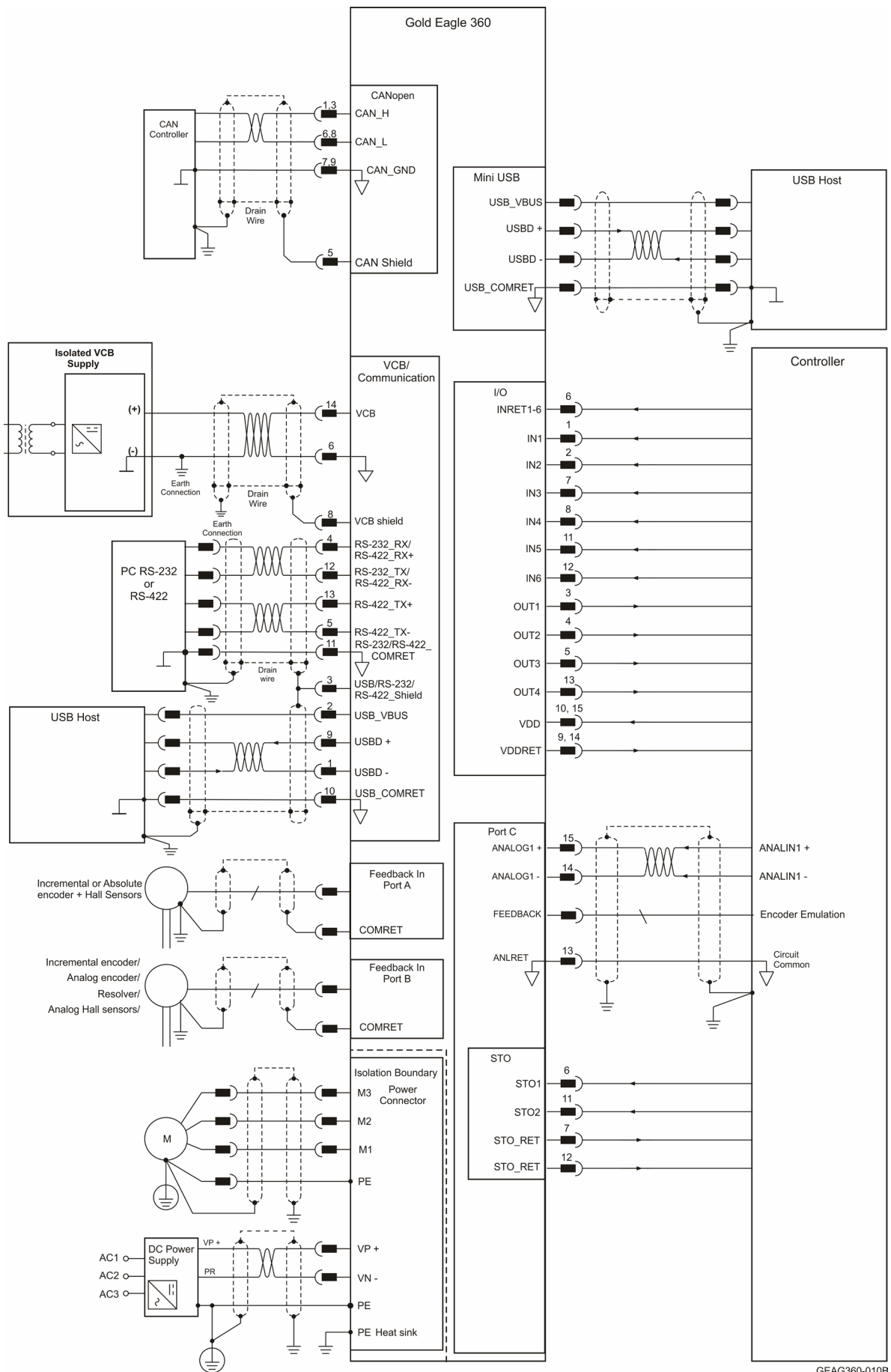


Figure 2: Gold Eagle 360/430 Connection Diagram for EtherCAT



5.4.2 Connection Diagrams for CAN Version



GEAG360-010B



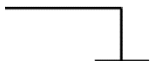
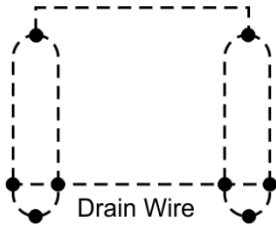
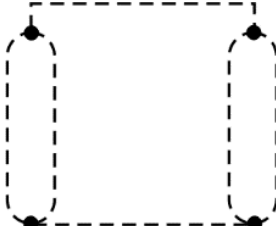
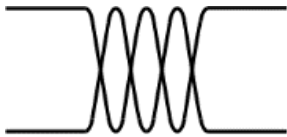
Figure 3: Gold Eagle 360/430 Connection Diagram for CAN



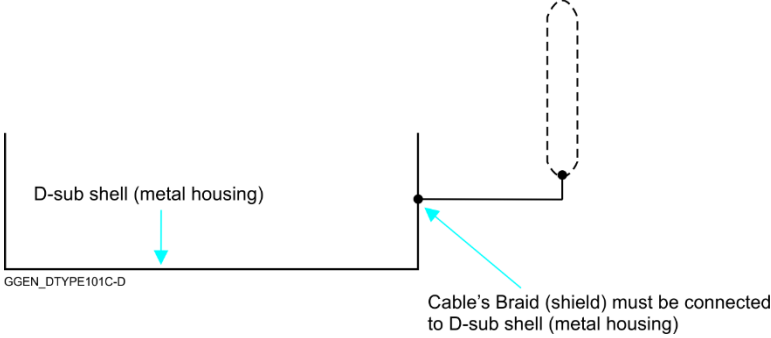
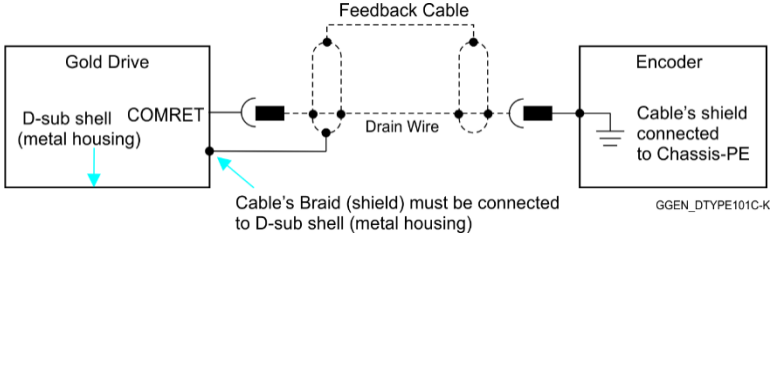
6. Wiring

Once the product is mounted, you are ready to wire the device. Proper wiring, grounding and shielding are essential for ensuring safe, immune and optimal servo performance of the drive.

The following table legend describes the wiring symbols detailed in all installation guides.

| Wiring Symbol | Description |
|--|---|
|  GGEN_DTTYPE101C-A | Earth connection (PE) |
|  GGEN_DTTYPE101C-B | Earth Connection |
|  GGEN_DTTYPE101C-C | Common at the Controller |
|  GGEN_101D-D | Shielded cable with drain wire. The drain wire is a non-insulated wire that is in direct contact with the braid (shielding). Shielded cable with drain wire significantly simplifies the wiring and earthing. |
|  GGEN_101D-E | Shielded cable braid only, without drain wire. |
|  GGEN_101D-F | Twisted-pair wires |



| Wiring Symbol | Description |
|--|--|
|  <p>D-sub shell (metal housing)</p> <p>GGEN_DTTYPE101C-D</p> <p>Cable's Braid (shield) must be connected to D-sub shell (metal housing)</p> | <p>In the D-type Connector: The cable's braid (Shield) must be connected to the D-sub shell (metal housing)</p> |
|  <p>Gold Drive</p> <p>D-sub shell (metal housing)</p> <p>COMRET</p> <p>Feedback Cable</p> <p>Drain Wire</p> <p>Encoder</p> <p>Cable's shield connected to Chassis-PE</p> <p>GGEN_DTTYPE101C-K</p> <p>Cable's Braid (shield) must be connected to D-sub shell (metal housing)</p> | <p>Encoder Earthing.</p> <p>T The cable's shield is connected to the chassis (PE) in the connector.</p> <p>Earthing the Encoder and connecting the Earth (PE) to the drive COMRET is mandatory to insure reliable operation, high noise immunity and rejection of voltage common mode interferences.</p> |



6.1 Basic Recommendations

6.1.1 General

1. Use shielded cables. For best results, the cable should have an aluminum foil shield covered by copper braid, and should contain a drain wire.
Use 24, 26 or 28 AWG twisted-pair shielded with drain wire cables.
2. Keep the cable as short as possible.
Do not mount the power cables of the motor and power bus in the proximity of the control and feedback cables.
3. Ensure that in normal operating conditions, the “earth connection” wires and shield of the control cables *carry no current*. The only time these conductors carry current is under abnormal conditions, when electrical equipment has become a potential shock or fire hazard while conducting external EMI interferences directly to ground, in order to prevent them from affecting the drive. Failing to meet this requirement might result in drive/controller/host failure.
4. After completing the wiring, carefully inspect all wires to ensure tightness, good solder of joints and general safety.

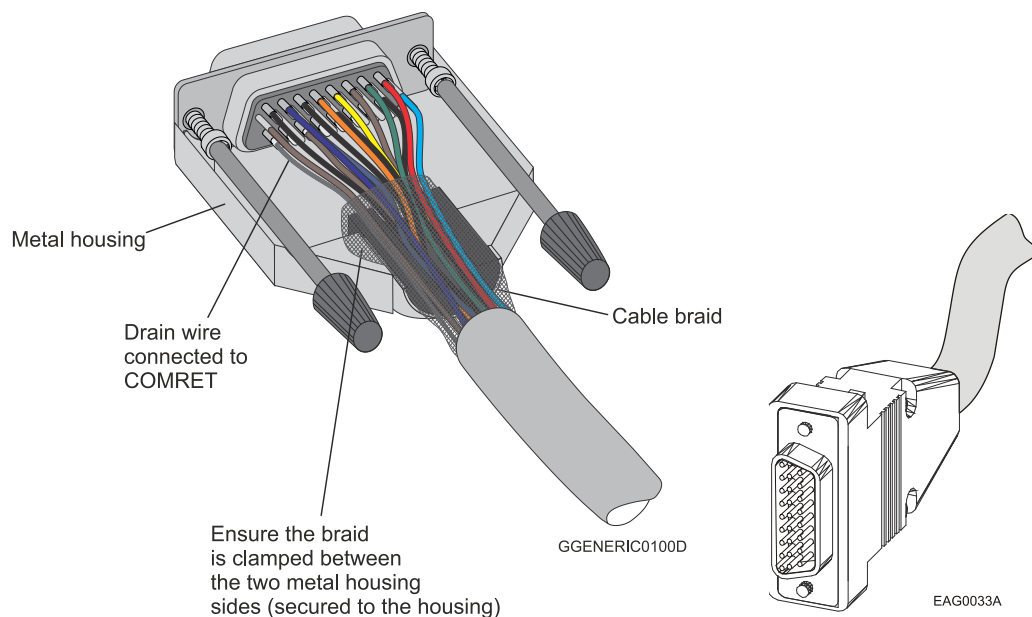


Figure 4: D-Type Cable Assemblies

5. Use only a D-Sub connector with a **metal housing** (Figure 4).
6. Make sure the braid shield is in tight contact with the metal housing of the D-type connector (Figure 4).



6.1.2 Feedback Cable Port A and Port B Connector

1. On the motor side connections, ground the shield to the motor chassis.
2. At least One COMRET (Common Return) must be connected to the PE.

Implement the following steps to connect the COMRET to the PE:

- a. At the drive, connect the feedback drain wire to one of the COMRET terminals in the D-Type feedback connector (Figure 5).
- b. At the motor, connect the feedback cable drain wire to the GND motor chassis terminal of the feedback connector.

The drawings below display two earth connections.

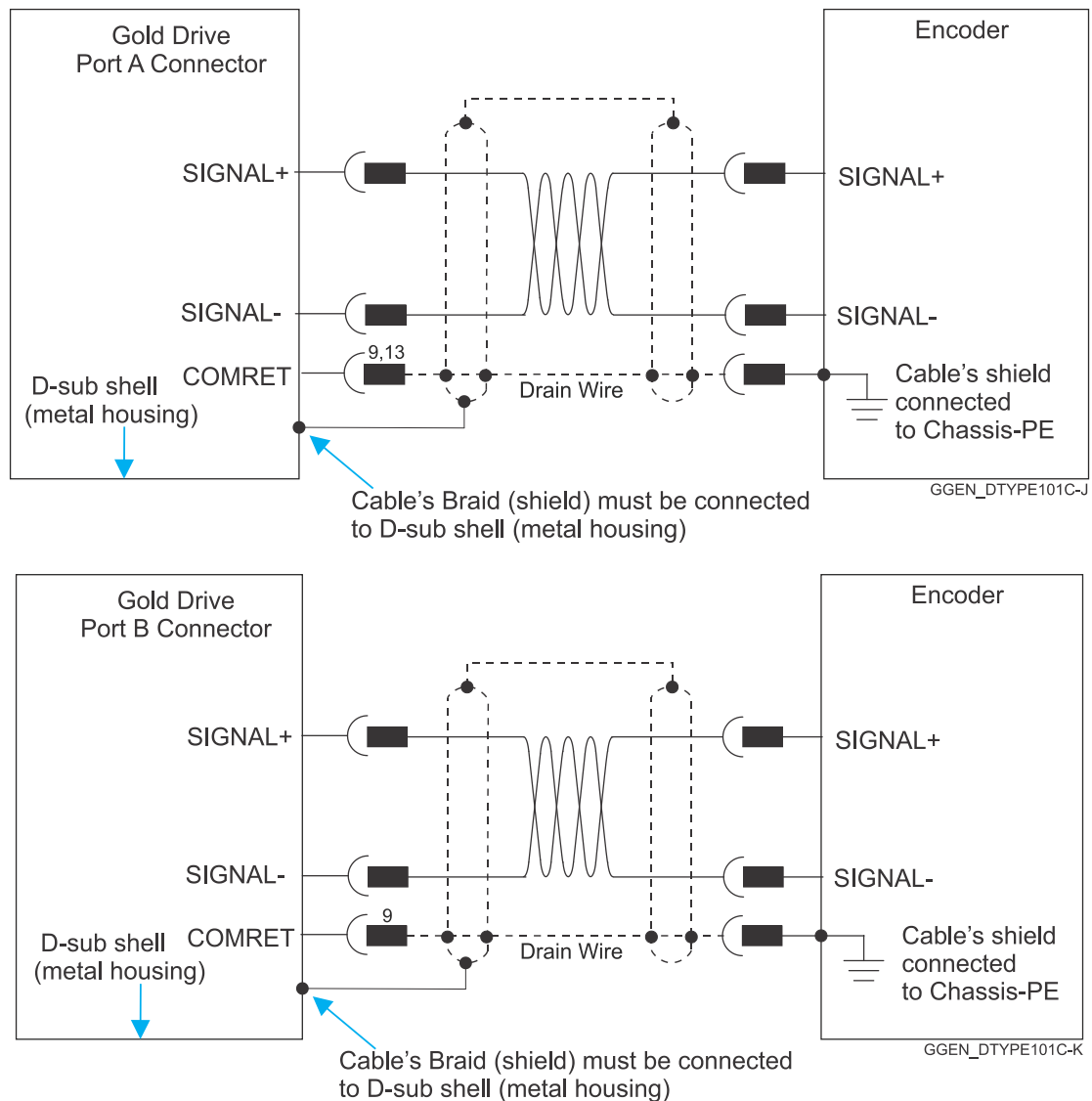


Figure 5: Feedback Port A and B Cable Assemblies



6.1.3 Feedback Cable Port C Connector

1. At the controller side connections, follow the controller manufacturer's recommendations concerning the shield.
2. The connection of the Drain wire to the Port C is not mandatory.

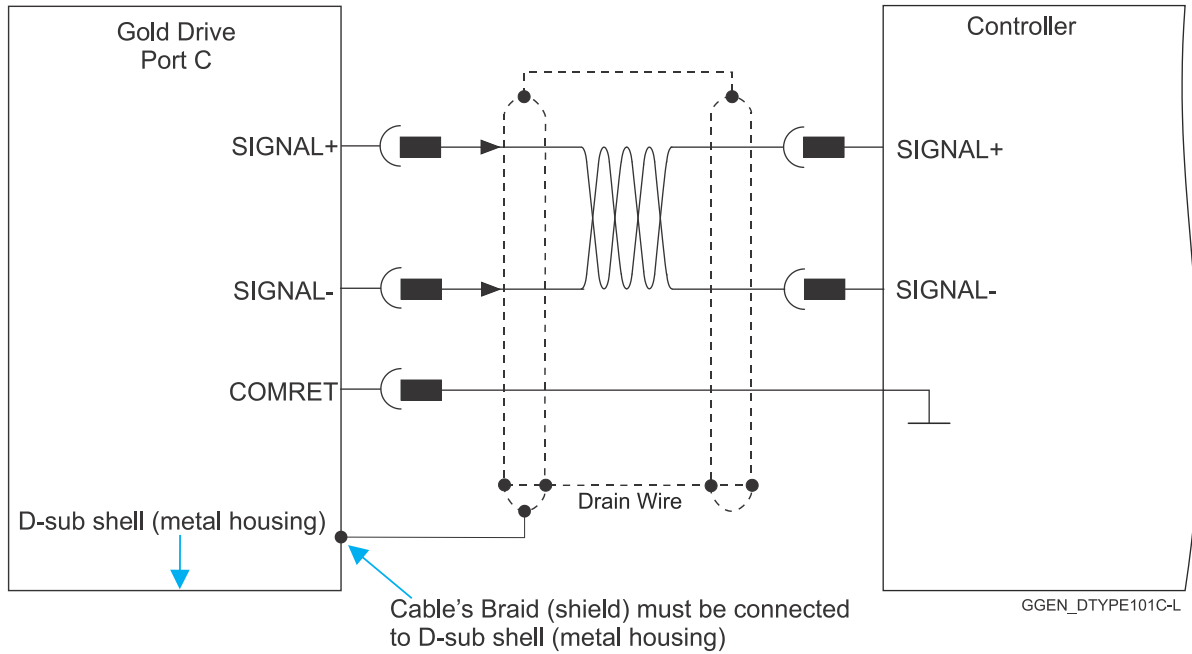


Figure 6: Feedback Port C Cable Assemblies

6.1.4 IO Cable Connector

It is recommended to use shielded cable, but is not mandatory.

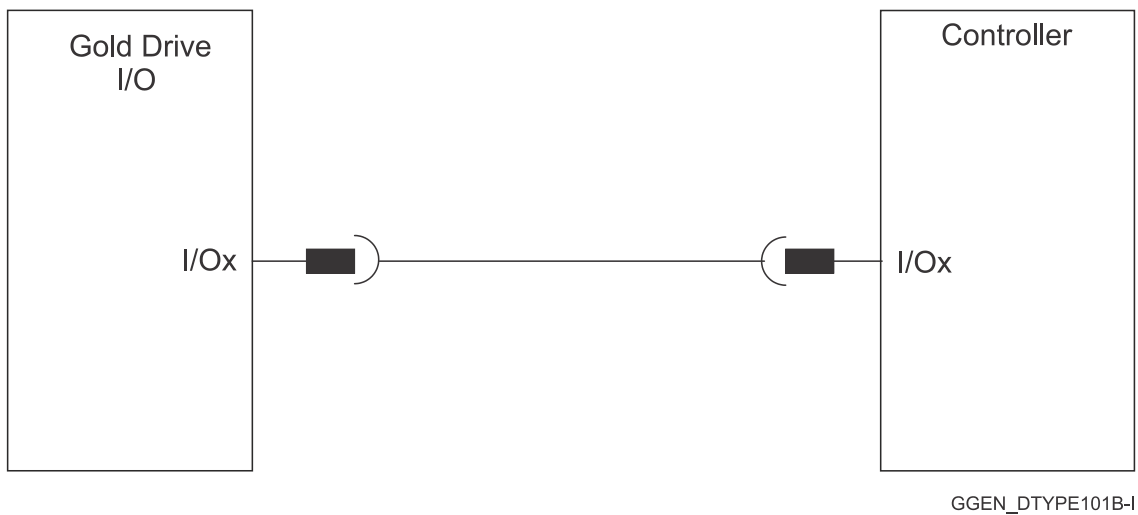


Figure 7: Feedback IO Cable Assemblies



6.1.5 STO (Port C) Cable Connector

It is recommended to use shielded cable, but is not mandatory.

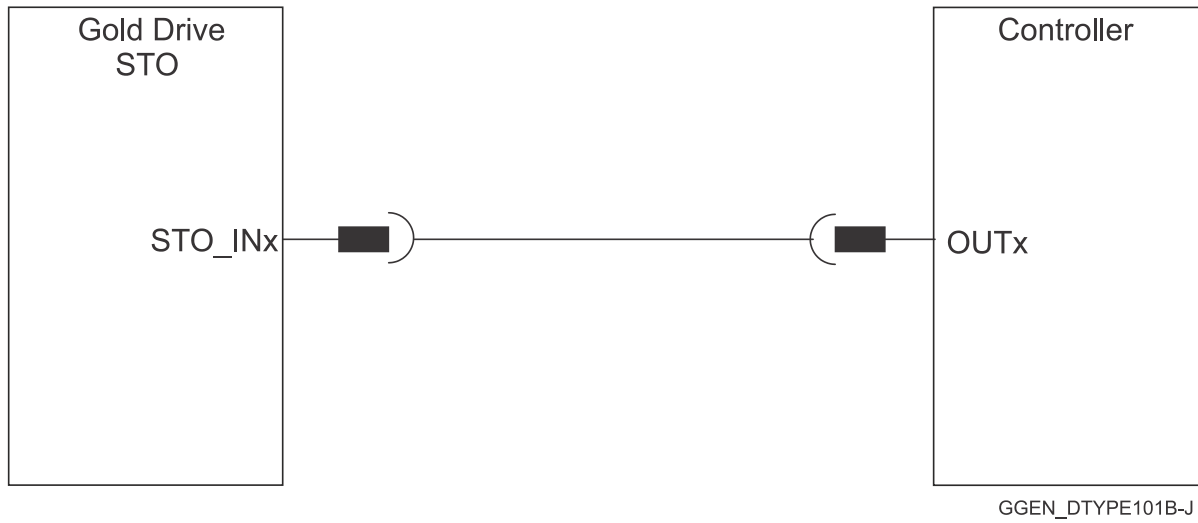
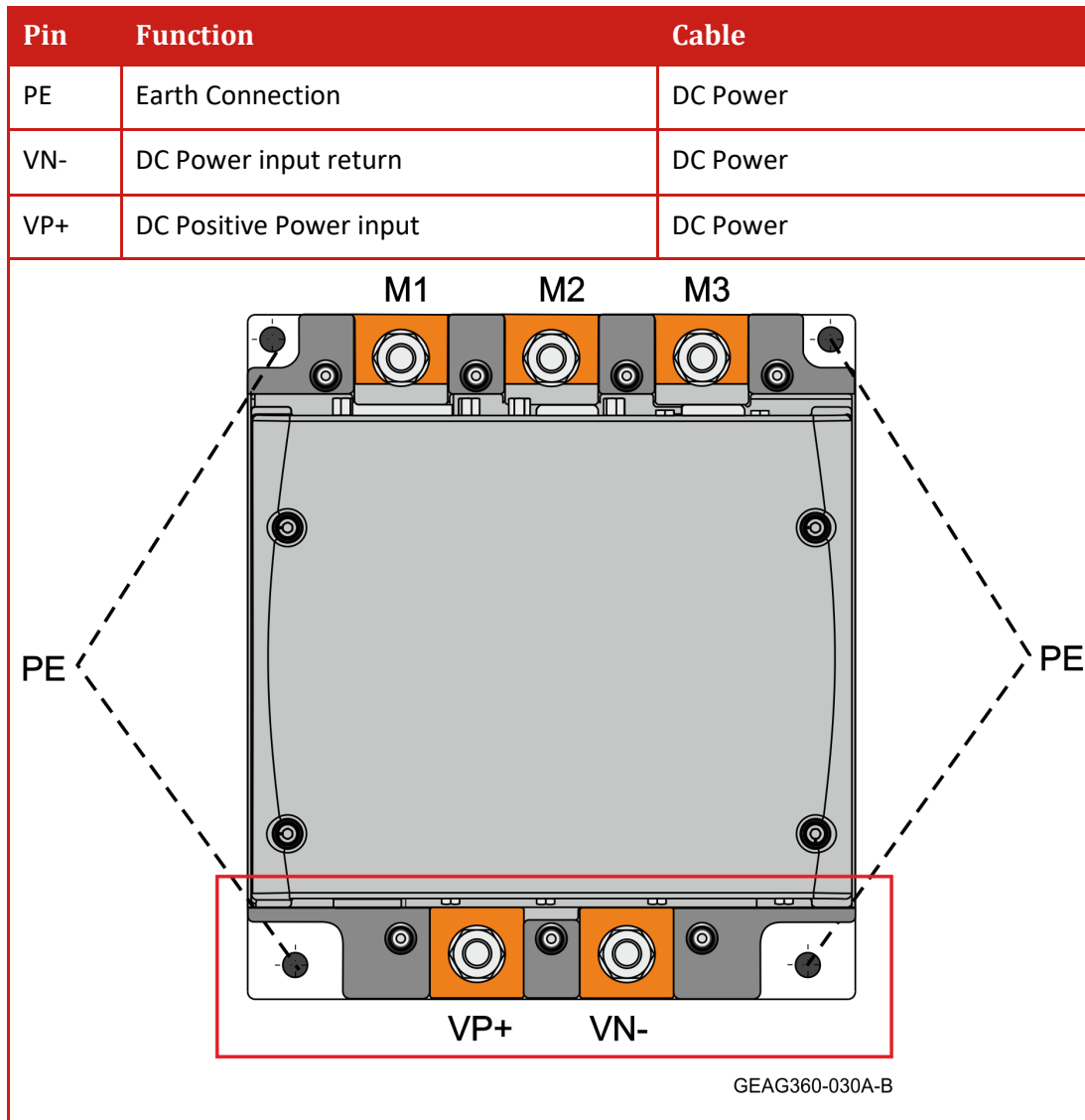


Figure 8: STO Cable Assemblies



6.2 Main Power and Control Supply

The Gold Eagle 360/430 receives power from mains DC power source and delivers power to the motor.





6.2.1 Main Power with Control Backup(VCB) Topology

The Gold Eagle 360/430 operates with only one power supply VP+ and VN- that can be delivered from any DC voltage source, either directly from a battery or from an AC rectifying unit.

The Power stage of the Gold Eagle 360/430 is fully isolated according to the UL61800-5-1, from both the Control Stage and heat-sink (PE). **This isolation allows the user to connect the common of the control section to the PE, a connection which significantly contributes to proper functionality, safety and EMI immunity, leading to better performance of the Gold Eagle 360/430.**

The Control section voltages are derived directly from the main power supply (VP+ and VN-) by an internal SMPS. The VCB Control Backup supply is used to power the control section, if required, when the VP+ is disconnected.

The following figure describes a power supply for Servo drives with sufficient internal capacitance and shunt regulator to handle power flow in both directions to-and-from the motor. The following figure describes this connection of main power and control power.

When operating from a battery, there is no need for additional capacitance on the DC bus.

Note: The Gold Eagle 360/430 operates with only the main power (VP+ and VN-) connected. The VCB Supply is used in case the VP+ is disconnected and the control has to be kept powered (for any reason, e.g. restoring parameters, keeping position data, and logic).

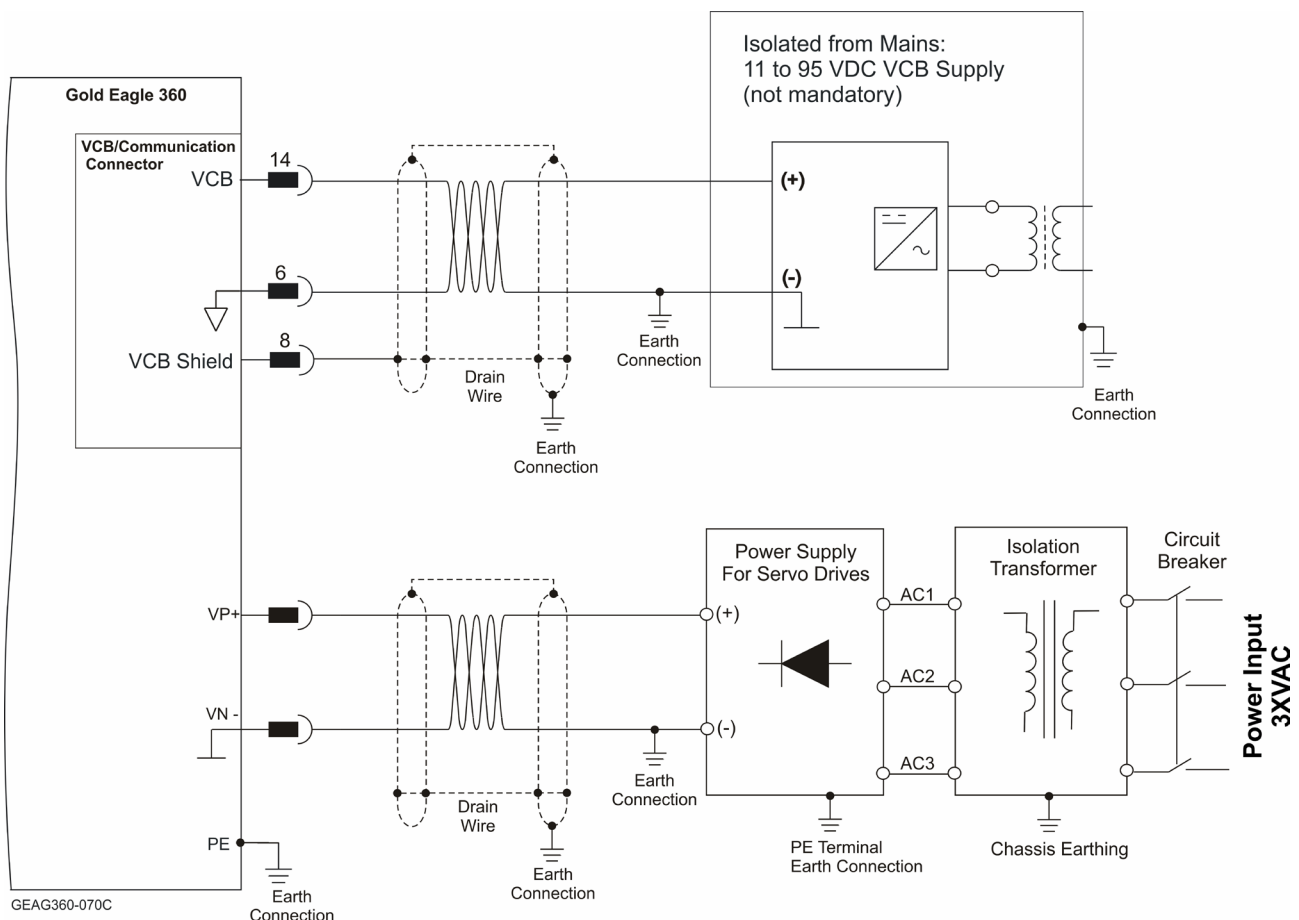


Figure 9: Separate VP and VCB Supplies Connection Diagram



6.2.2 DC Power

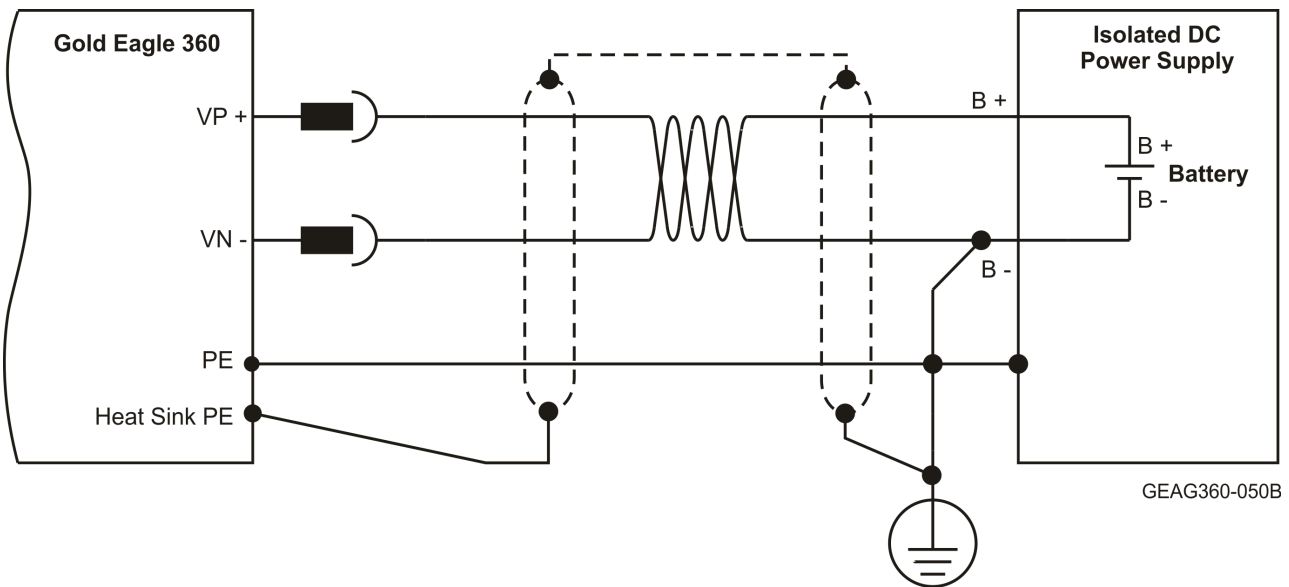


Figure 10: Battery Connection Topology



Caution: When using batteries, it is recommended to connect the negative pole to the PE. When doing so, the charger of the battery **must** be isolated from the mains by an isolation transformer.

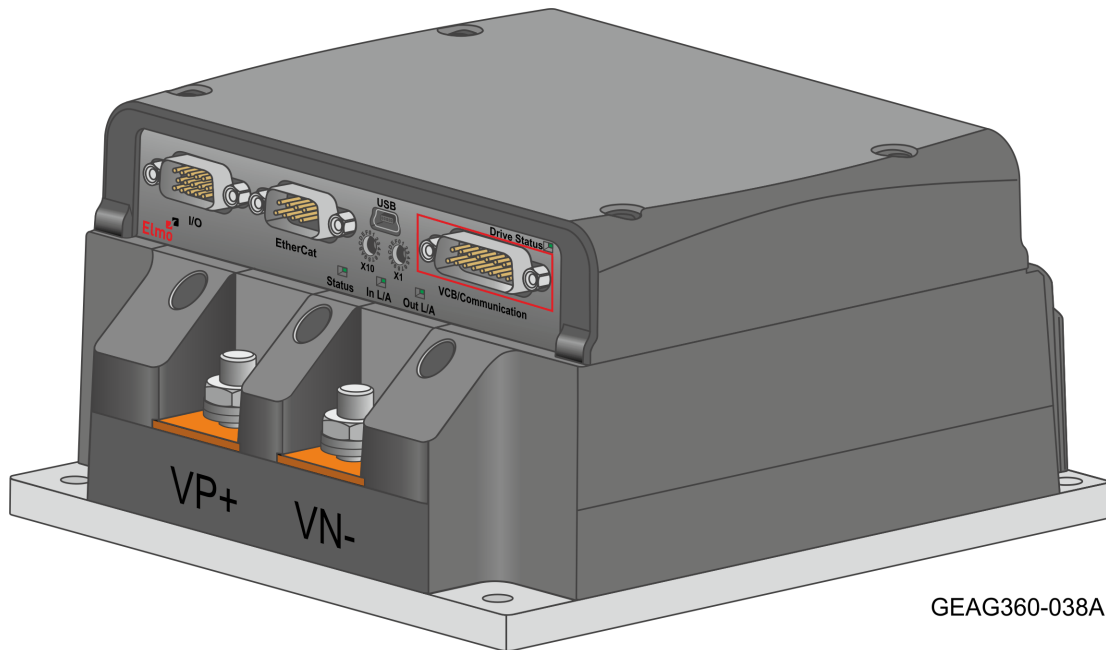
To connect to an isolated DC power supply:

1. For best immunity, it is highly recommended to use twisted cables for the DC power supply cable. A 3-wire shielded cable should be used. The gauge is determined by the actual current consumption of the motor.
2. Connect both ends of the cable shield to the closest ground connection, one end near the power supply and the other end to the PE terminal on the Gold Eagle 360/430's heat sink.
3. For safety reasons connect the VN- of the power supply to the closest ground connection in the power supply side.
4. Connect the appropriate terminal lugs from the DC Power Input cables to the VP+, VN-, and PE terminals on the Gold Eagle 360/430. Refer to section 6.4 Connecting the DC Power and the Motor Power Cables, and in particular Table 2.
 - a. Mount the power supply cable into the drive using the recommended Terminal Lug (FLEX) (Stud hall size: 8 mm (5/16")) 1/0 AWG, M8 flat washer, M8 spring washer, and secure with an M8 nut (to the drive). The required M8 nut torque is typically 8 to maximum 12 Nm.
 - b. Install the recommended PE 1/0 AWG wire to the drive, using a barrel connector, M6 flat washer, M6 spring washer, and secure with an M6 x 20 mm(minimum) head cup Allen screw to the heat-sink. The required M6 screw torque is typically 15 to maximum 20 Nm.
5. Before applying power, first verify that the polarity of the connection is correct.



6.2.3 Control Backup Supply(VCB)

| Pin | Function | Function |
|-----|--------------------|------------------|
| 14 | VCB Input Positive | DC Power |
| 6 | COMRET | DC Power |
| 8 | VCB Shield | Drain wire cable |



GEAG360-038A

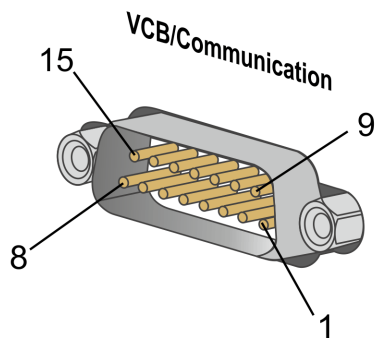


Table 1: VCB Supply Pins and Polarity

A smart control supply(VCB) algorithm enables the Gold Eagle 360/430 to operate with the main power supply only, *with no need for a VCB supply voltage to supply the drive's logic section.*

If backup functionality is required to store control parameters in the event of a mains power outage, then an external control isolated supply(VCB) is connected to the Gold Eagle 360/430.

Connect the control power supply as described below.

To connect the power supply:

1. Use a 24 AWG twisted pair shielded cable. The shield should have copper braid.
The source of the VCB supply must be isolated from the mains.



2. For safety and EMI reasons, connect the return of the VCB supply to the closest ground (PE) in the power supply side.
3. Connect the cable shield to the closest ground (PE) near the power source.
4. Connect the drain wire shield to the Terminal No. 8 (PE).
5. Before applying power, first verify that the polarity of the connection is correct.

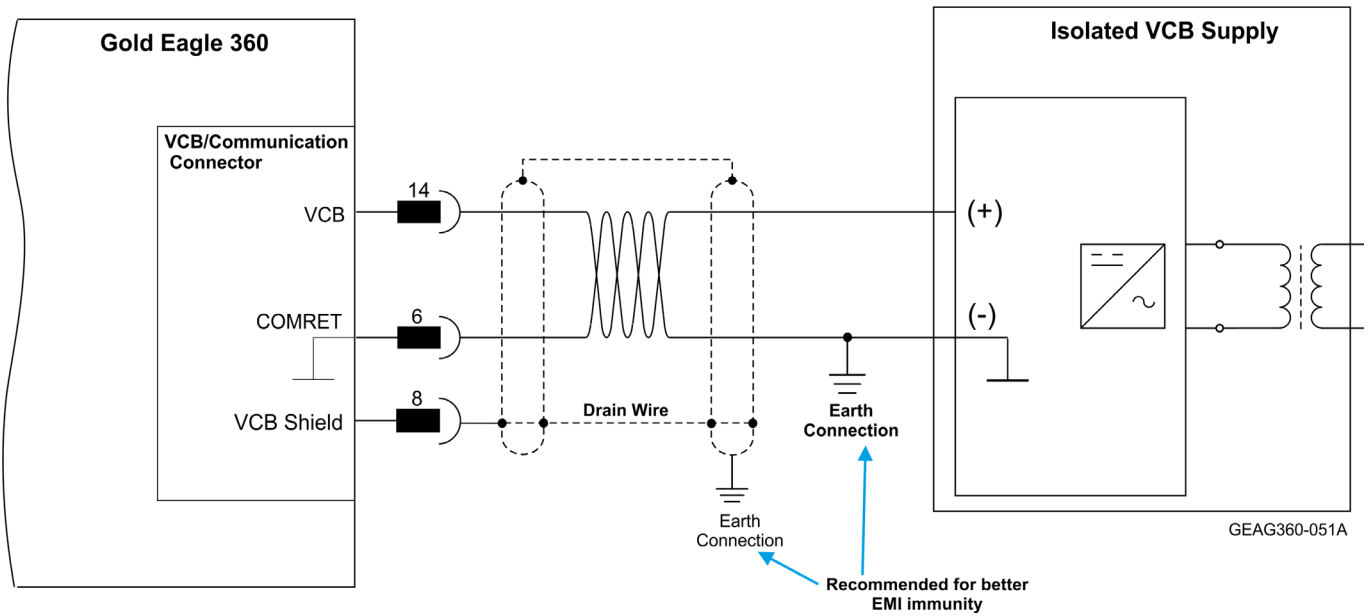


Figure 11: VCB Supply Connection Diagram



6.3 Motor Power Connector Pinouts

See Chapter 8 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

| Pin | Function | Cable | |
|-----|------------------|-----------------|------------------|
| | | Brushless Motor | Brushed DC Motor |
| M3 | Motor phase | Motor | Motor |
| M2 | Motor phase | Motor | Motor |
| M1 | Motor phase | Motor | N/C |
| PE | Earth Connection | Motor | Motor |

Diagram illustrating the Motor Power Connector Pinout for the GEAG360-030A-C. The connector features four terminals on the top and four on the bottom. The top terminals are labeled M1, M2, and M3, and the bottom terminals are labeled VP+ and VN-. The PE (Earth Connection) is indicated on both the top and bottom terminals. The diagram shows the internal wiring connections for the motor phases and the earth connection.

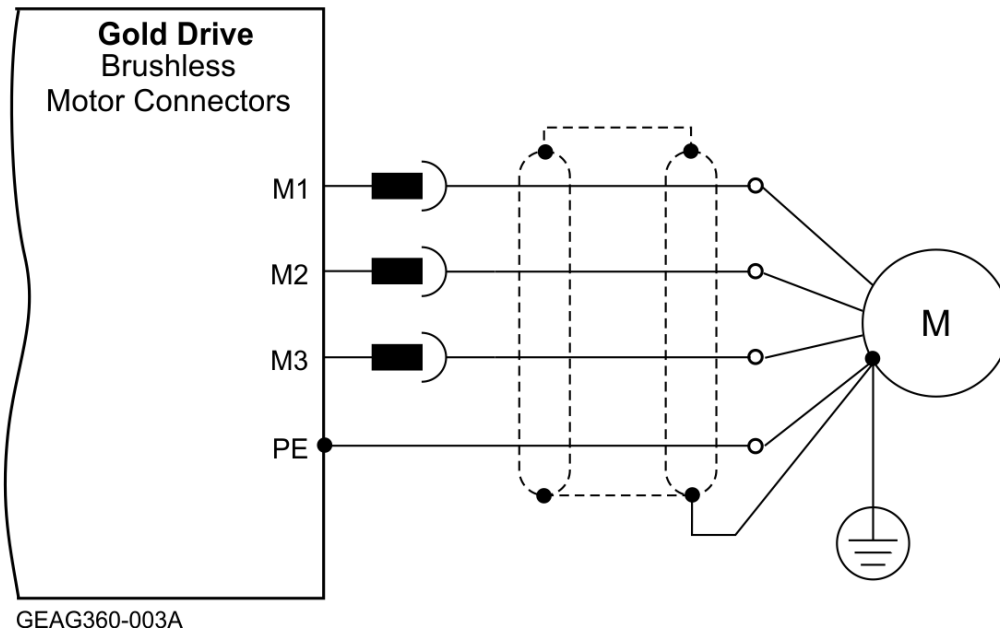


Figure 12: Brushless Motor Power Connection Diagram

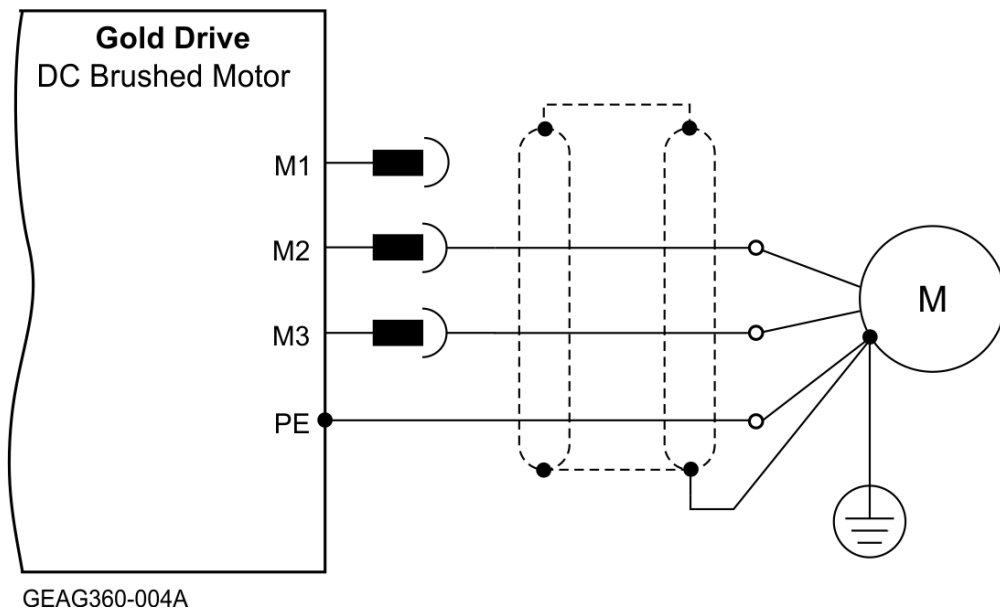


Figure 13: Brushed Motor Power Connection Diagram

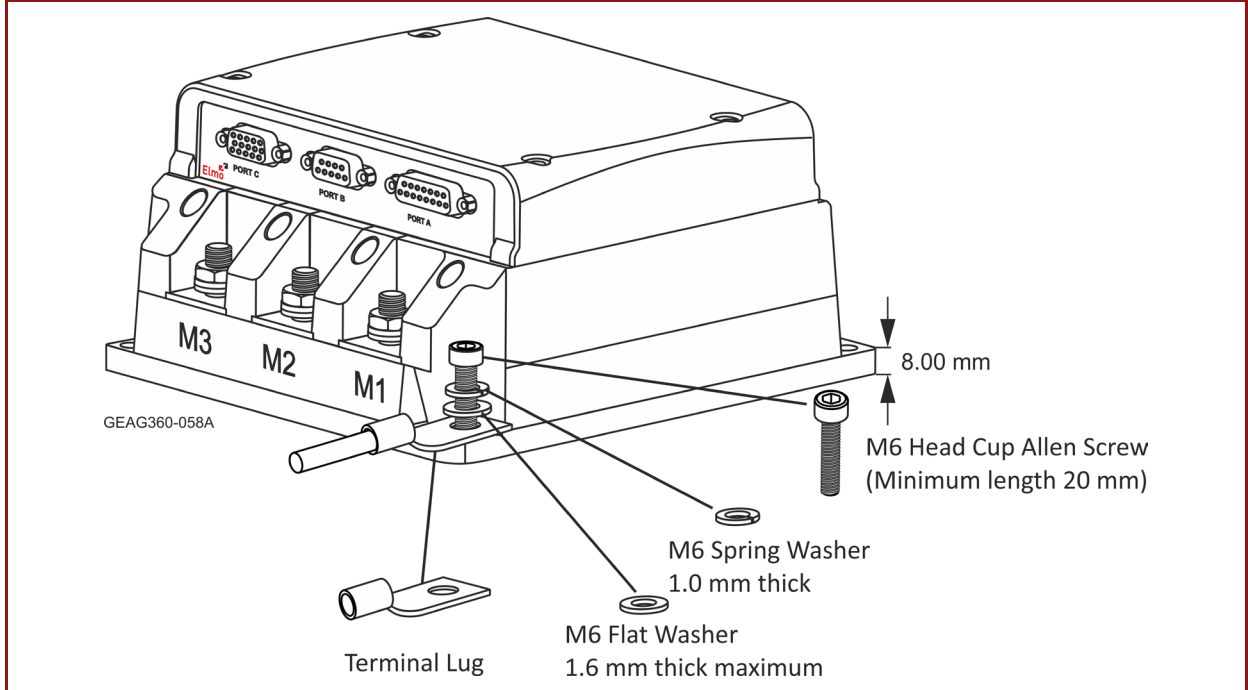


6.4 Connecting the DC Power and the Motor Power Cables

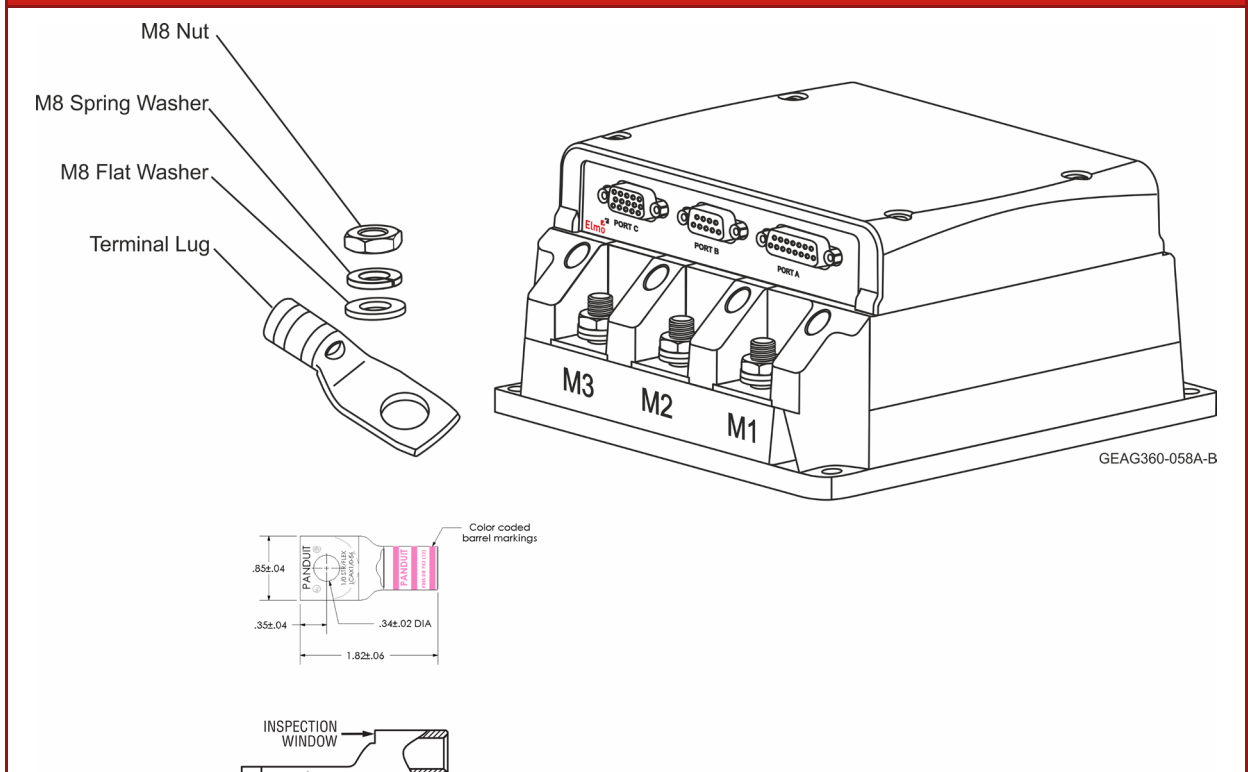
This section describes the installation of the cable terminal lugs for both the Main Power Cables to VP+, VN-, and PE terminals on the Gold Eagle 360/430, and the Motor Power cables to the M1, M2, M3, and PE terminals on the Gold Eagle 360/430.

Note: When connecting several motors, all the motor phases must be connected in an identical sequence.

Step 1: PE Earth Connection



Step 2: Power and Motor Connection





Step 3: Power and Motor Connection

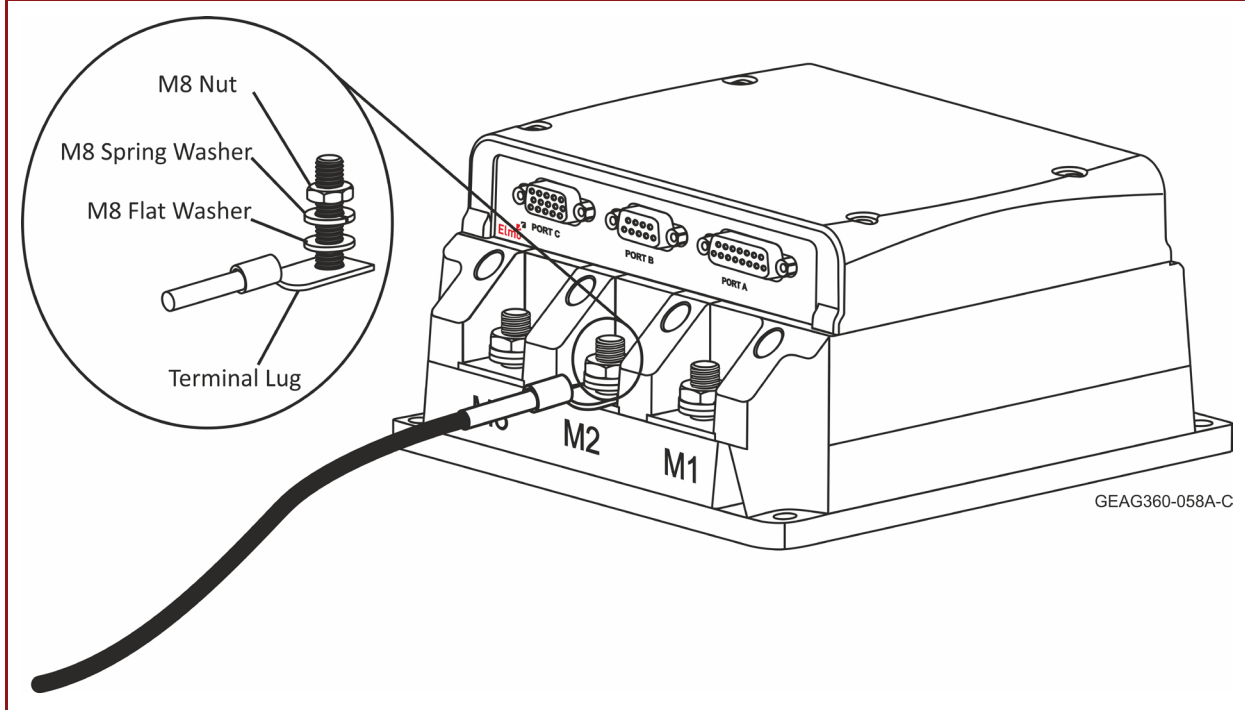


Table 2: Connecting the Main Power and Motor Cables

6.4.1 Motor Power

1. For best immunity, it is highly recommended to use a 4-wire shielded (not twisted) cable for the motor connection. The gauge is determined by the actual RMS current consumption of the motor.

Connect the cable shield to the closest ground connection at the motor end.

For better EMI performance, the shield should be connected to Earth Connection (heat sink mounting holes).

2. Ensure that the motor chassis is properly earthed.
3. Connect the appropriate terminal lugs from the Motor Power cables to the M1, M2, M3, and PE terminals on the Gold Eagle 360/430.

The phase connection is arbitrary as Elmo Application Studio (EASII) will establish the proper commutation automatically during setup. When tuning a number of drives, you can copy the setup file to the other drives and thus avoid tuning each drive separately. In this case the motor-phase order must be the same as on the first drive.

- a. Install the motor cable to the drive using the recommended Terminal Lug (FLEX) (Stud hole size: 8 mm (5/16")) 1/0 AWG, M8 flat washer, M8 spring washer, and secure with an M8 nut (to the drive). The required M8 nut torque is typically 8 to maximum 12 Nm.
- b. Install the recommended PE 1/0 AWG wire to the drive, using a barrel connector, M6 flat washer, M6 spring washer, and secure with an M6 x 20 mm(minimum) head cup Allen screw to the heat-sink. The required M6 screw torque is typically 15 to maximum 20 Nm.

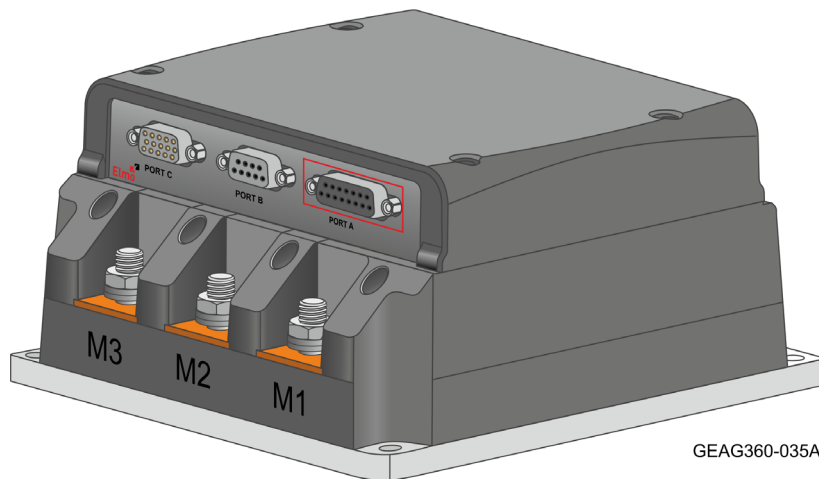


6.5 Port A

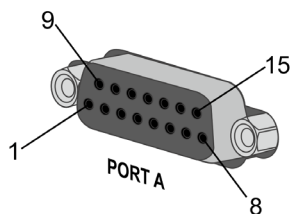
See Section 10.3 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

| Port A | Incremental Encoder | | Absolute Serial Encoder | |
|-----------|---------------------|--------------------|-------------------------|---------------------|
| Pin | Signal | Function | Signal | Function |
| 12,4 | +5V | Encoder +5V supply | +5V | Encoder +5V supply |
| 3,9,11,13 | COMRET | Common return | COMRET | Common Return |
| 6 | PortA_ENC_A+ | Channel A+ | ABS_CLK+ | Abs encoder clock + |
| 5 | PortA_ENC_A- | Channel A- | ABS_CLK- | Abs encoder clock - |
| 15 | PortA_ENC_B+ | Channel B+ | ABS_DATA+ | Abs encoder data + |
| 14 | PortA_ENC_B- | Channel B- | ABS_DATA- | Abs encoder data - |
| 8 | PortA_ENC_INDEX+ | Index+ | Reserved | Reserved |
| 7 | PortA_ENC_INDEX- | Index- | Reserved | Reserved |
| 2 | HA | Hall sensor A | HA | Hall sensor A |
| 10 | HB | Hall sensor B | HB | Hall sensor B |
| 1 | HC | Hall sensor C | HC | Hall sensor C |

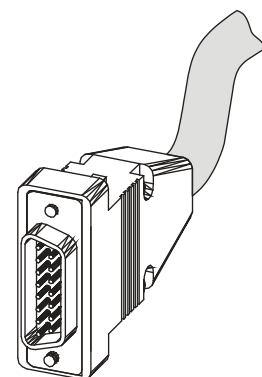
Pin Positions



GEAG360-035A



15-Pin D-Type Female Connector



15-Pin D-Type Male Connector

Table 3: Port A Pin Assignments



6.5.1 Incremental Encoder

The following figure describes the connections at Port A for the Incremental encoder.

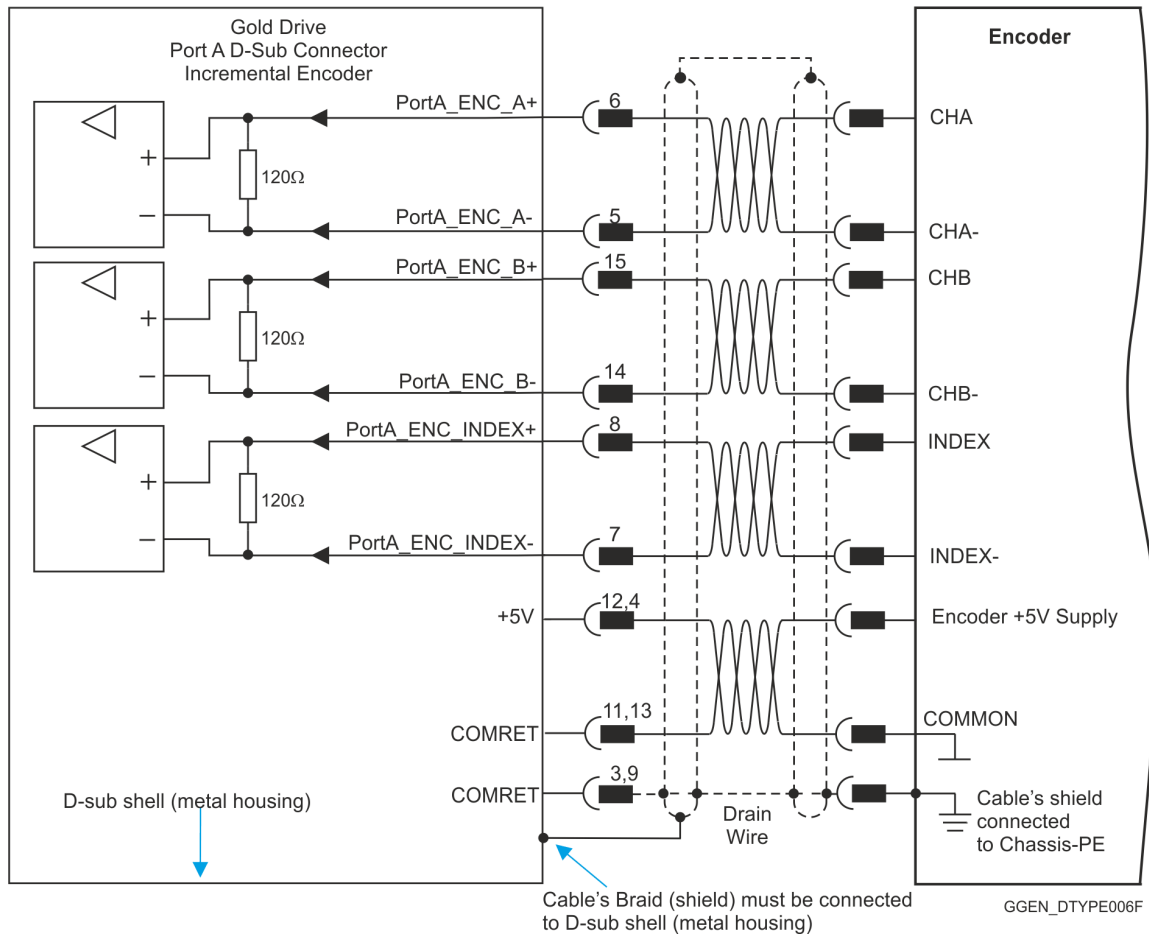


Figure 14: Port A D-Type Incremental Encoder Input – Recommended Connection Diagram

6.5.2 Hall Sensor

The following figure describes the connections at Port A for the Hall Sensor.

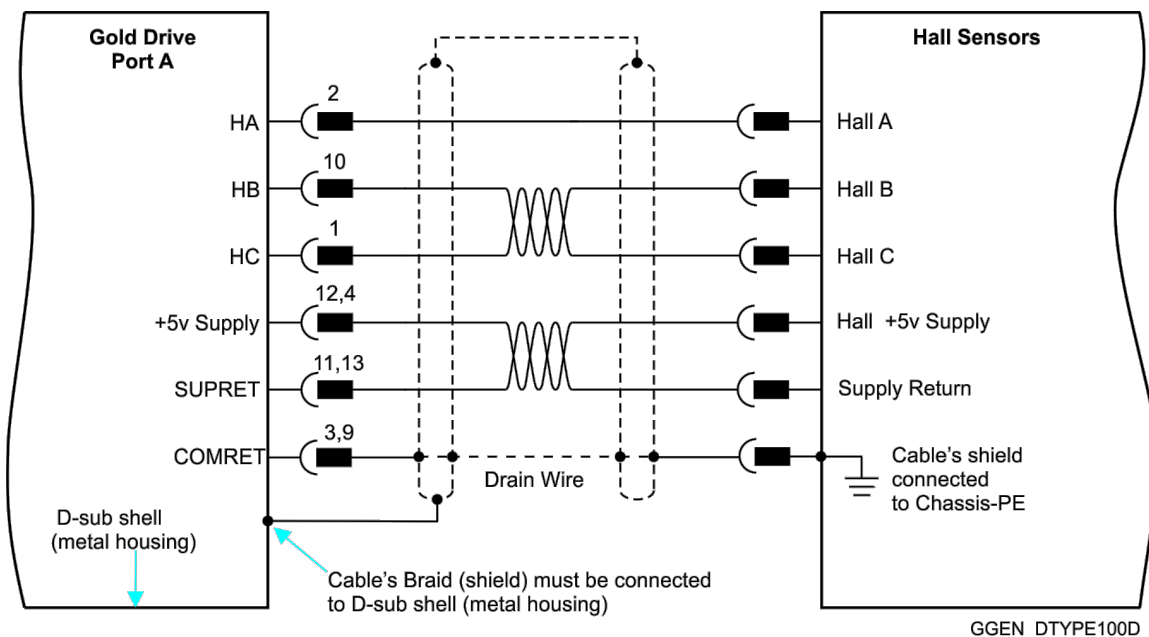
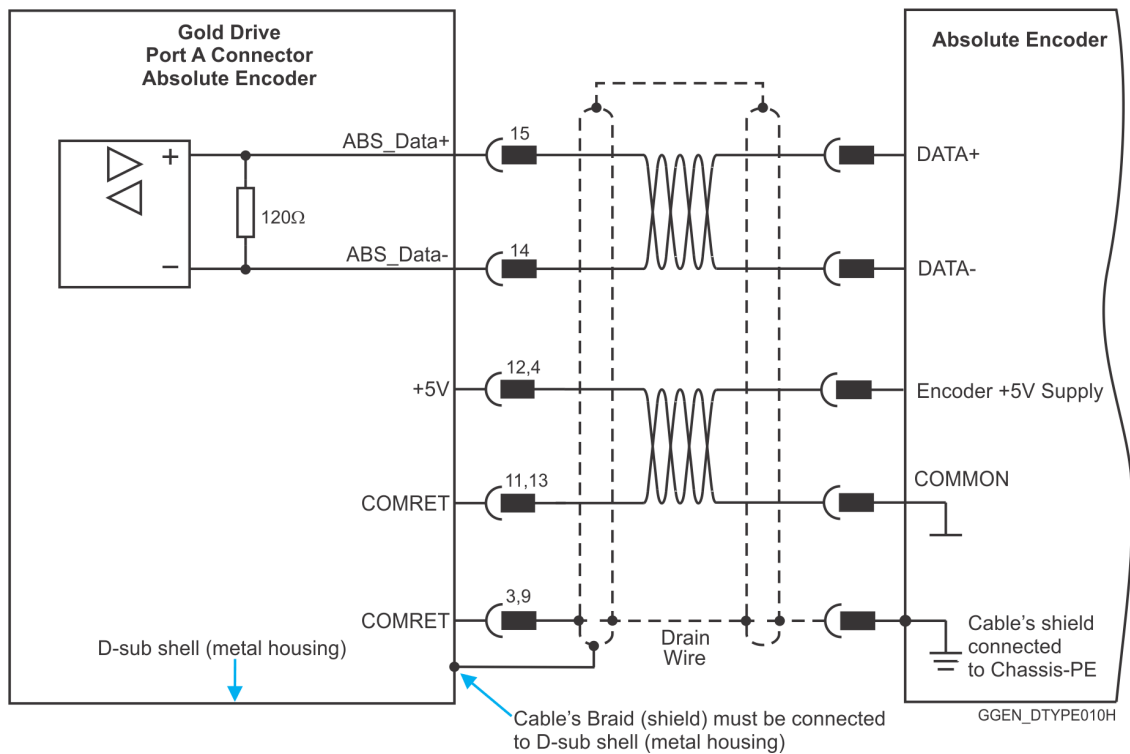
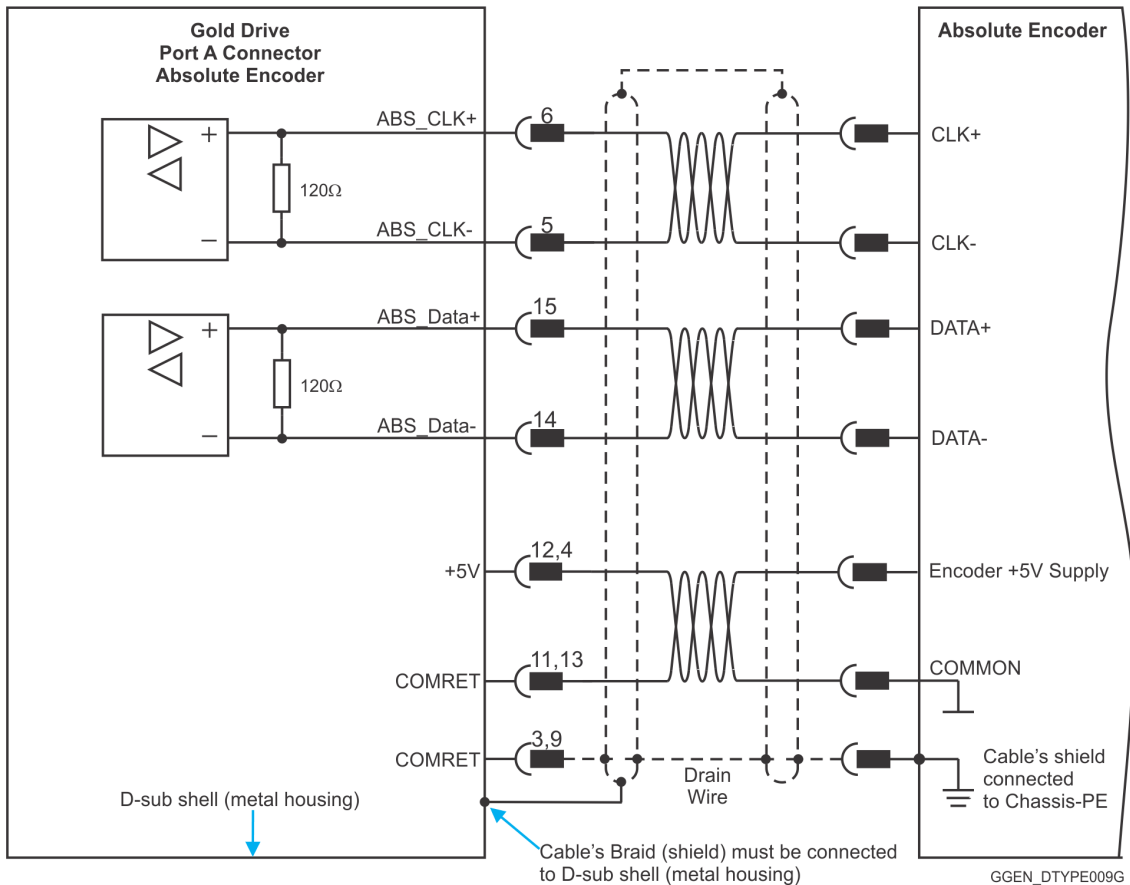


Figure 15: Hall Sensor Connection Diagram



6.5.3 Absolute Serial Type Encoder

The following figures describe the connections at Port A for the Absolute Serial type encoders.



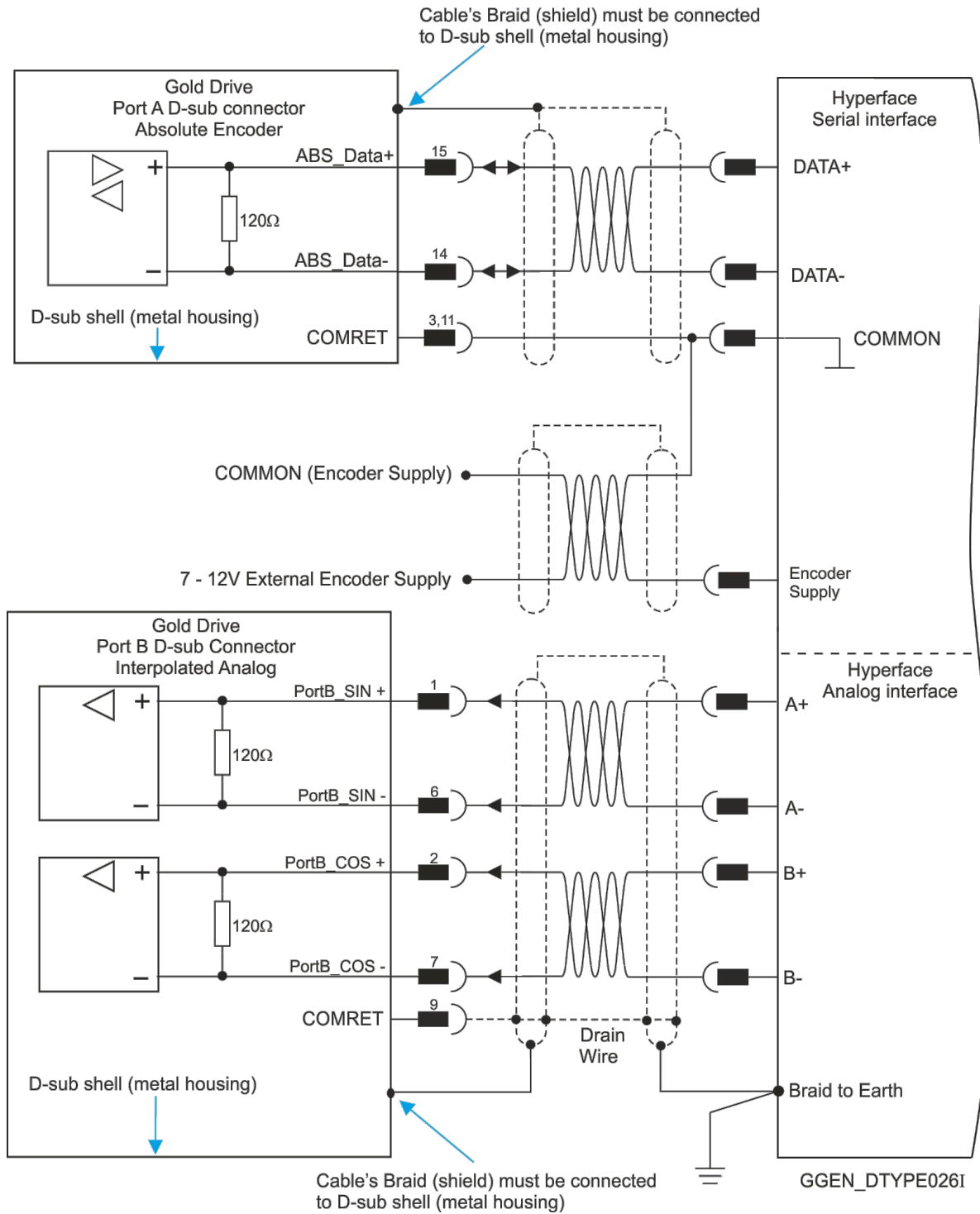


Figure 18: Absolute Serial Encoder – Recommended D-Type Connection Diagram for Stegmann Hiperface

Note: When the Hiperface protocol is used, the RS-232 connection is not available.

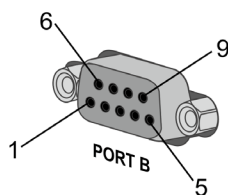
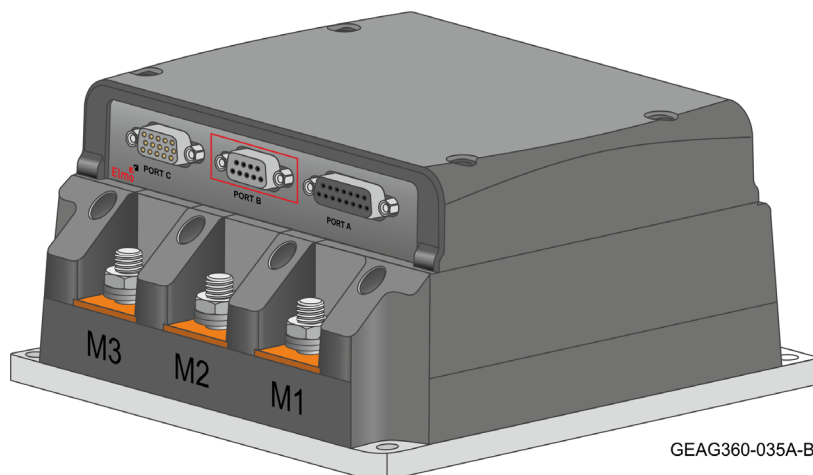


6.6 Port B Connector

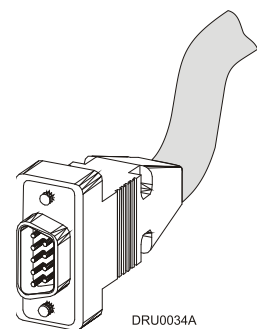
See Section 10.4 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

| Port B | Incremental or Interpolated Analog Encoder | | Resolver | |
|--------|--|----------------------|-------------------|-------------------------------------|
| | G-EAGX360/100XEXX | | G-EAGX360/100XRXX | |
| Pin | Signal | Function | Signal | Function |
| 4 | +5V | Encoder +5V supply | NC | NC |
| 5,9 | COMRET | Common Return | COMRET | Common Return |
| 1 | PortB_ENC_A+/SIN+ | Channel A+ / Sine+ | SIN+ | Sine+ |
| 6 | PortB_ENC_A-/SIN- | Channel A- / Sine- | SIN- | Sine- |
| 2 | PortB_ENC_B+/COS+ | Channel B+ / Cosine+ | COS+ | Cosine+ |
| 7 | PortB_ENC_B-/COS- | Channel B- / Cosine- | COS- | Cosine- |
| 3 | PortB_ENC_INDEX+ | Index+ | RESOLVER_OUT+ | Vref f=1/TS, 50 mA Max. |
| 8 | PortB_ENC_INDEX- | Index - | RESOLVER_OUT- | Vref complement f= 1/TS, 50 mA Max. |

Pin Positions



9-Pin D-Type Female Connector



9-Pin D-Type Male Connector

Table 4: Port B Pin Assignments



6.6.1 Incremental Encoder

The following figure describes the connections at Port B for the Incremental encoder.

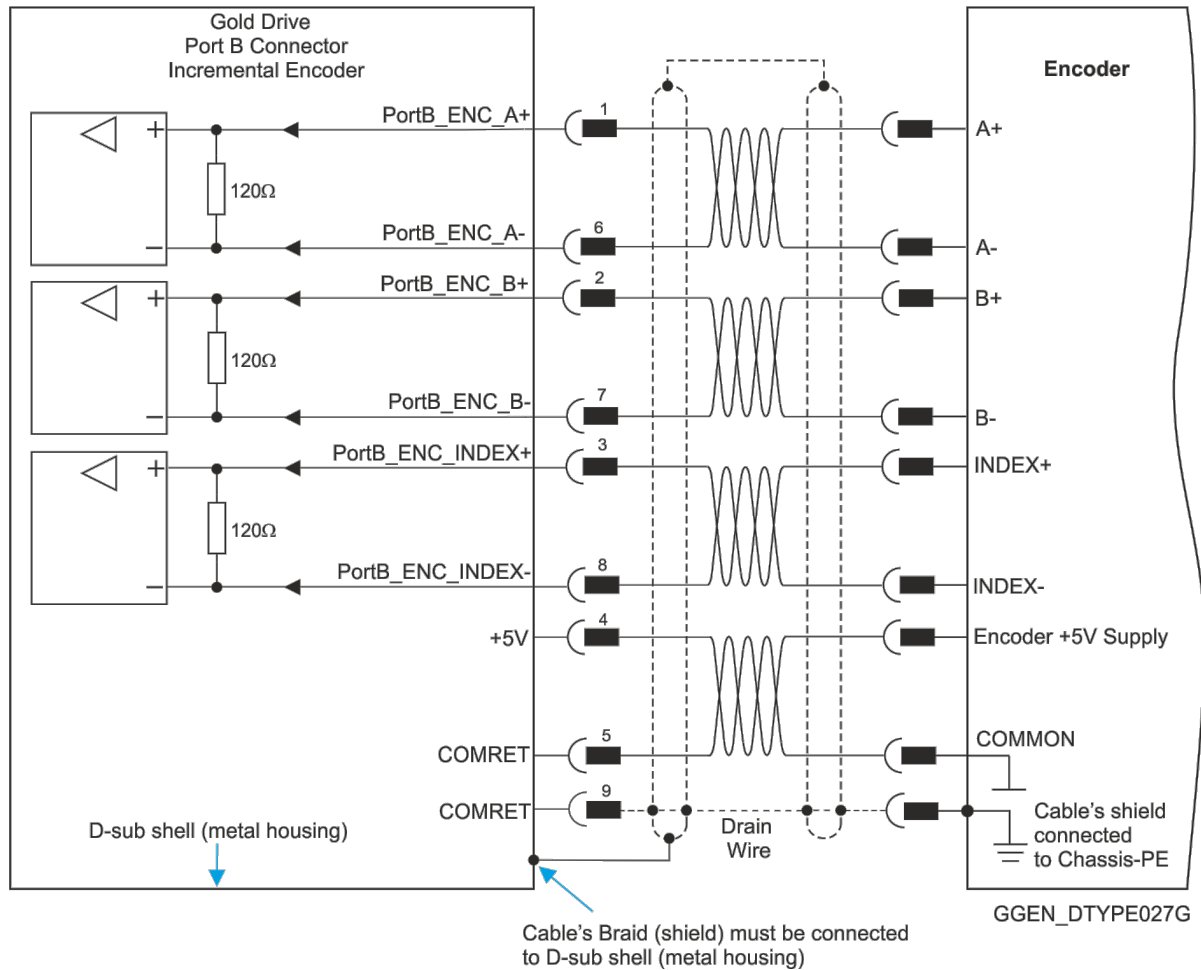


Figure 19: Port B Incremental Encoder Input – Recommended D-Type Connection Diagram



6.6.2 Interpolated Analog Encoder

The following figure describes the connections at Port B for the Interpolated Analog encoder.

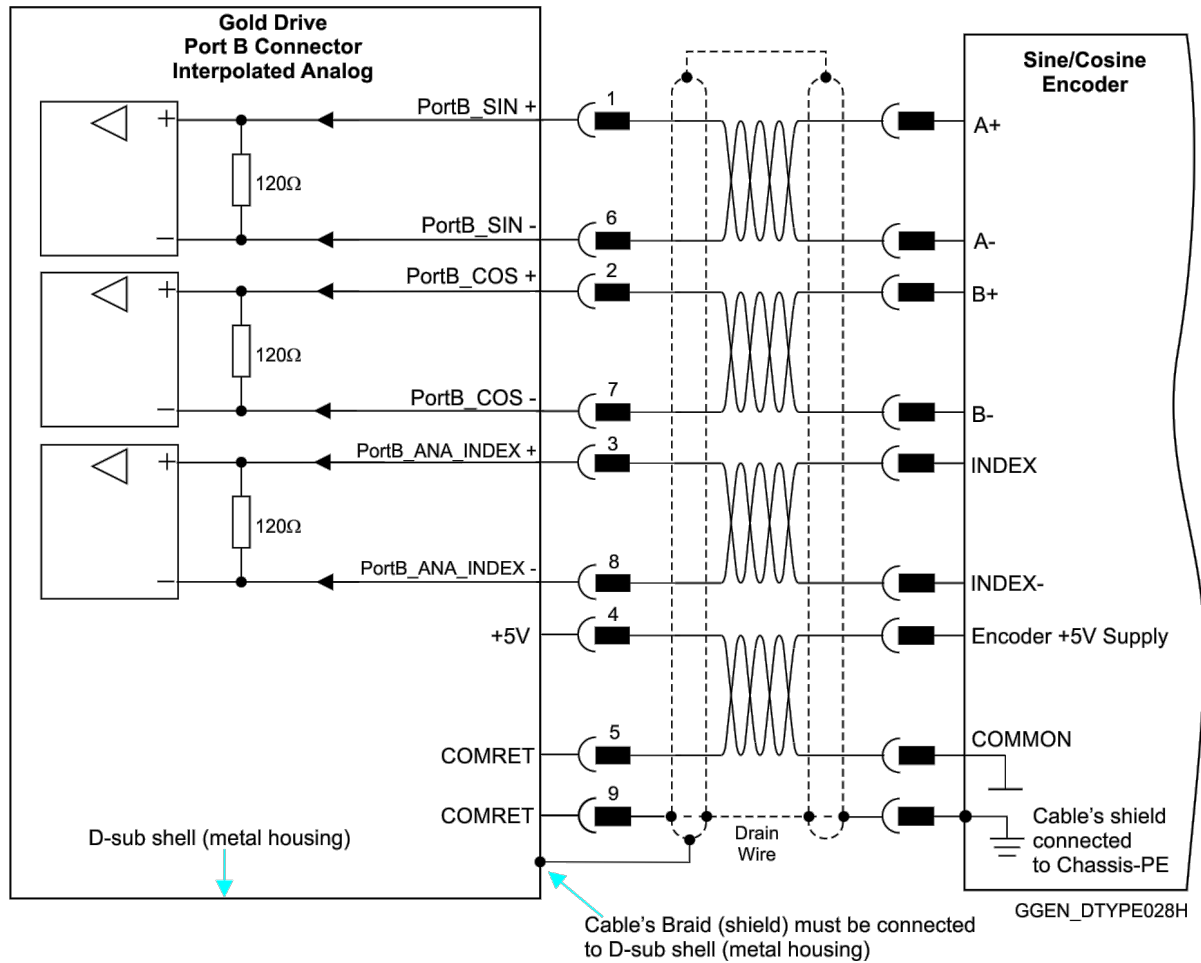


Figure 20: Port B - Interpolated Analog Encoder D-Type Connection Diagram



6.6.3 Resolver

The following figure describes the connections at Port B for the Resolver encoder.

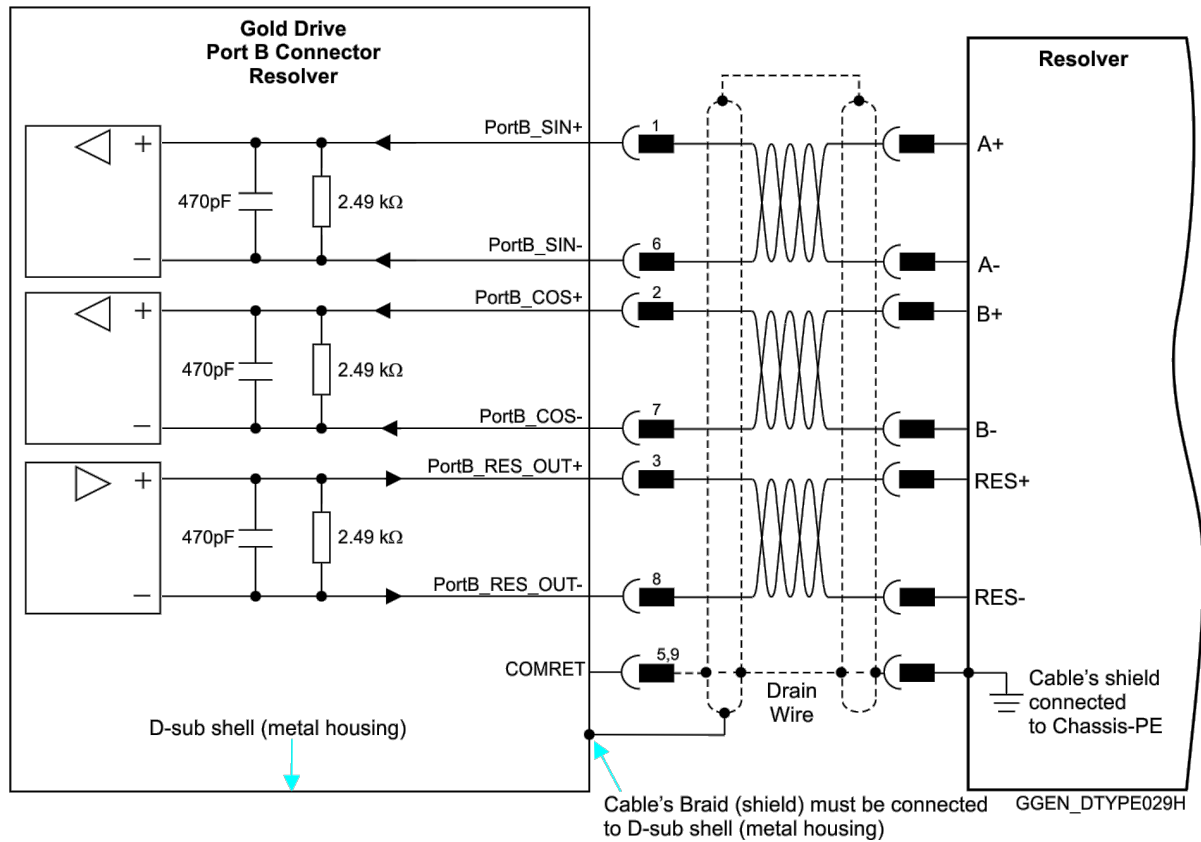


Figure 21: Port B – Resolver D-Type Connection Diagram



6.7 Port C, Analog Input, and STO

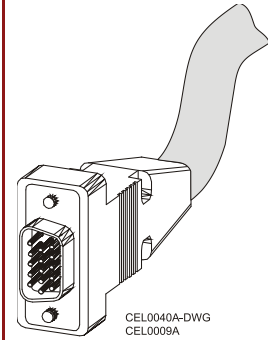
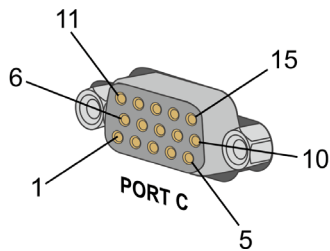
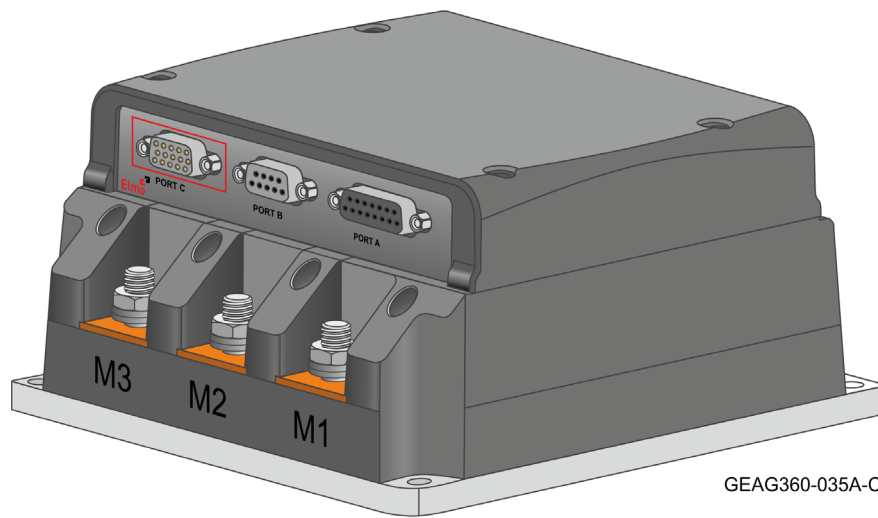
The Port C connector includes the following functions:

- Port C: Refer to Sections 10.5 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details
- STO: See Chapter 9 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.
- Analog input: See Section 11.2 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

| Pin on Port C | Signal | Function |
|---------------|-------------------|--|
| 1 | PortC_ENCO_A+ | Buffered Channel A+ output/Pulse+/PWM+ |
| 2 | PortC_ENCO_A- | Buffered Channel A- output / Pulse- / PWM- |
| 3 | PortC_ENCO_B+ | Buffered Channel B+ output / Dir+ |
| 4 | PortC_ENCO_B- | Buffered Channel B- output / Dir- |
| 5 | PortC_ENCO_Index+ | Buffered Channel INDEX+ output |
| 6 | STO1 | STO 1 input (default 24 V) |
| 7, 12 | STO_RET | STO signal return |
| 8 | Reserved | Reserved |
| 9 | COMRET | Common return |
| 10 | PortC_ENCO_Index- | Buffered Channel INDEX- output |
| 11 | STO2 | STO 2 input (default 24 V) |
| 13 | ANLRET | Analog ground |
| 14 | ANALOG1- | Analog input 1- |
| 15 | ANALOG1+ | Analog input 1+ |



Pin Positions



15-Pin High Density D-Type Male Connector

Table 5: Port C Pin Assignments



6.7.1 Port C

The following figure describes the connections at Port C for the Emulated Encoder Differential.

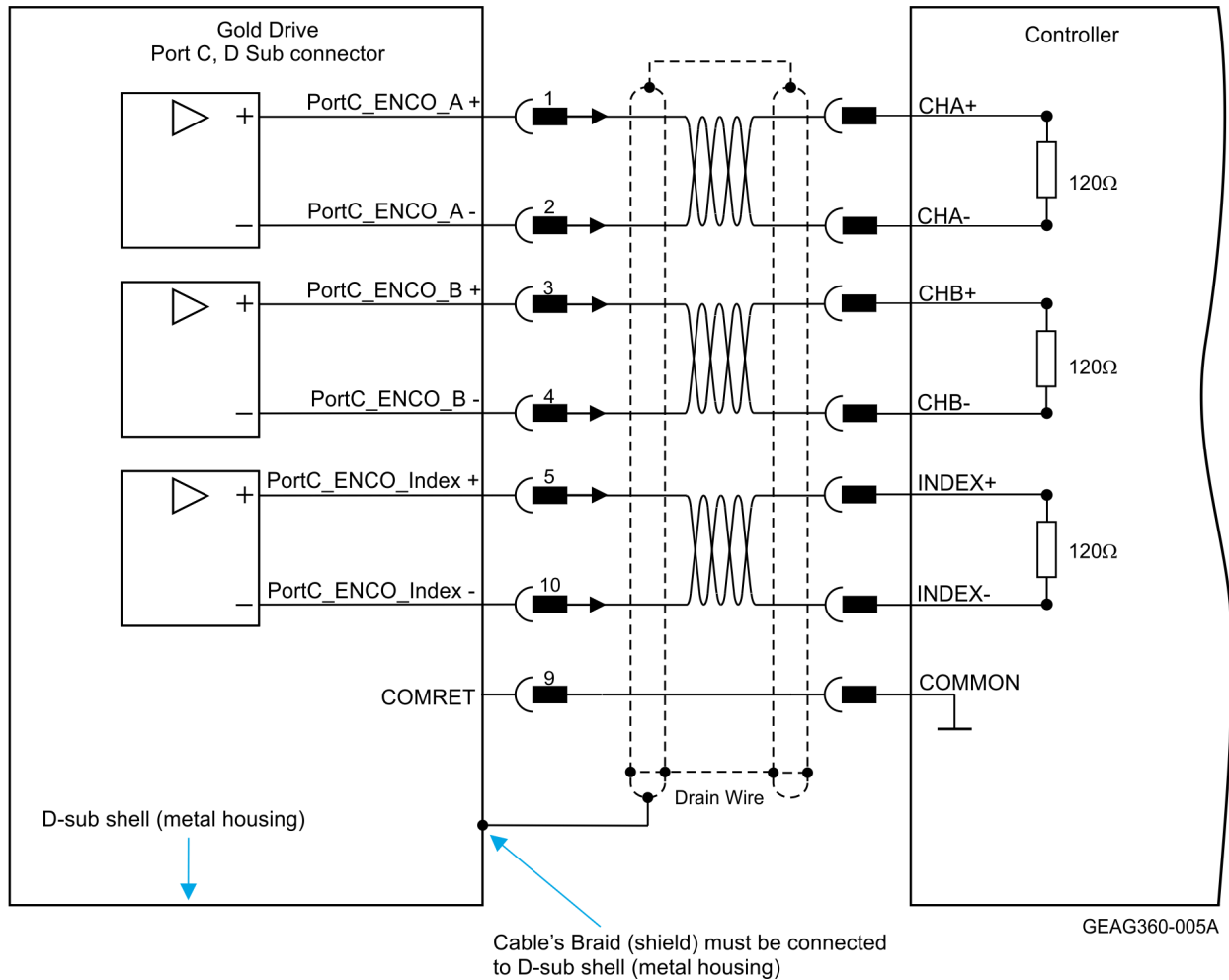


Figure 22: Emulated Encoder Differential Output – Recommended D-Type Connection Diagram

6.7.2 Analog Input

The following circuit describes the internal interface of the Analog input.

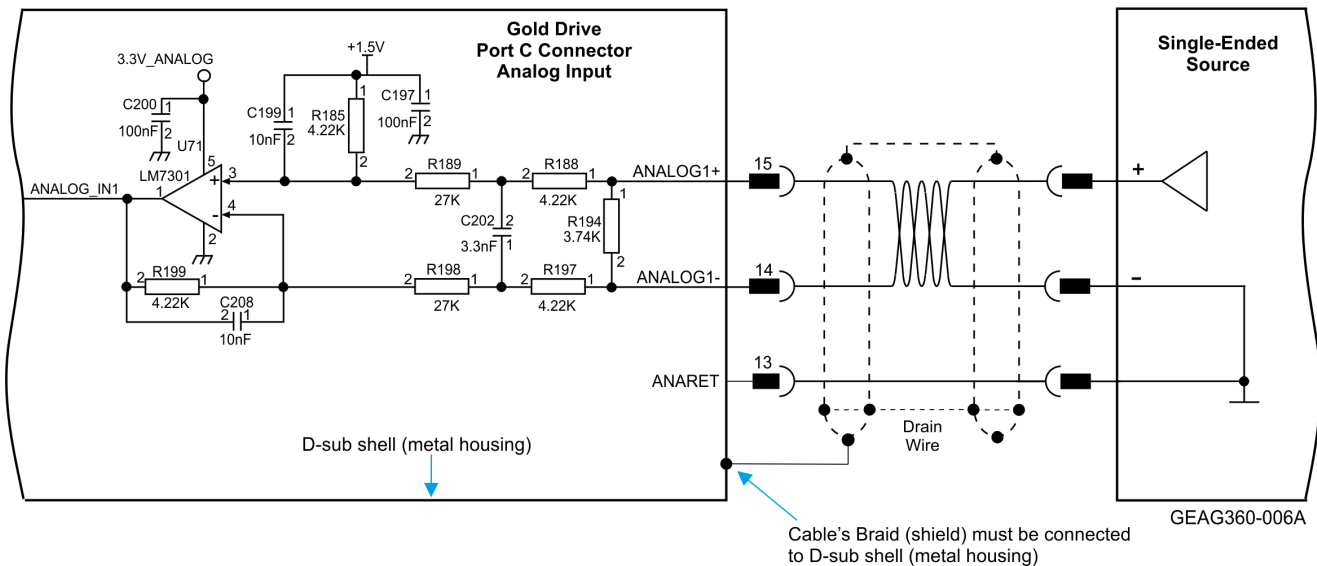


Figure 23: Differential Analog D-Type Input



6.7.3 STO

The following circuits describe the STO wiring options.

6.7.3.1 Source Mode PLC Voltage Level

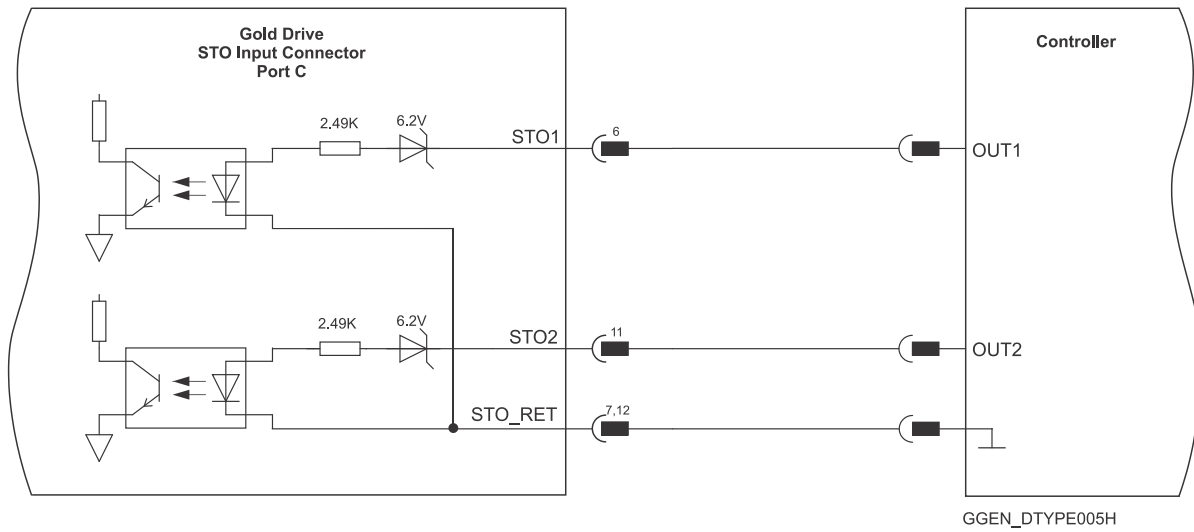


Figure 24: STO D-Type Input Connection – PLC Source Option

6.7.3.2 TTL Mode TTL Voltage Level

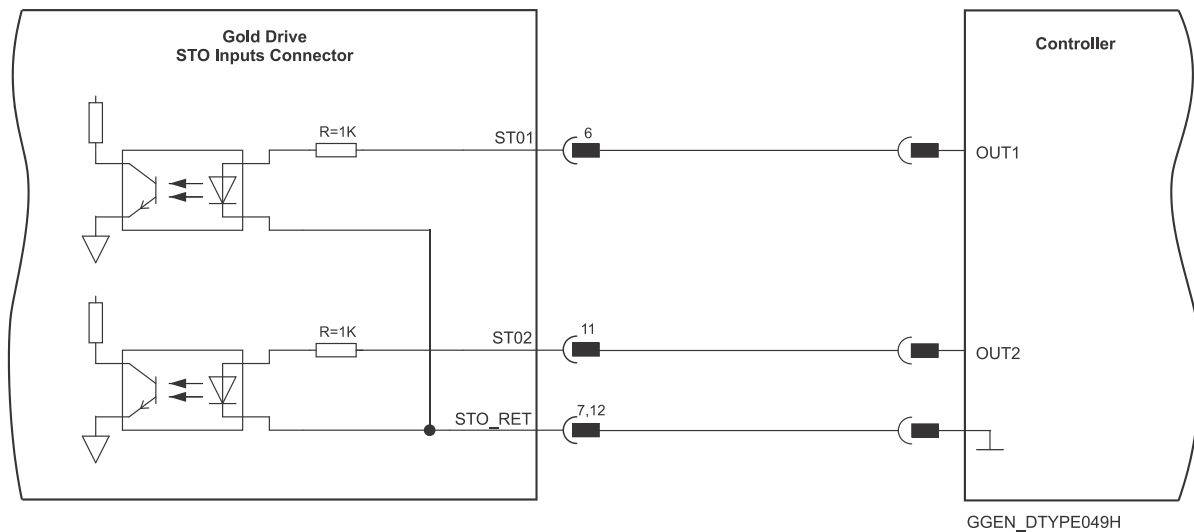


Figure 25: STO Input Connection – TTL Option



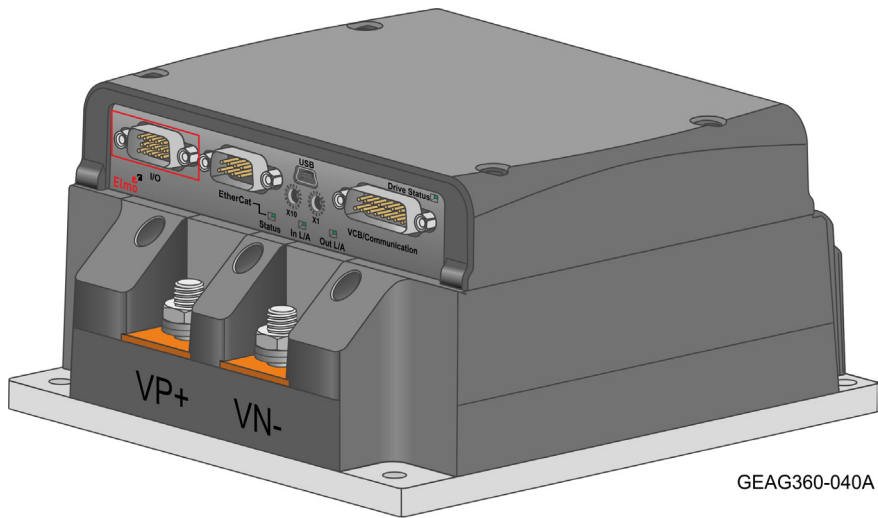
6.8 Digital Inputs and Outputs

Refer to Chapter 11 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

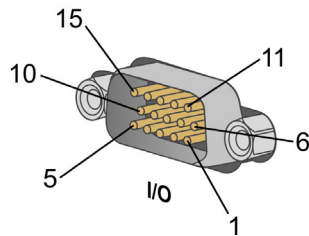
| I/O Pins | Signal | Function |
|----------|----------|---|
| 1 | IN1 | High speed programmable input 1 |
| 2 | IN2 | High speed programmable input 2 |
| 7 | IN3 | High speed programmable input 3 |
| 8 | IN4 | High speed programmable input 4 |
| 11 | IN5 | High speed programmable input 5 |
| 12 | IN6 | High speed programmable input 6 <i>or</i> |
| | | STO OUT Collector in the ○ version |
| 6 | INRET1-6 | Inputs 1 to 6 return for the Source version |
| | | Positive input 1 to 6 for the Sink version |
| 3 | OUT1 | Programmable output 1 |
| 4 | OUT2 | Programmable output 2 |
| 5 | OUT3 | Programmable output 3 |
| 13 | OUT4 | Programmable output 4 <i>or</i> |
| | | STO OUT Emitter in the ○ version |
| 10, 15 | VDD | Supply for out 1-4 |
| 9, 14 | VDDRET | Supply return for out 1-4 |



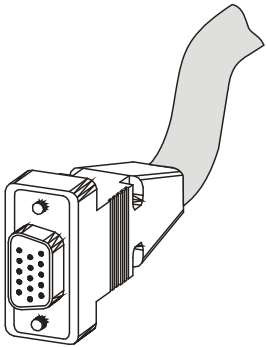
Pin Positions



GEAG360-040A



15-Pin High Density D-Type Male Connector



15-Pin High Density D-Type Female Connector

Table 6: I/O Connector Pin Assignments



6.8.1 Digital Input and Output TTL Source Mode

The following figure describes the connections at the I/O Port for the Digital Input and Output TTL Source Mode.

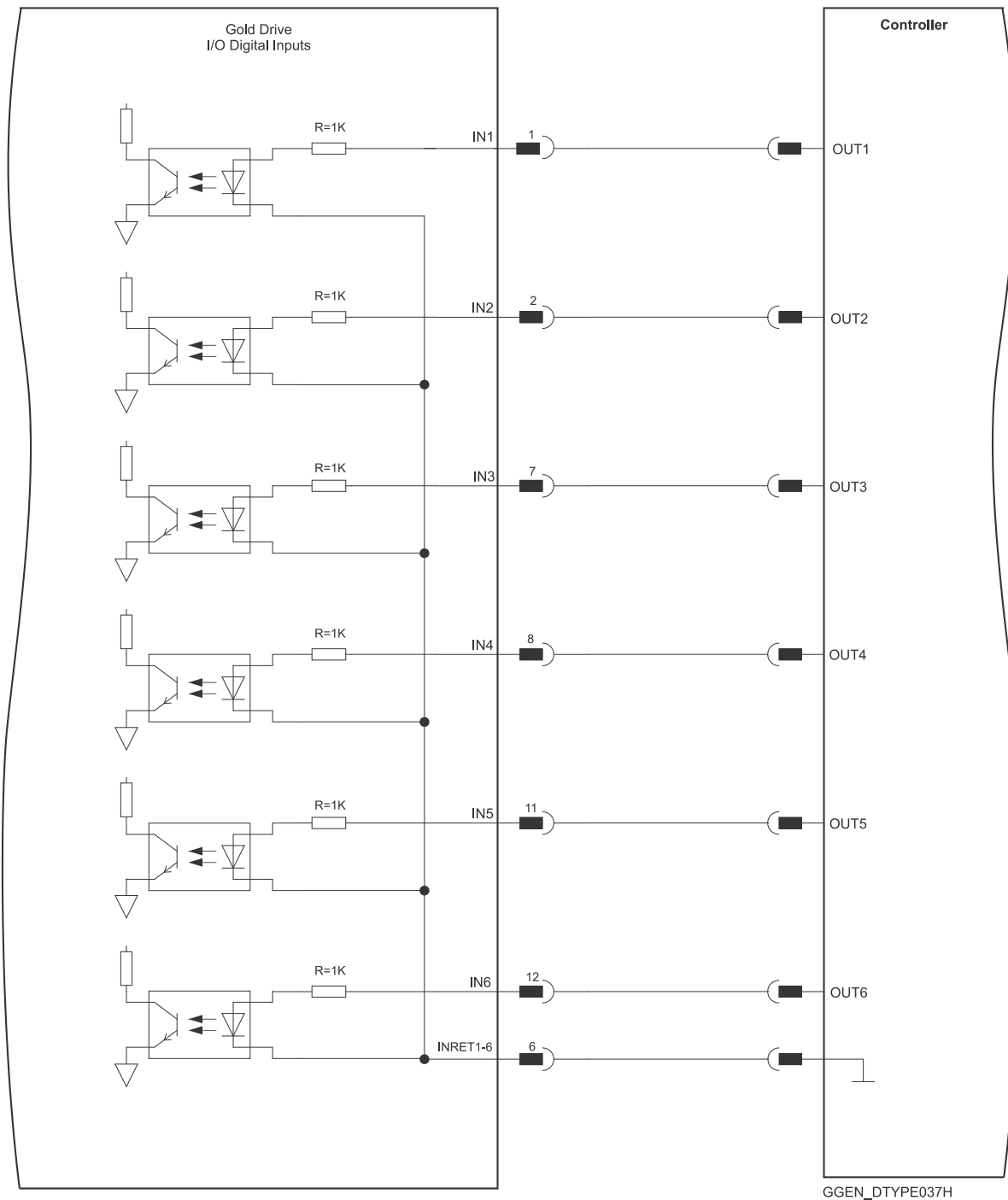


Figure 26: Digital Input TTL Source Mode D-Type Connection Diagram

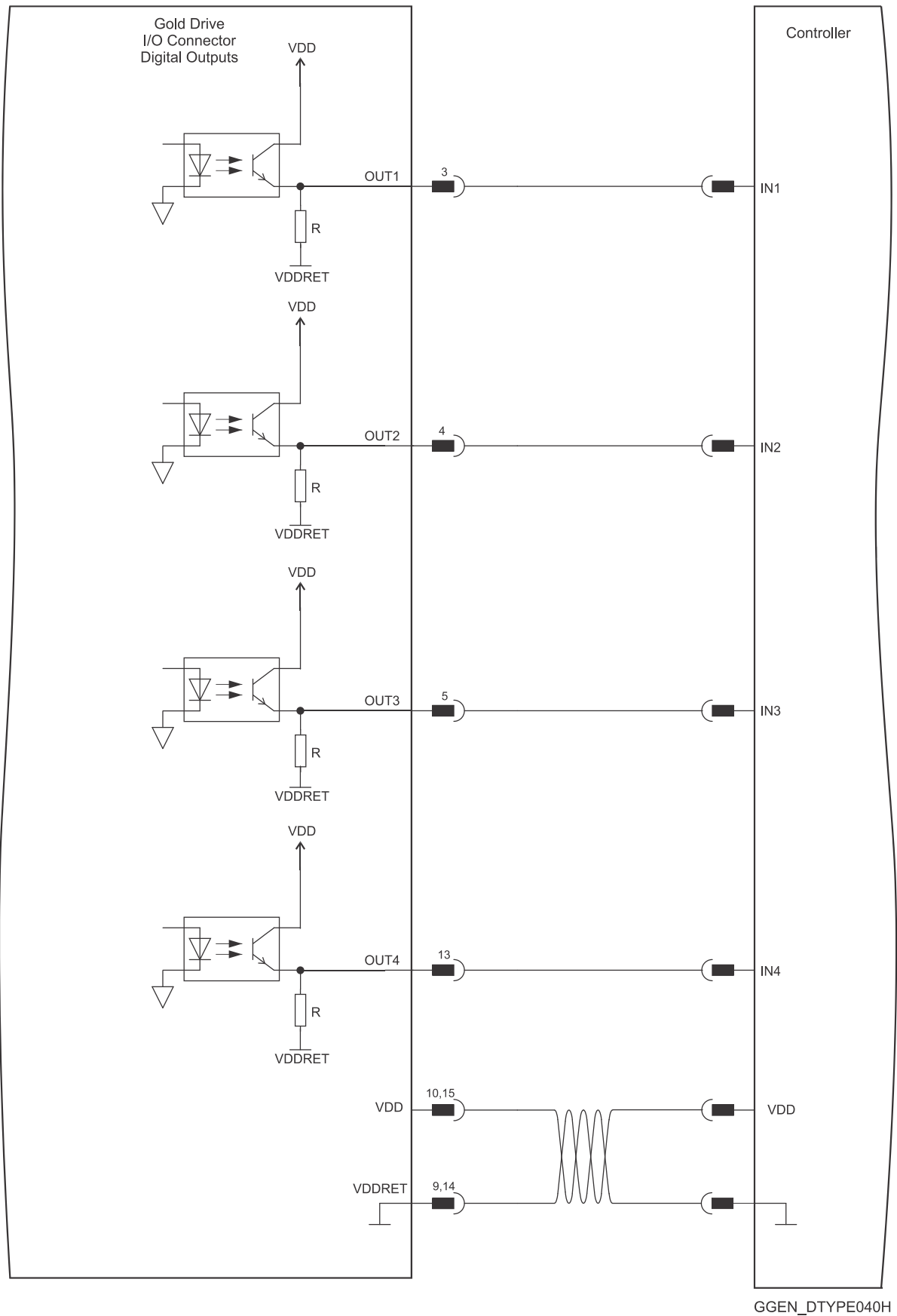


Figure 27: Digital Output D-Type Connection Diagram – TTL Source Option



6.8.2 Digital Input and Output PLC Source Mode

The following figure describes the connections at the I/O Port for the Digital Input and Output PLC Source Mode.

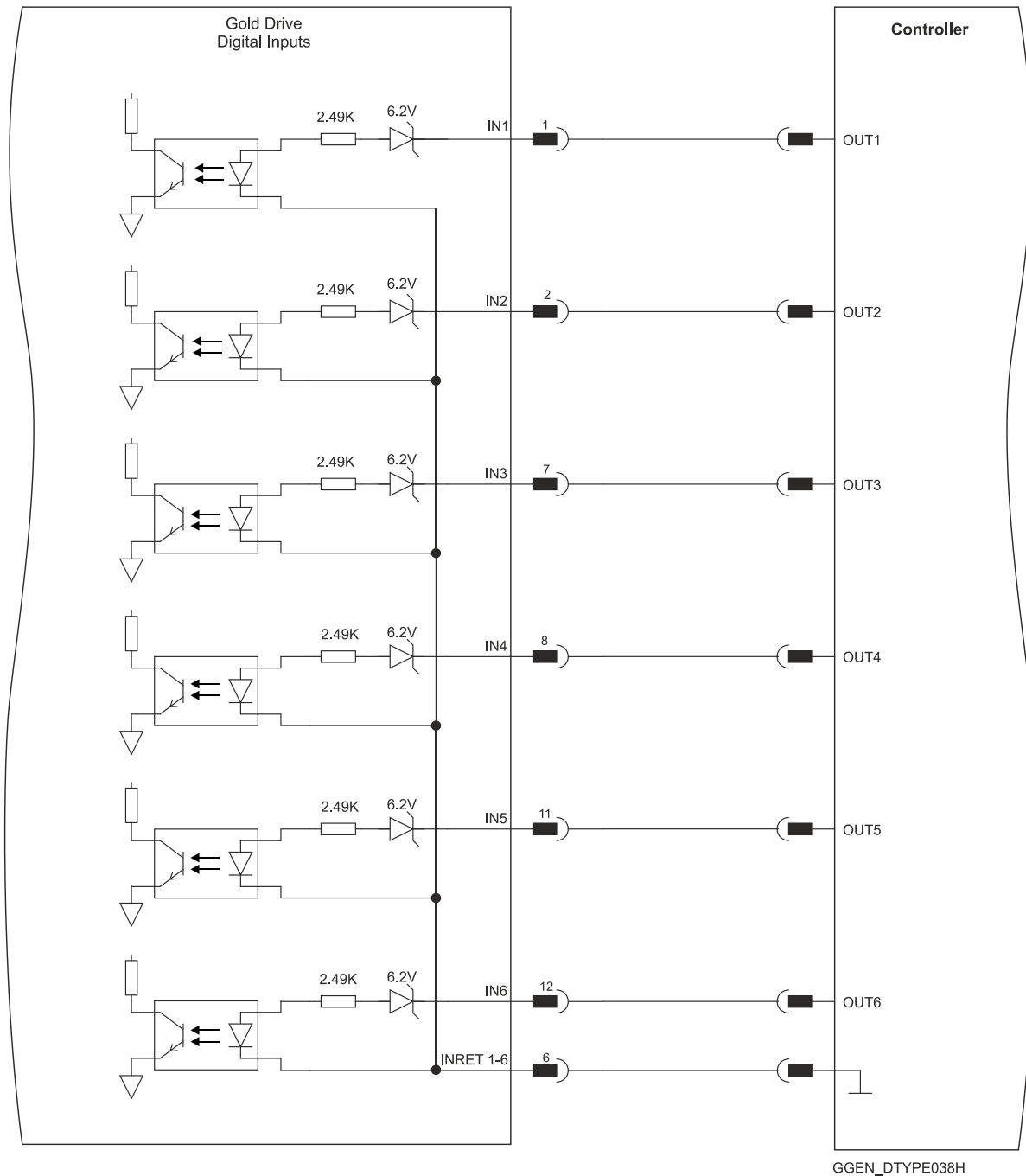


Figure 28: Digital Input D-Type Connection Diagram – Source PLC Option

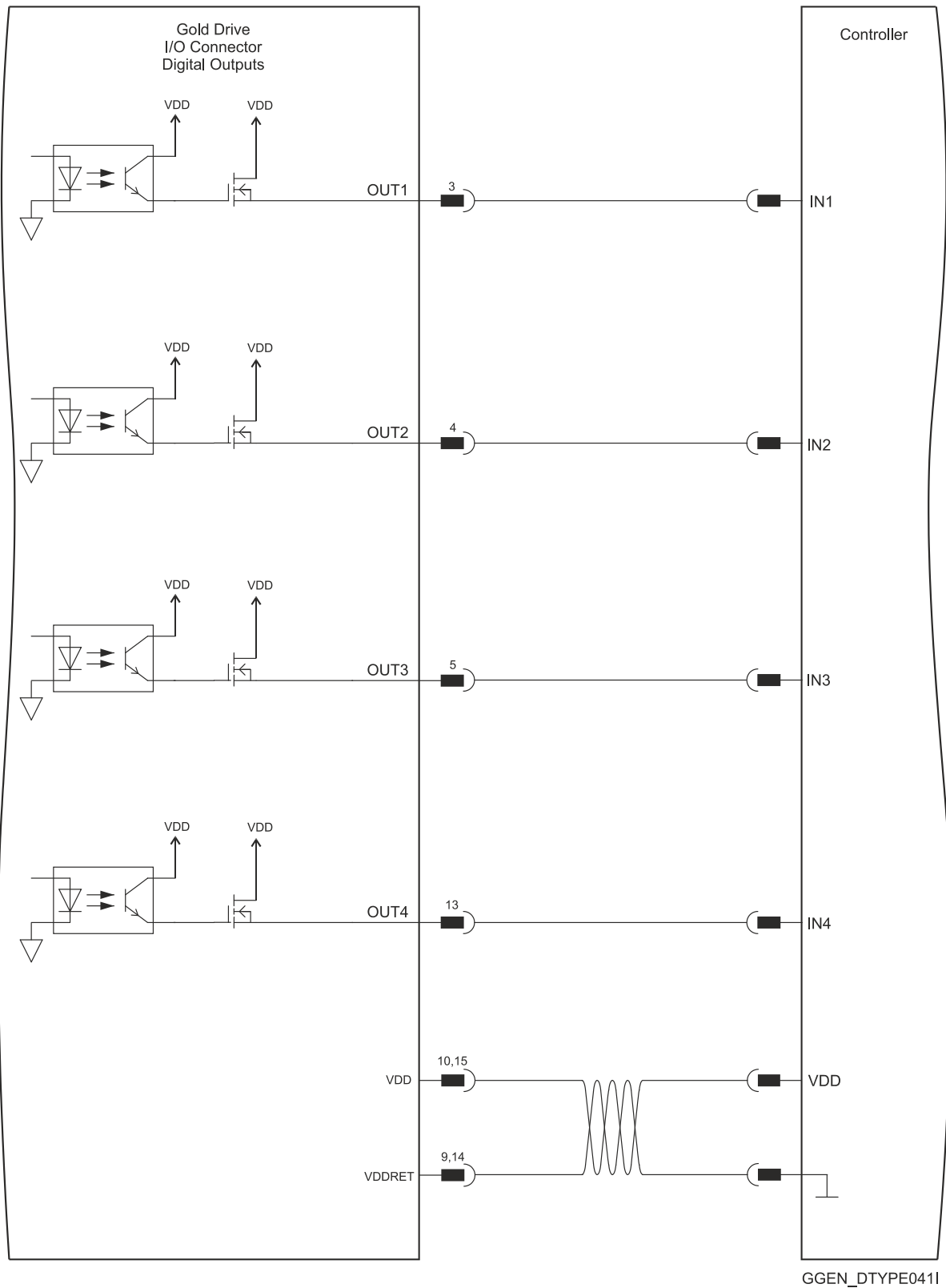


Figure 29: Digital Output D-Type Connection Diagram – Source PLC Option



6.8.3 Digital Input and Output PLC Sink Mode

The following figure describes the connections at the I/O Port for the Digital Input and Output PLC Sink Mode.

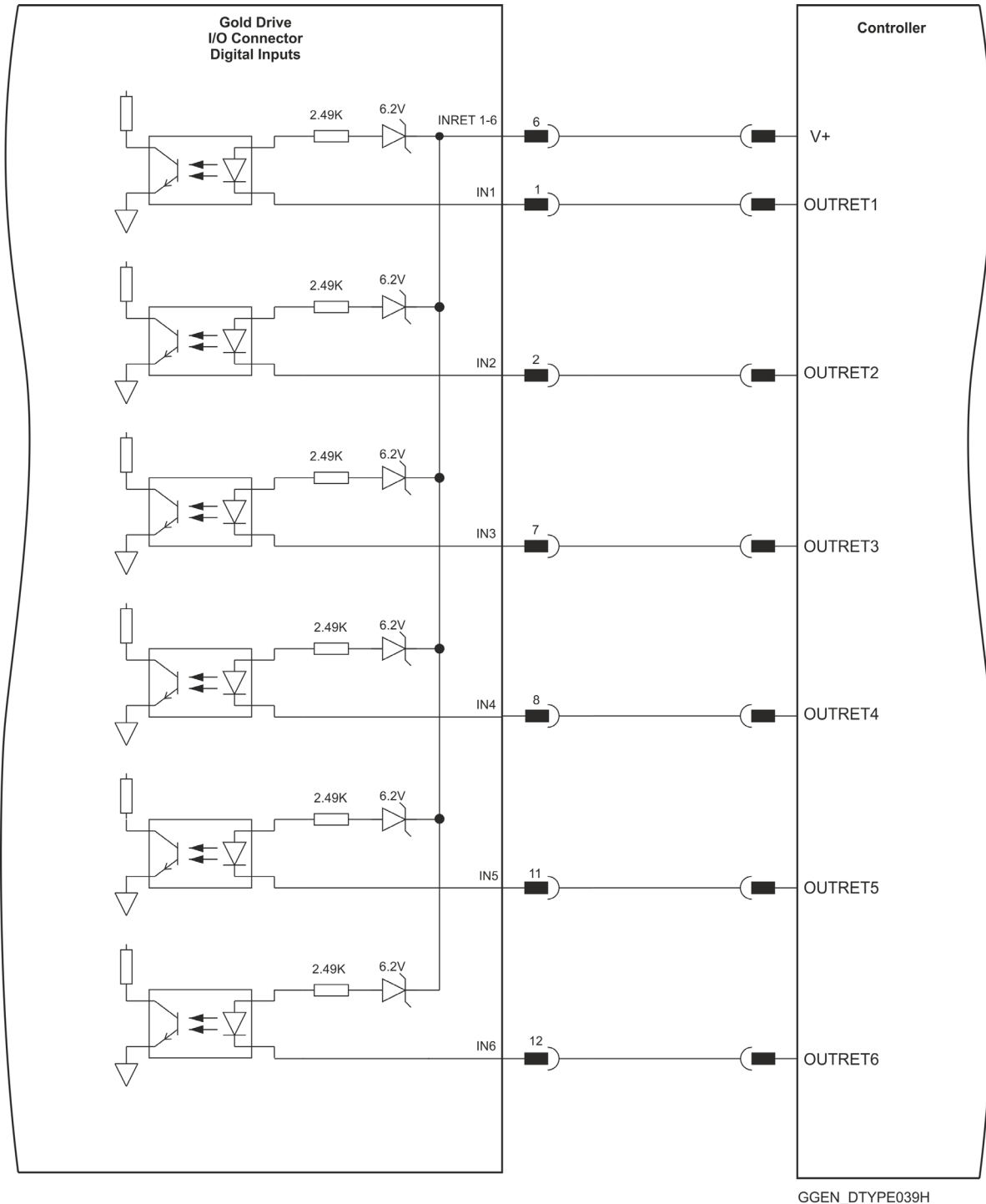


Figure 30: Digital Input PLC Sink Mode – PLC voltage level D-Type Connection Diagram

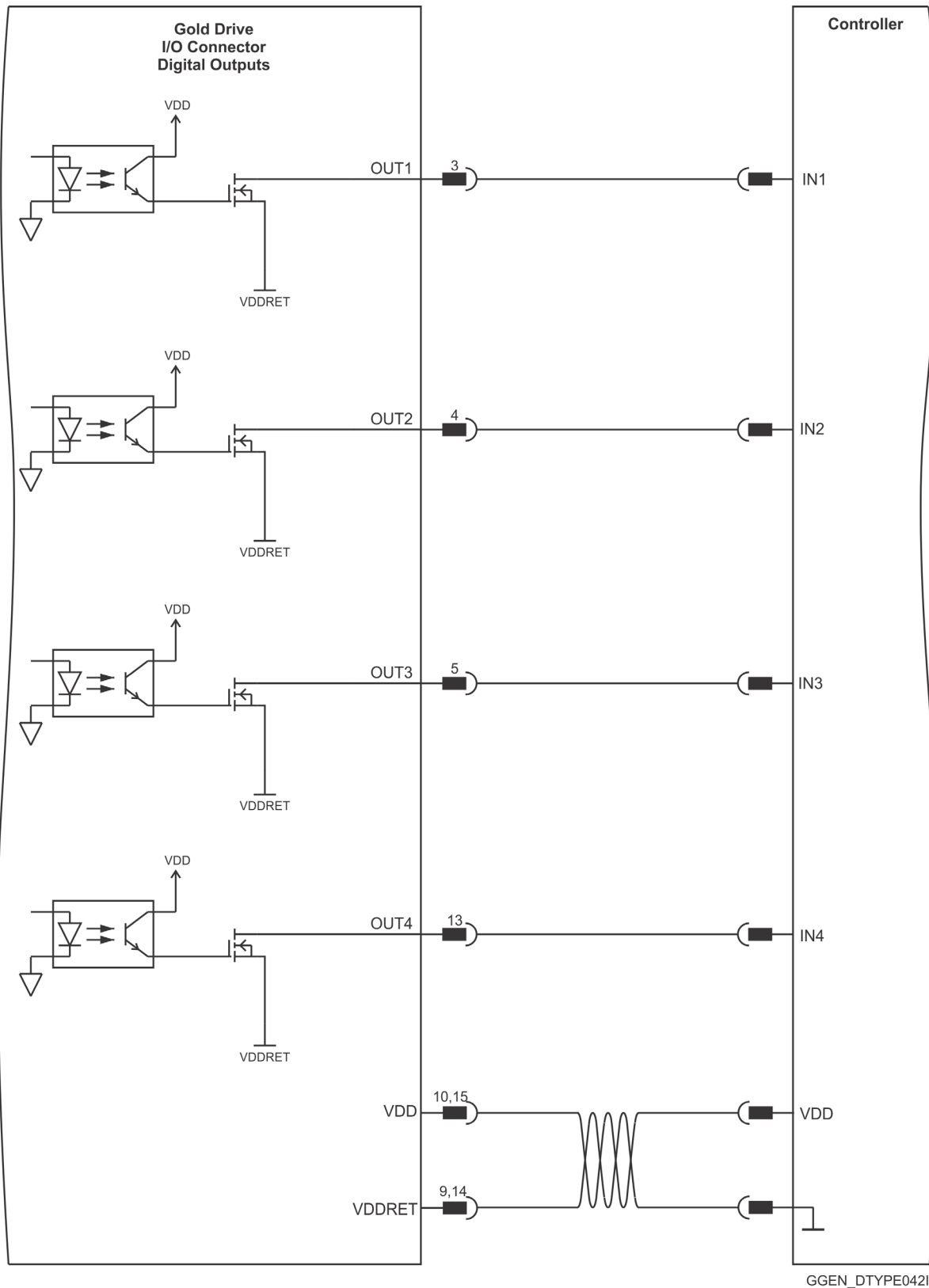


Figure 31: Digital Output as PLC Sink Configuration D-Type Connection Diagram



6.9 USB 2.0 Option 1

See Section 12.1 in the in the MAN-G-Panel Mounted Drives Hardware manual for full details.

Note: The USB connection can be either from the front mini USB connector or from the VCB/Communication D-Type connector.

Note: DO NOT connect the USB communication from the front mini USB and the VCB/Communication D-Type connector simultaneously.

| Pin on USB | Signal | Function |
|------------|------------|--------------------------|
| 1 | USB VBUS | USB VBUS 5V |
| 2 | USBD- | USB _N line |
| 3 | USBD+ | USB _P line |
| 5 | USB COMRET | USB communication return |

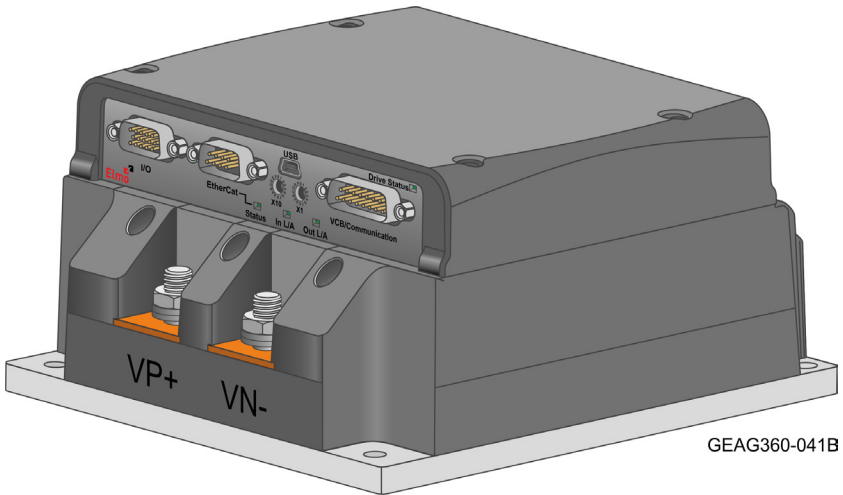
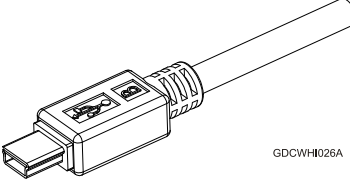
| Pin Positions | |
|---|---|
|  |  |
| | <p>USB Device Mini B Plug</p> |

Table 7: USB 2.0 Pin Assignments

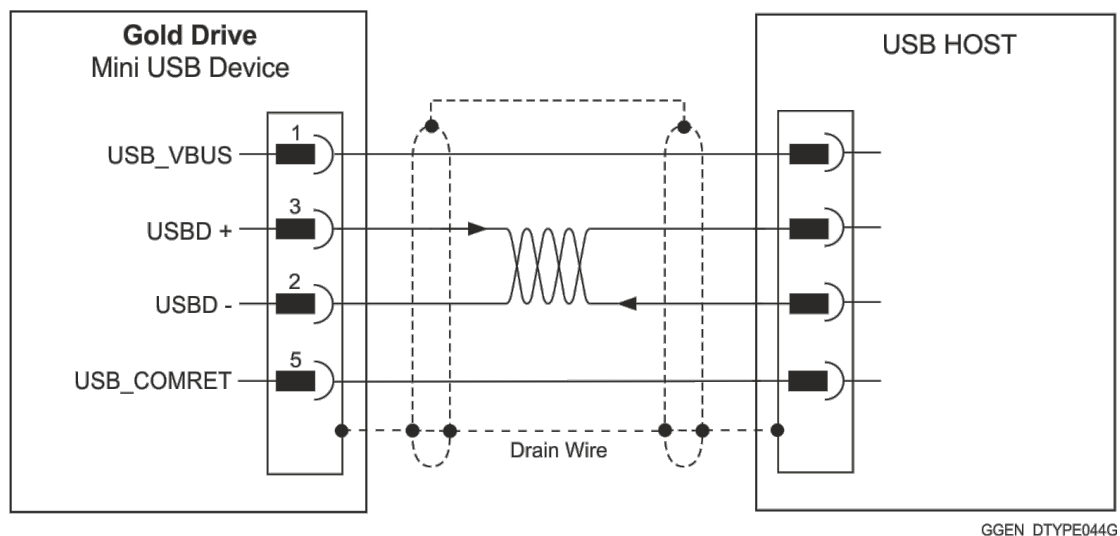


Figure 32: USB Network Diagram



6.10 VCB/Communication Connector

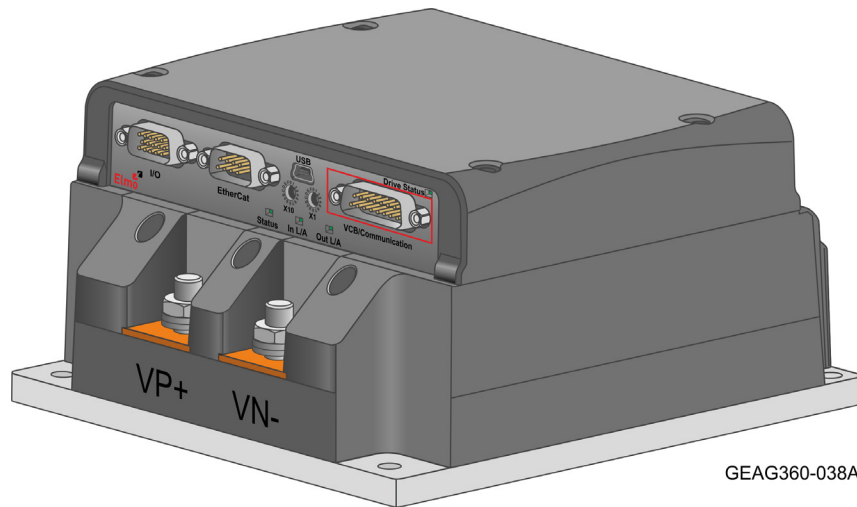
Note: The USB connection can be either from the front mini USB connector or from the VCB/Communication D-Type connector.

DO NOT connect the USB communication from the front mini USB and the VCB/Communication D-Type connector simultaneously.

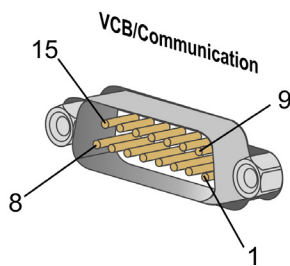
| Pin | Signal | Function |
|-----|---------------------------|--|
| 2 | USB_VBUS | USB VBUS 5V |
| 1 | USB D- | USB _N line |
| 9 | USB D+ | USB _P line |
| 10 | USB COMRET | USB Common Return |
| 3 | COMRET | Common Return (connected to the drain wire of cable) |
| 11 | COMRET | Common Return |
| 4 | RS-232_RX/RS-422_RX+ | RS-232 Receive/RS-422 Receive+ |
| 5 | RS-422_TX- | RS-422 Transmit- |
| 13 | RS-422_TX+ | RS-422 Transmit+ |
| 12 | RS-232_TX/RS-422_RX- | RS-232 Transmit/RS-422 Receive- |
| 15 | Not in use | |
| 7 | Not in use | |
| 14 | VCB Supply Input Positive | DC Power |
| 6 | COMRET | DC Power |
| 8 | VCB Supply Shield | Drain wire cable |



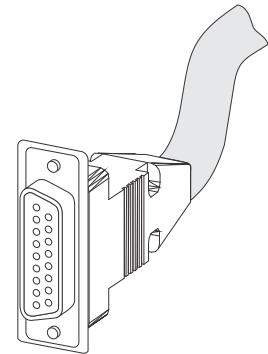
Pin Positions



GEAG360-038A



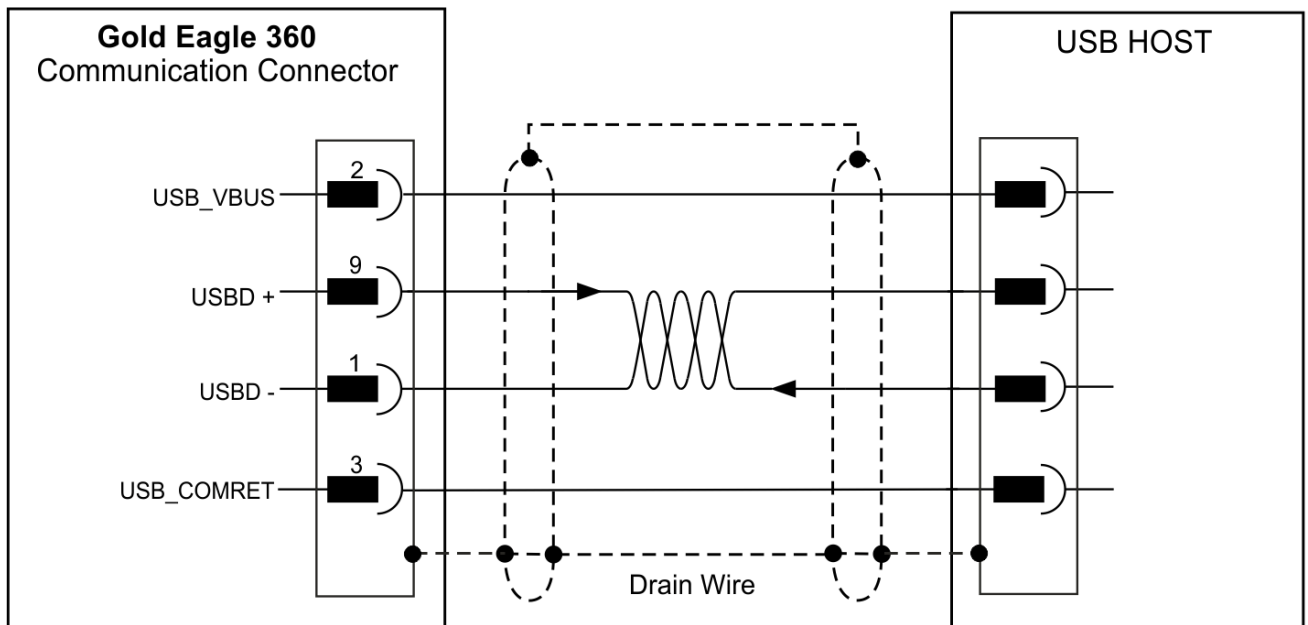
15-Pin D-Type Male Connector



GEAGHV022A

15-pin D-Type Female Connector

6.10.1 USB 2.0 Option 2



GEAG360-052A

Figure 33: USB Network Diagram



6.10.2 RS-232

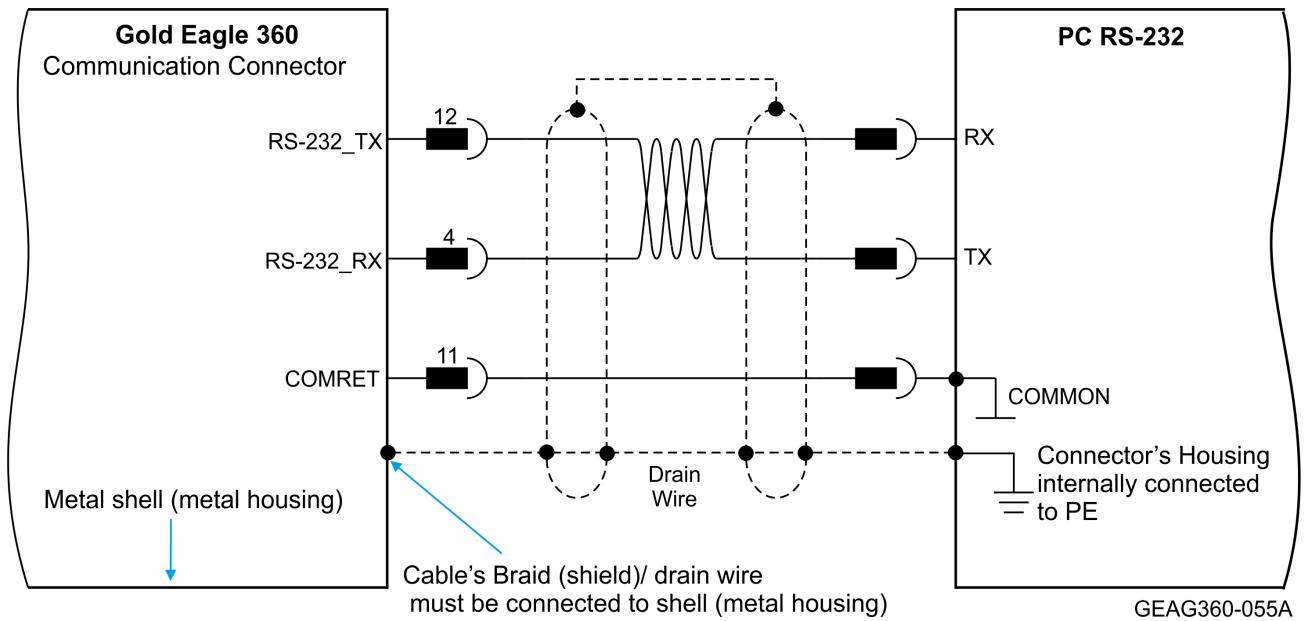


Figure 34: RS-232 D-Type Connection Diagram Example

6.10.3 RS-422 (Differential RS-232)

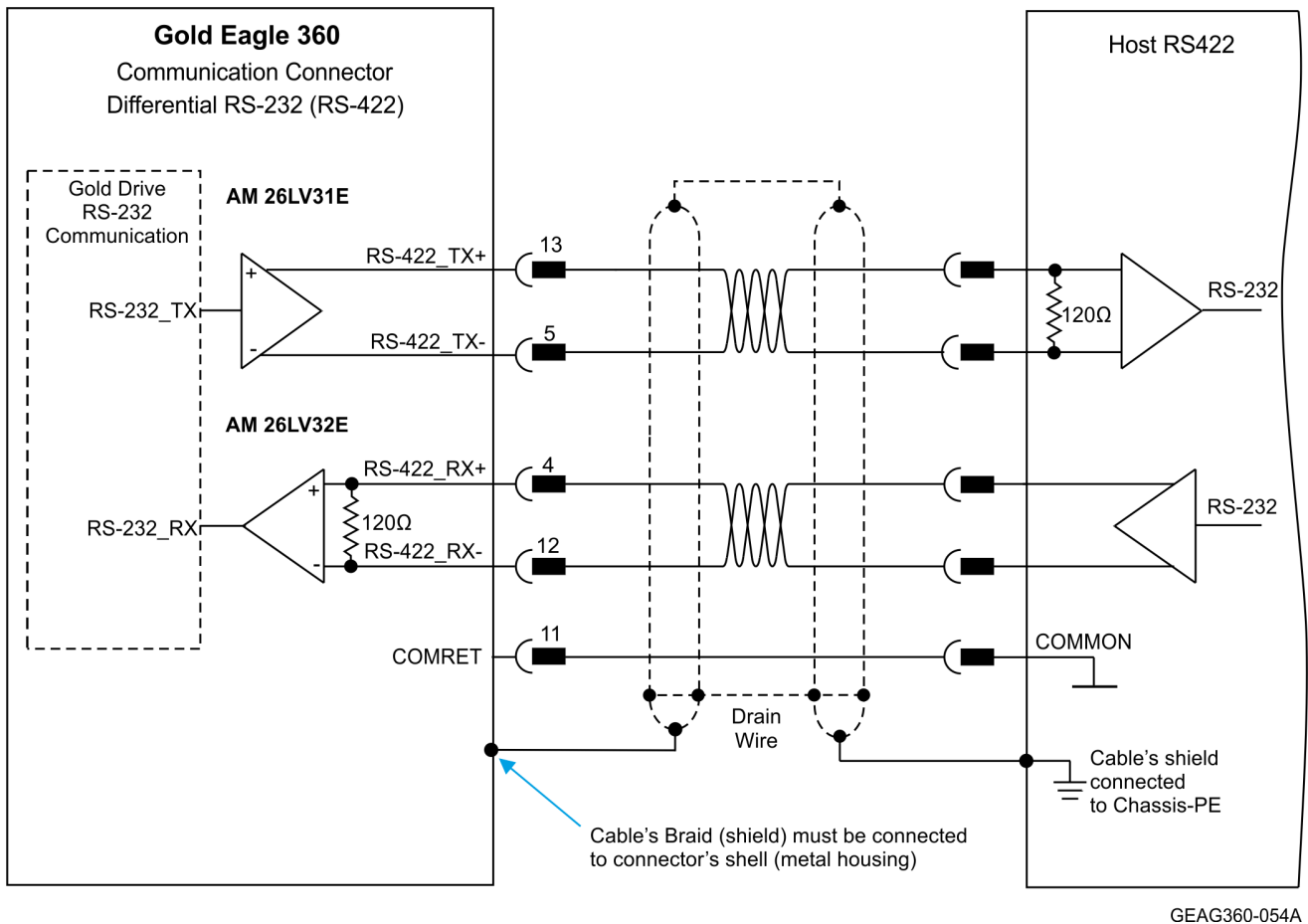


Figure 35: Differential RS-232 D-Type Connection Diagram Example



6.11 EtherCAT Communications Version

The Gold Eagle 360/430 supports EtherCAT fieldbus industrial network protocol.

| Fieldbus Type | Product Number |
|---|--|
| EtherCAT + RS-232 | G-EAGR360/100EXXX G-EAGR430/80EXXX |
| EtherCAT with switches | G-EAGR360/100FXXX G-EAGR430/80FXXX |
| EtherCAT + Differential RS-232 (RS-422) | G-EAGR360/100GXXX G-EAGR430/80GXXX |

6.11.1 EtherCAT/Ethernet Pinouts

See Section 6.8.2 in the manual: MAN-G-Drive Hardware for the electrical diagram.

| Pin | Signal | Function |
|-----|------------------------------|---|
| 1 | EtherCAT_IN_TX+/Ethernet_TX+ | EtherCAT in transmit+/Ethernet transmit + |
| 2 | EtherCAT_IN_RX+/Ethernet_RX+ | EtherCAT in receive+/Ethernet receive+ |
| 3 | EtherCAT_OUT_TX+ | EtherCAT out transmit+ |
| 4 | EtherCAT_OUT_RX+ | EtherCAT out receive+ |
| 5 | EtherCAT Shield | Drain wire cable |
| 6 | EtherCAT_IN_TX-/Ethernet_TX- | EtherCAT in transmit-/Ethernet transmit- |
| 7 | EtherCAT_IN_RX-/Ethernet_RX- | EtherCAT in receive-/Ethernet receive- |
| 8 | EtherCAT_OUT_TX- | EtherCAT out transmit- |
| 9 | EtherCAT_OUT_RX- | EtherCAT out receive- |



Pin Positions

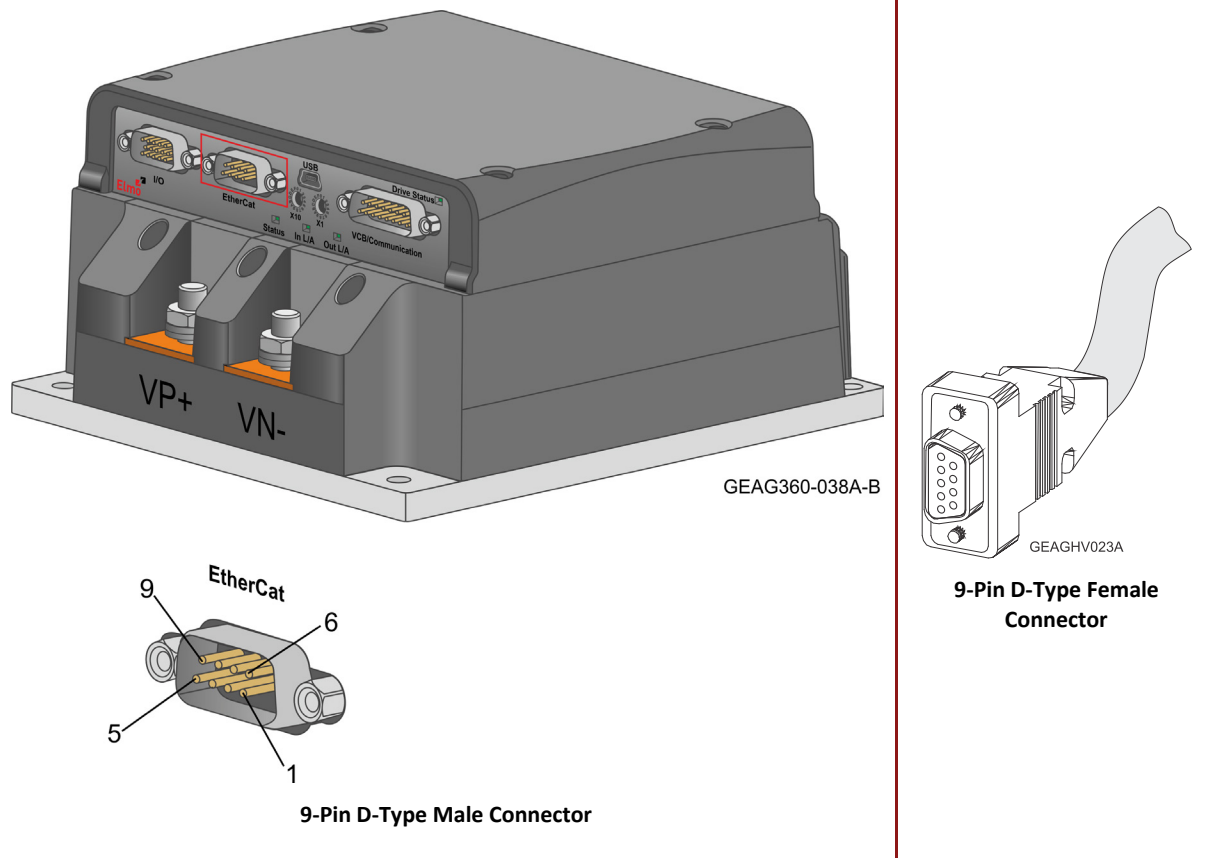


Table 8: EtherCAT Connector Pin Assignments

6.11.2 EtherCAT Wiring

Figure 36 describes the wiring diagram for the EtherCAT connections.

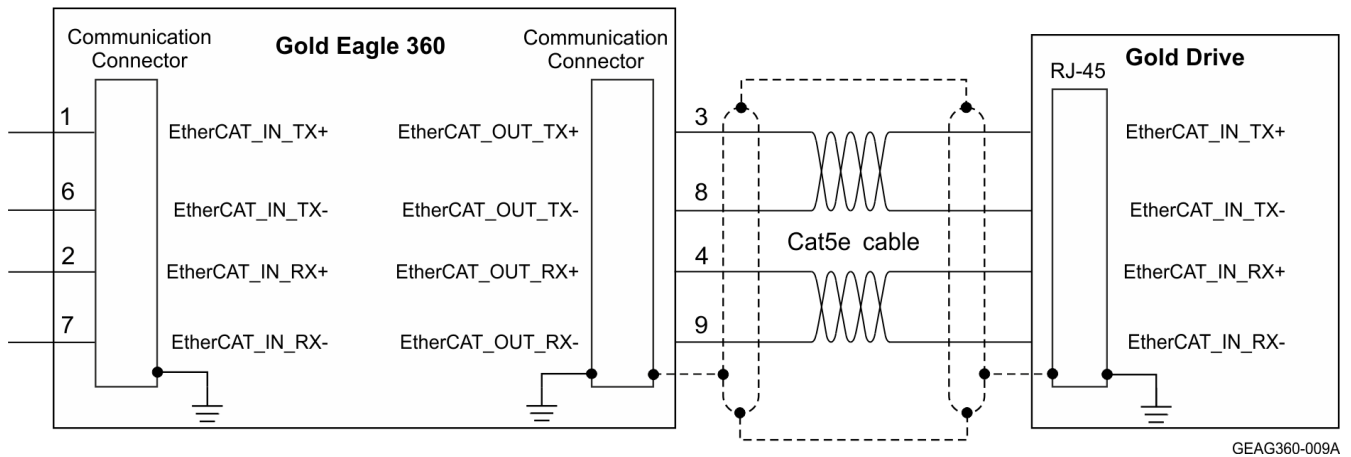
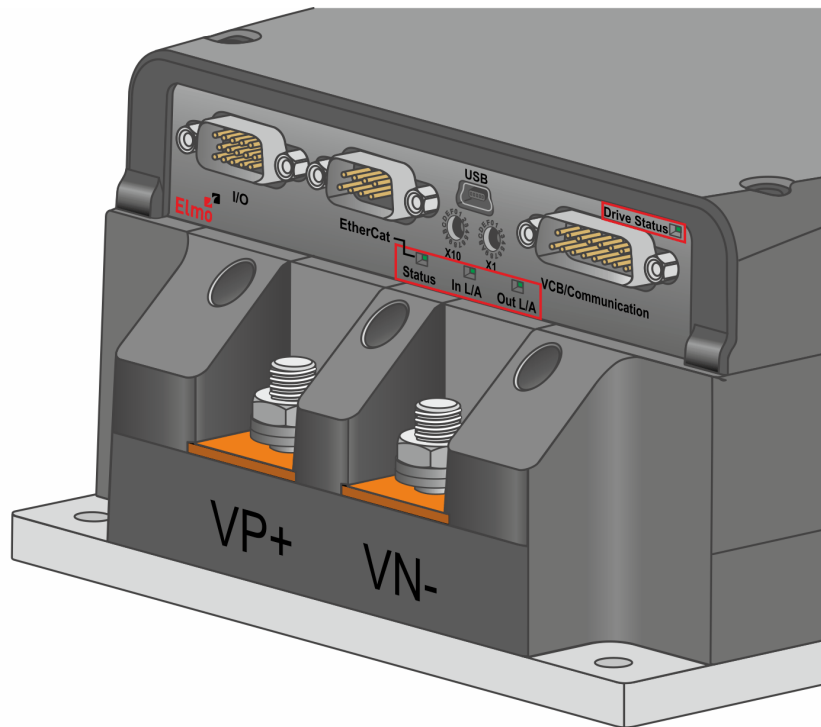


Figure 36: EtherCAT RJ-45 Connections



6.11.3 EtherCAT and Drive Status Indicator LEDs



GEAG360-041B-B

Figure 37: EtherCAT and Drive Status Indicator LEDs on Gold Eagle 360/430

The Gold Eagle 360/430 is equipped with several light-emitting diode (LED) indicators:

- Drive Status
- EtherCAT indicators

The **Drive Status Indicator** red/green dual LED is used for immediate indication of the Initiation and Working states.

The red/green dual LED is used for immediate indication of the following states:

- **Initiation state:** In this state the LED indicates whether the drive is in the boot state (blinking red) or in the operational state (steady red).
- **Working state:** In this state the LED indicates whether the drive is in an amplifier failure state (red) or is ready to enable the motor (green).

The **EtherCAT status indicator** is a red/green dual LED. It combines run indication (when it is green) and error indication (when it is red) of the EtherCAT device.

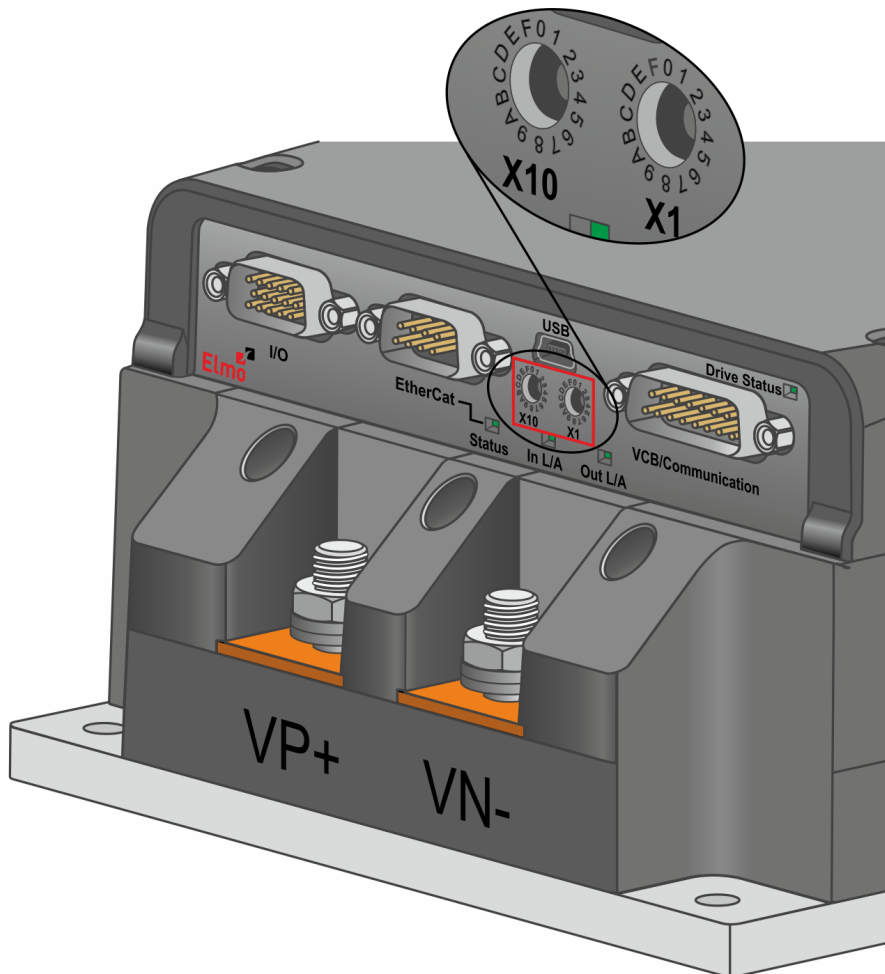
The Gold Eagle 360/430 can serve as an EtherCAT slave device. For this purpose it has a D-Type connector, which is designated as EtherCAT In and EtherCAT Out.

The green LED is the link/activity indicator. It shows the state of the applicable physical link and the activity on that link. The amber LED is the speed indicator. It shows the speed of the connection on the Ethernet line. Refer to the section 12.2.1.2 in the document; MAN-G-Panel Mounted Drives Hardware manual.



6.11.4 EtherCAT Rotary Switches

Note: This option is only for the **G-EAGR360/100FXXX** and **G-EAGR430/80FXXX** type.



GEAG360-041B-C

Figure 38: Position of EtherCAT Address Switches on Gold Eagle 360/430

The positions of the switches on the drive are shown in Figure 38. Use a screwdriver to set the low and high bytes values of the drive EtherCAT address. This address is only retrieved after power-up.



6.12 CAN Communications Version

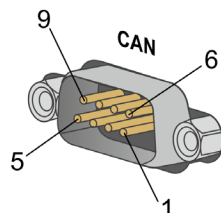
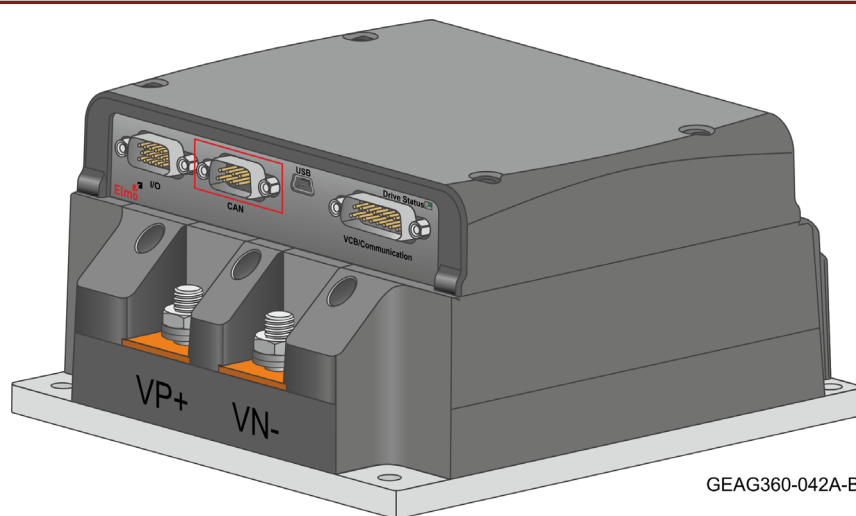
Fieldbus communications are industrial network protocols for real-time distributed control that allows connection of servo drives. The Gold Eagle 360/430 supports the following CAN fieldbus type industrial network protocol:

| Fieldbus Type | Product Number |
|------------------------------------|-------------------|
| CAN + RS-232 | G-EAGR360/100SXXX |
| CAN + Differential RS-232 (RS-422) | G-EAGR360/100TXXX |

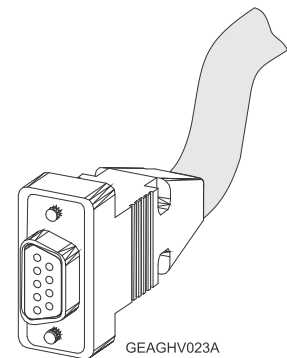
See Section 6.8.4 in the manual: MAN-G-Drive Hardware for the electrical diagram.

| Pin on CAN | Signal | Function |
|------------|----------|--------------------------------|
| 1, 3 | CAN_H | CAN_H bus line (dominant high) |
| 6, 8 | CAN_L | CAN_L bus line (dominant low) |
| 7, 9 | CAN_RET | CAN Return |
| 5 | CAN_SHLD | Drain wire cable |

Pin Positions



9-Pin D-Type Male Connector



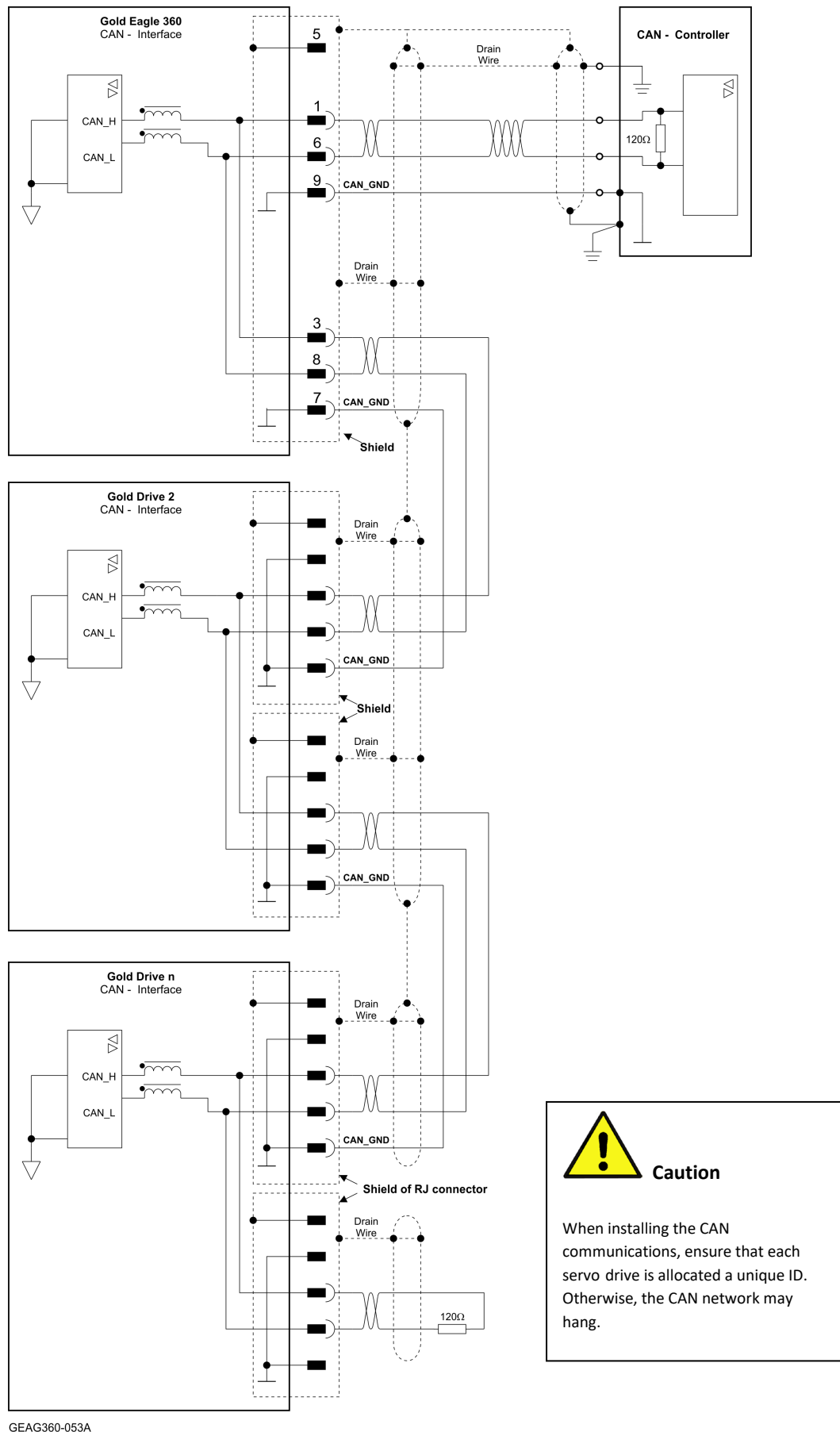
9-Pin D-Type Female Connector

Table 9: CAN In/Out Connector Pin Assignments



6.12.1 CAN Wiring

Figure 39 describes the CAN wiring diagram below.



GEAG360-053A

Figure 39: Gold Eagle 360/430 Connection Diagram – CAN



6.12.2 CAN Indicator

There is one indicator LED; the **Drive Status**. For details of the Drive Status, refer to Section 6.2 in the MAN-G-Panel Based Drive Hardware manual.

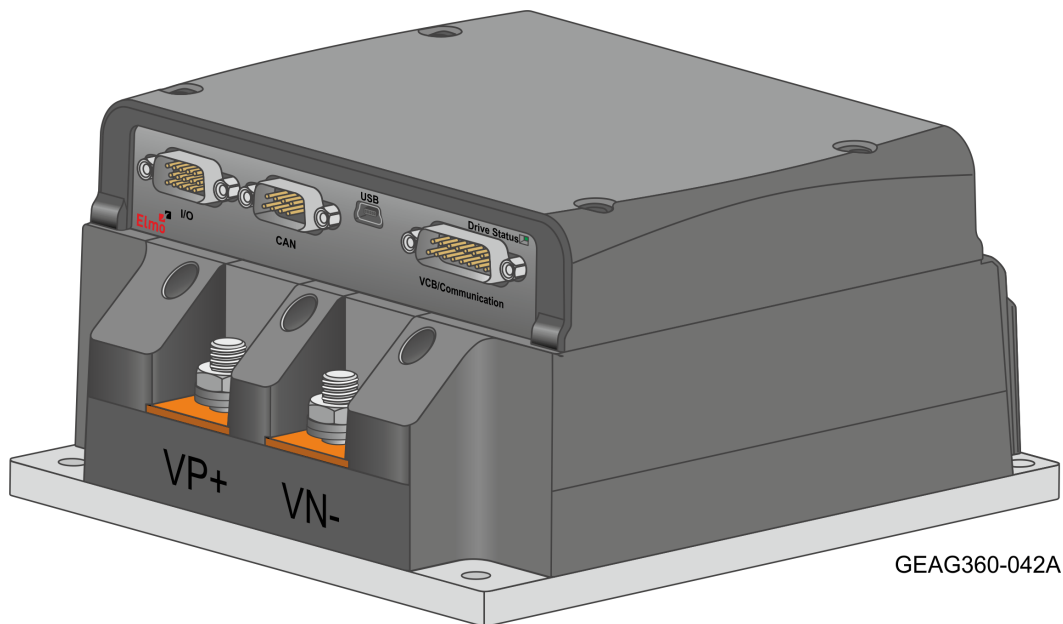


Figure 40: Drive Status Indicator LEDs on Gold Eagle 360/430 – CAN Version

The **Drive Status Indicator** red/green dual LED is used for immediate indication of the Initiation and Working states.

The red/green dual LED is used for immediate indication of the following states:

- **Initiation state:** In this state the LED indicates whether the drive is in the boot state (blinking red) or in the operational state (steady red).
- **Working state:** In this state the LED indicates whether the drive is in an amplifier failure state (red) or is ready to enable the motor (green).



7. Heat Dissipation

For full power output capability the Gold Eagle 360/430 is designed to be mounted on an external heat-sink. It is highly recommended that the “Wall” on which the Gold Eagle 360/430 is mounted will have heat dissipation capabilities. The Gold Eagle 360/430 at “free air convection” (without an additional heat-sink) can dissipate around 20W - 30 W not exceeding 80 °C on the heat sink.

When “Free Air Convection” is sufficient for the application it is recommended to leave approximately 10 mm of space between the Gold Eagle 360/430's heat sink and any other assembly.

7.1 Gold Eagle 360/430 Thermal Data

- Free air convection thermal resistance (θ): Approximately 12- 18°C/W.
- Thermal time constant: Approximately 40 minutes/ 2400 seconds (thermal time constant means that the Gold Eagle 360/430 will reach 2/3 of its final temperature after 40 minutes).
- Self-heat dissipation capability (no external heat sink): 20 W -30W for 40°C/W temperature rise.
- Shut-off temperature: 86 to 88°C.
- The thermal resistance when connecting to an external heat sink using a thermal conductive compound/foil. By proper smearing of the surface a significant improvement of the thermal resistance is achieved: $\approx 0.018^\circ\text{C/W}$.
- When attaching to an external heat-sink, it is recommended to use $\sqrt{R_z}10$ surface treatment and thermal foil or smearing thermal compound.



7.2 Heat Dissipation Data

Heat Dissipation is shown graphically below:

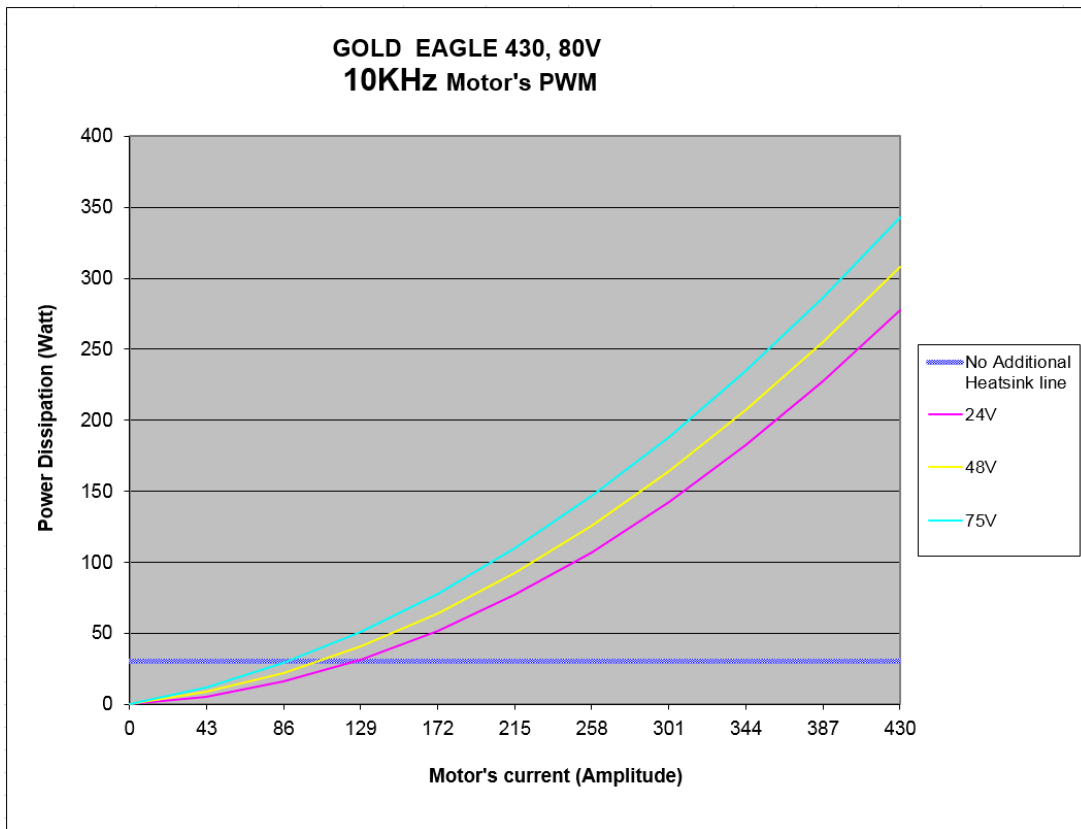


Figure 41: Dissipation versus Current Graph for 430A, 80VDC @ 10KHz PWM

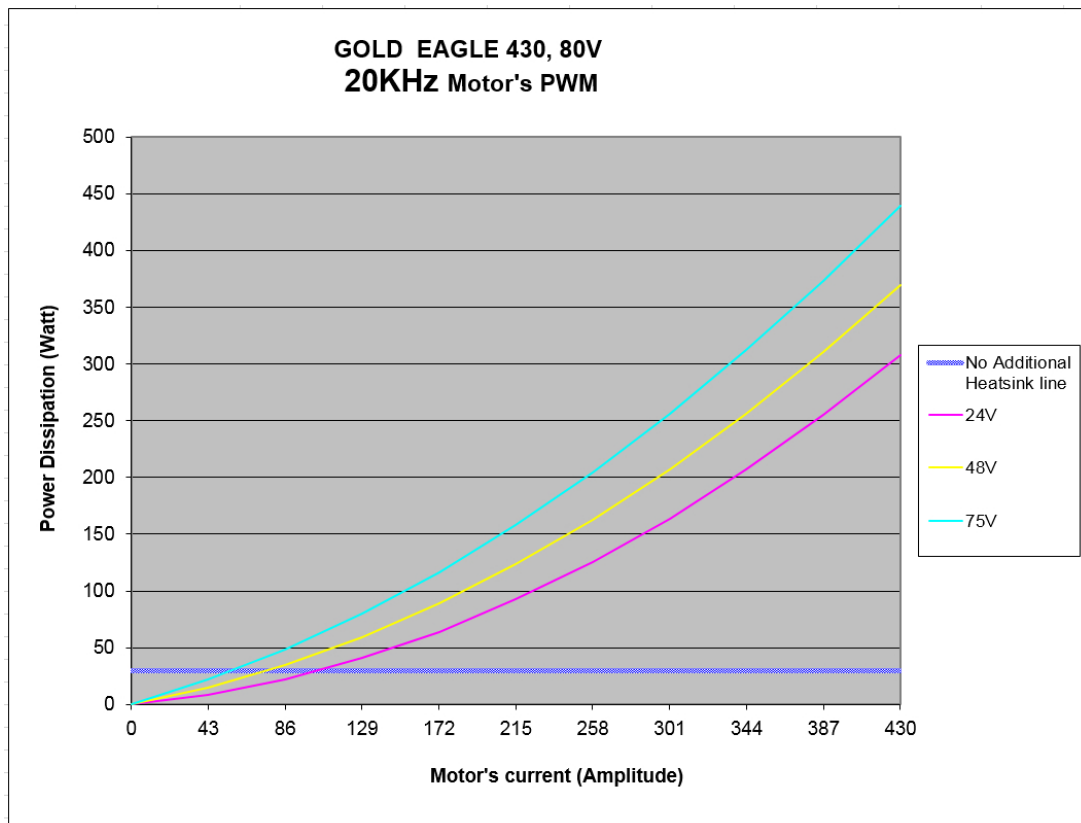


Figure 42: Dissipation versus Current Graph for 430A, 80VDC @ 20KHz PWM

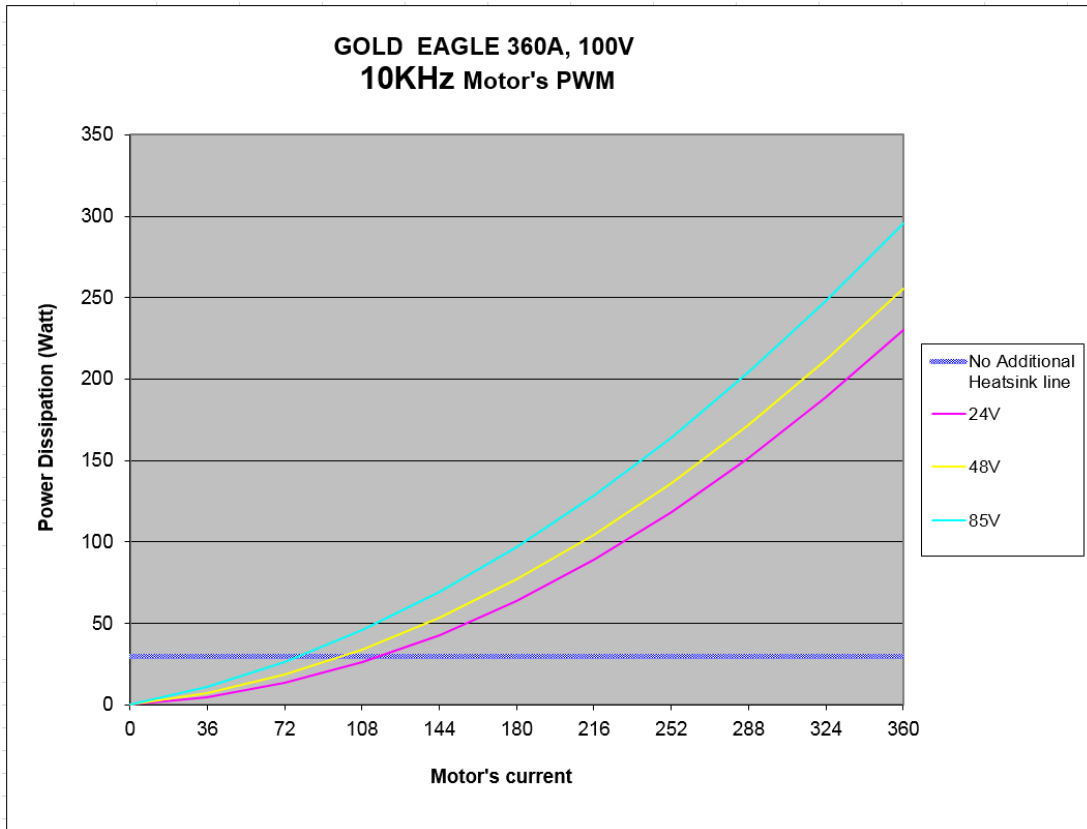


Figure 43: Dissipation versus Current Graph for 360A, 100VDC @ 10KHz PWM

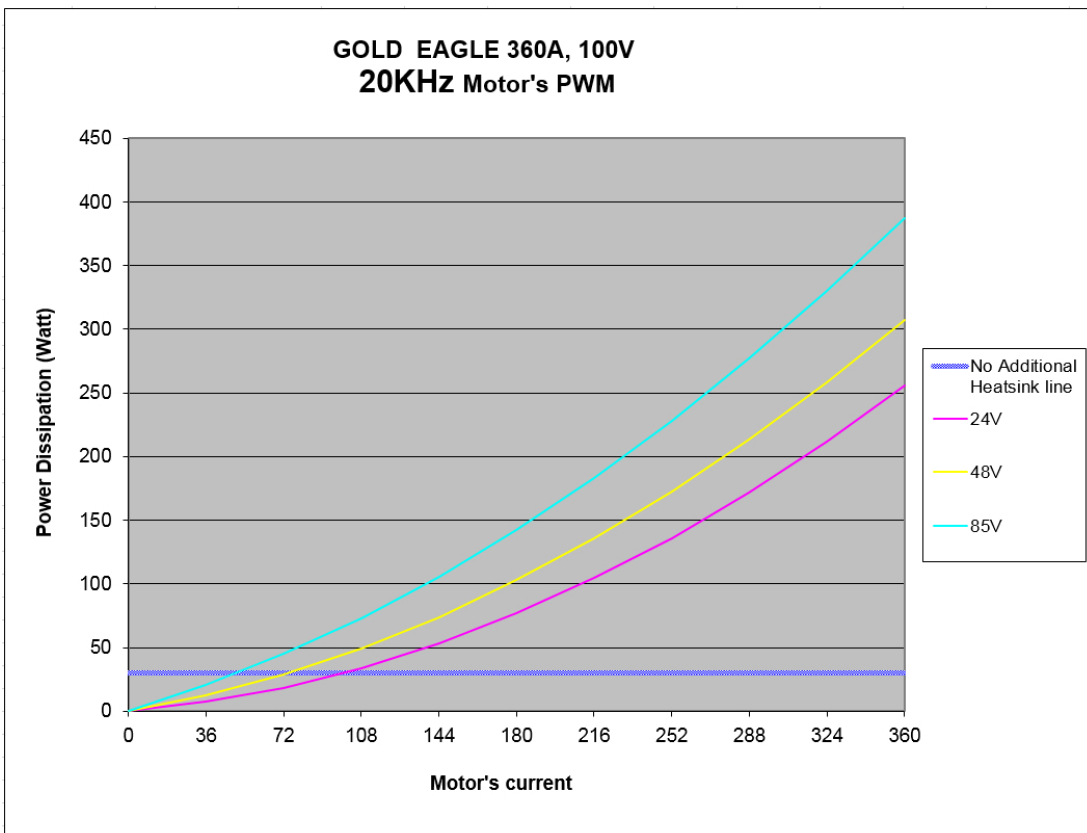


Figure 44: Dissipation versus Current Graph for 360A, 100VDC @ 20KHz PWM



7.3 How to Use the Charts

The charts above are based upon theoretical worst-case conditions. Actual test results show 30% to 50% better power dissipation.

To determine if your application needs a heat sink:

1. Allow maximum heat sink temperature to be 80 °C or less (shunt down is 6 °C to 8 °C higher).
2. Determine the ambient operating temperature of the Gold Eagle 360/430 as $\leq 70^{\circ}\text{C}$.
3. Calculate the allowable temperature increase according to the following example: For an ambient temperature of 70 °C, $\Delta T = 80 \text{ to } 70^{\circ}\text{C} = 10^{\circ}\text{C}$
4. Use the chart to find the actual dissipation power of the drive. Follow the voltage curve to the desired output current and then find the dissipated power.

7.4 Thermal Operating Envelope

The Gold Eagle 360/430 drive has a built in Safe Operating Area Thermal Limit Envelope, as defined in the following "Current vs. Temperature" chart (Figure 46).

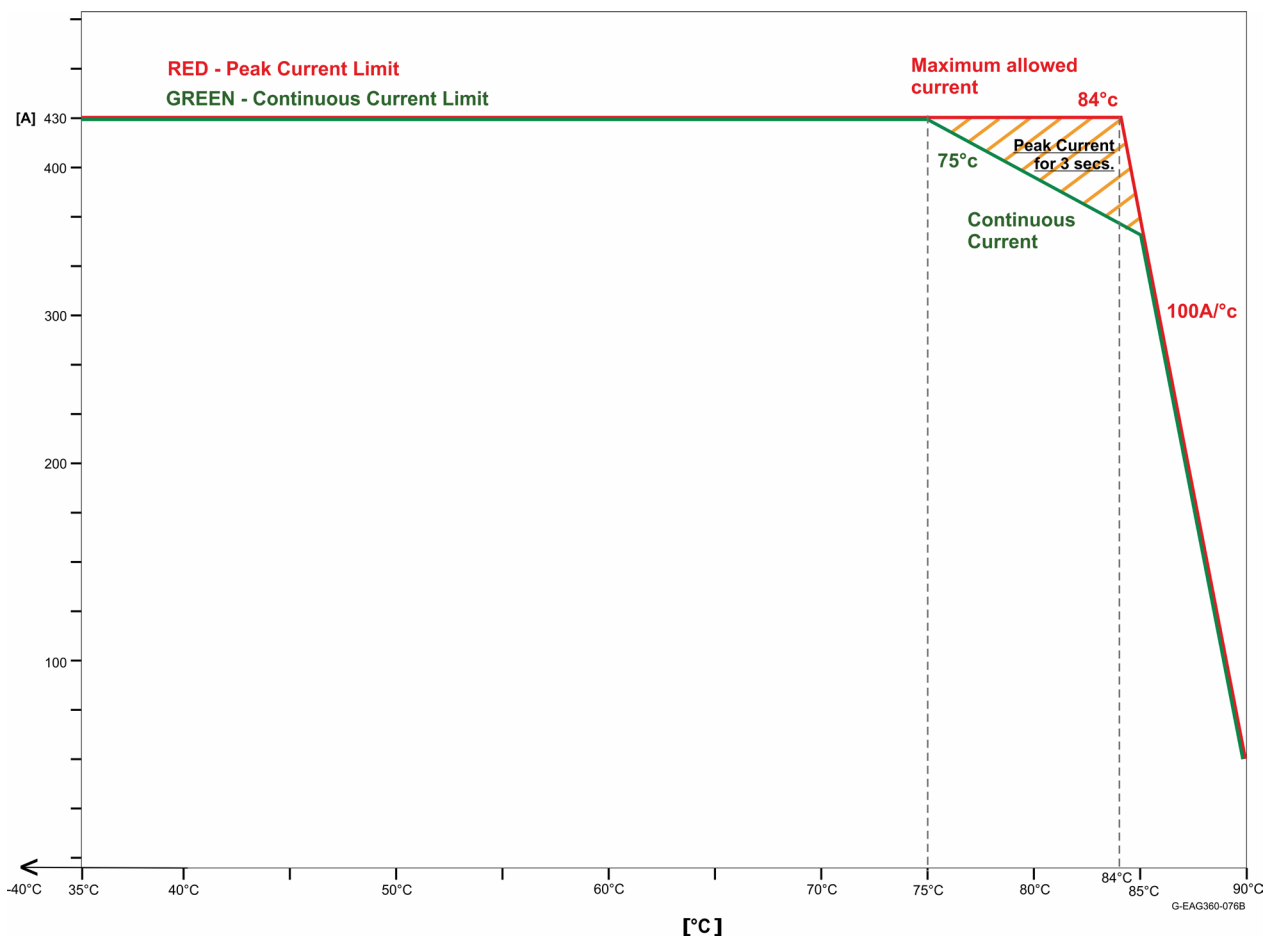


Figure 45: Thermal Operation for 430A under Continuous Current for both Voltage and Temperature

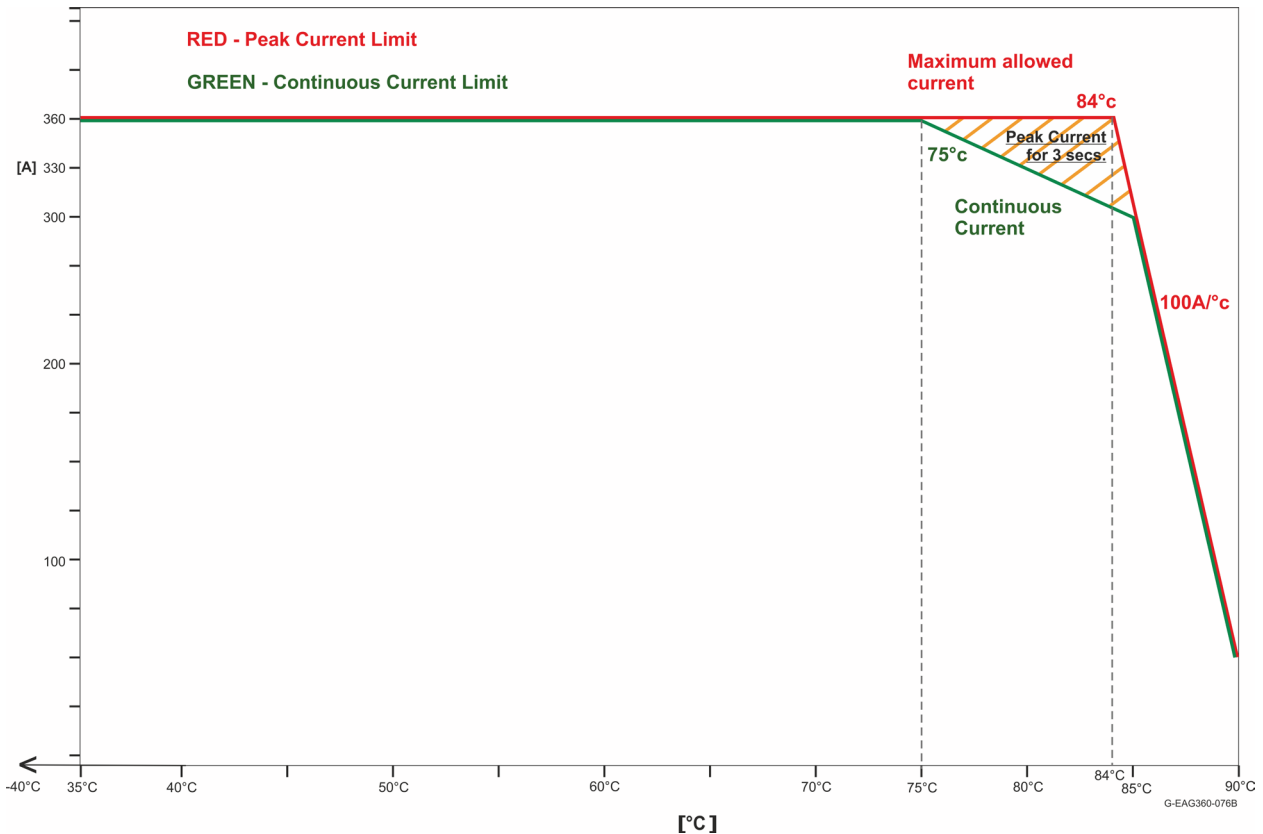


Figure 46: Thermal Operation for 360A under Continuous Current for both Voltage and Temperature

Up to a heat sink Temperature $TI[1] \leq 75^{\circ}\text{C}$, the drive can provide a Max current of e.g. 360A continuously.

Between $75^{\circ}\text{C} \leq TI[1] \leq 84^{\circ}\text{C}$ the Peak Current of 360A is allowed for up to 3 Seconds.

The limitation in this range is based on the standard drive's "RMS" current limit mechanism.

Check the Drive's Software Command Reference Manual under **PL/CL** operation for further explanation.

At the heat sink Temperature $TI[1] > 84^{\circ}\text{C}$, the Drive's Peak Current limit (**PL**) is internally limited by the red/green line Linear slopes. The Current slope limit is $100\text{A}/^{\circ}\text{C}$, starting from $TI[1] \geq 84^{\circ}\text{C}$.

This means, for example, that at a Temperature of $TI[1] = 87^{\circ}\text{C}$, the Peak Current is limited to 250A.

At a Temperature of $TI[1] \geq 89.5^{\circ}\text{C}$ the Output Current is 0.

Thermal Shut down (Motor Disabled) will be tripped at $TI[1] = 92^{\circ}\text{C}$.



8. Powering Up

After the Gold Eagle 360/430 is connected to its device, it is ready to be powered up.



Caution:

Before applying power, ensure that the DC supply is within the specified range and that the proper plus-minus connections are in order.

8.1 Initializing the System

After the Gold Eagle 360/430 has been connected and mounted, the system must be set up and initialized. This is accomplished using the *EASII*, Elmo's Windows-based software application. Install the application and then perform setup and initialization according to the directions in the *EASII User Manual*.



9. Gold Eagle 360/430 Dimensions

This chapter provides detailed technical dimensions regarding the Gold Eagle 360/430.

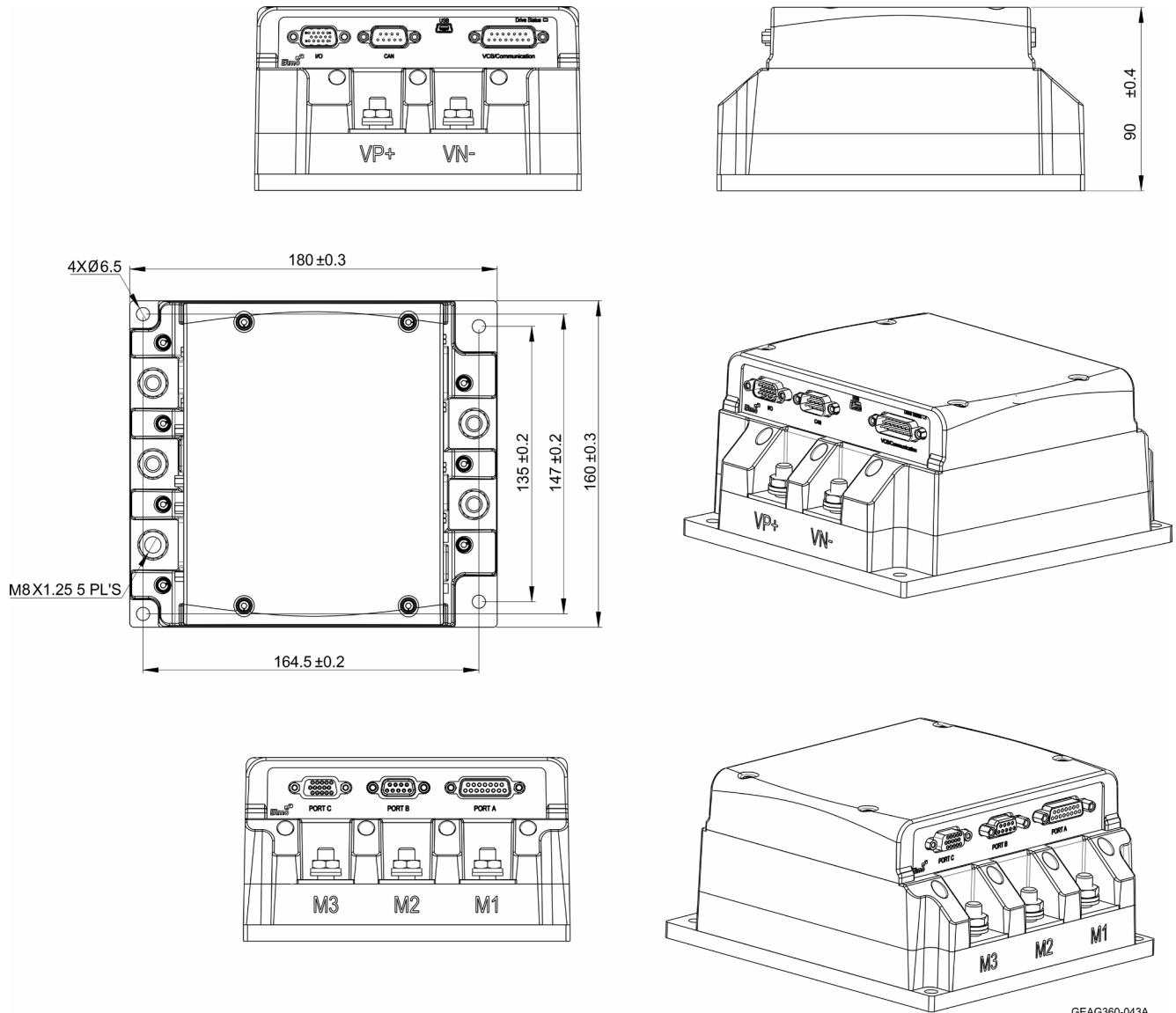


Figure 47: Gold Eagle 360/430 CAN Version Dimensions

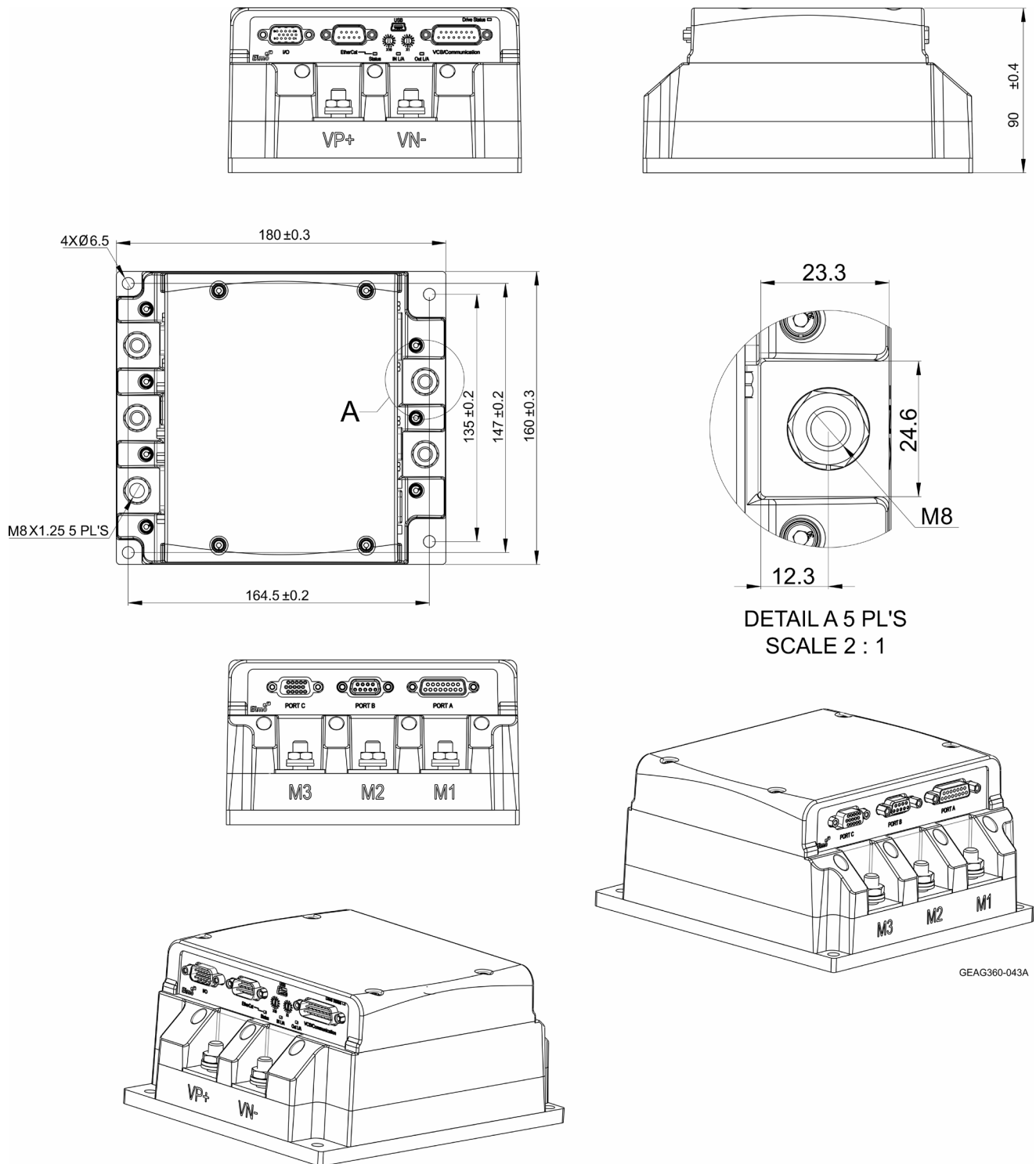


Figure 48: Gold Eagle 360/430 EtherCAT Version Dimensions

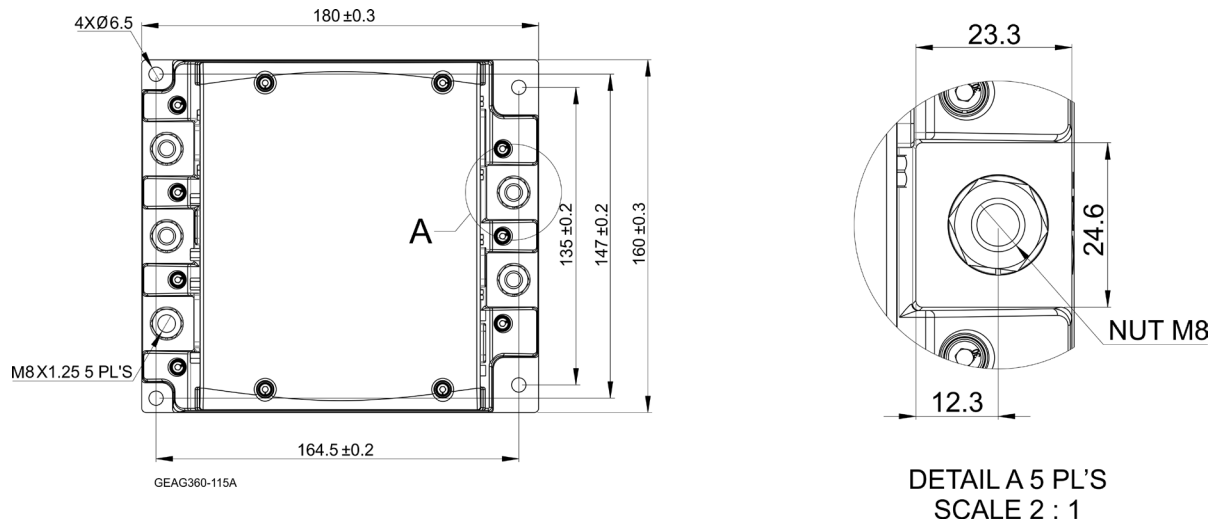


Figure 49: Gold Eagle 360/430 Terminal Connectors' Dimensions



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